bürkert
FLUID CONTROL SYSTEMS

Type SE58 L

Transmitter

CE

Operating Instructions

MAN 1000495958 EN Version: B Status: RL (released | freigegeben) printed: 01.04.2022

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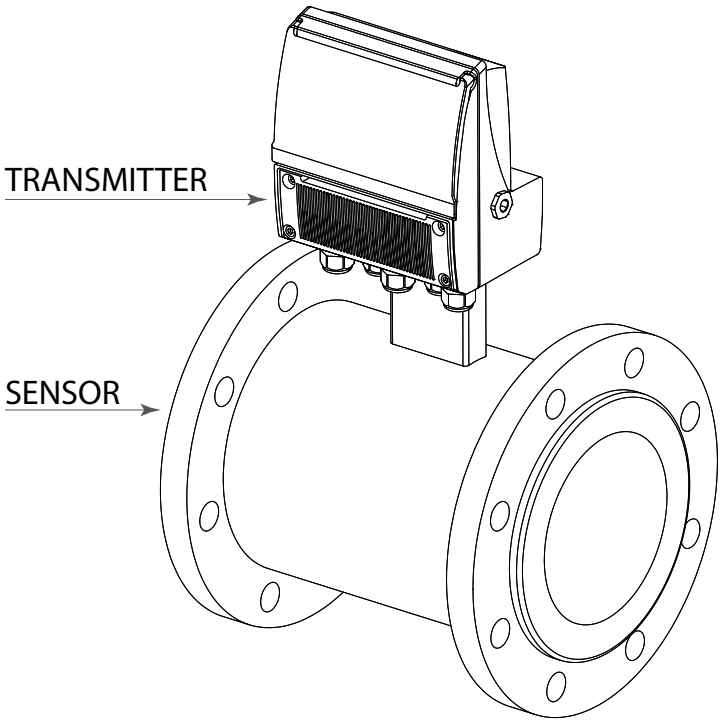
(*) Any changes using MCP are not recommended, unless:
- after receiving corresponding training by burkert,
- done by professional,
- agreed by the end user, and done inline with the MCP manual

INTRODUCTION

- These operating instructions and description of device functions are provided as part of the scope of supply.
- They could be modified without prior notice. The improper use, possible tampering of the device or parts of it and substitutions of any components not original, renders the warranty automatically void.
- The flowmeter realizes a measure with liquids of conductivity greater than 5µS/cm in closed conduits, and is composed of a transmitter (described in this manual) and a sensor (refer to the specific manual).
- The transmitter could be coupled directly on the sensor (compact version) or coupled to the sensor by cable supplied with it (remote version).



SAFETY INFORMATION

Any use other than described in this manual affects the protection provided by the manufacturer and compromises the safety of people and the entire measuring system and is, therefore, not permitted. The manufacturer is not liable for damaged caused by improper or non-designated use.

- Transport the measuring device to the measuring point in the original packaging. Do not remove covers or caps before starting installation. In case of cartons packaging it is possible to place one above the other but no more than three cartons. In case of wooden packaging do not place one above the other.
- Disposal of this product or parts of it must be carried out according to the local public or private waste collection service regulations.
- The transmitter must only be installed, connected and maintained by qualified and authorized specialists (e.g. electrical technicians) in full compliance with the instructions in this Operating Instruction, the applicable norms, legal regulations and certificates (depending on the application).

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- The specialists must have read and understood these Operating Instructions and must follow the instructions it contains. The Operating Instructions provide detailed information about the transmitter. If you are unclear on anything in these Operating Instructions, you must call the Bürkert service department.
- The transmitter should only be installed after have verified technical data provided in these operating instructions and on the data plate.
- Specialists must take care during installation and use personal protective equipment as provided by any related security plan or risk assessment.
- Never mount or wire the transmitter while it is connected to the power supply and avoid any liquid contact with the device's internal components. To connect remove the terminals from the terminal block.
- Each part of the instrument must be examined or supplied exclusively by the manufacturer or his representative
- Before connecting the power supply check the functionality of the safety equipment.
- Repairs may only be performed if a genuine spare parts kit is available and this repair work is expressly permitted.
- For the cleaning of the device use only a damp cloth and for the maintenance/repairs contact the service center.
- If the instrument is used in a another way than the one specified by the manufacturer, the protection provided by the device may be compromised.

Before starting up the equipment please verify the following:

- Power supply voltage must correspond to that specified on the data plate
- Electric connections must be completed as described
- Ground (earth) connections must be completed as specified

Verify periodically (every 3-4 months):

- The power supply cables integrity, wiring and other connected electrical parts
- The transmitter housing integrity
- The suitable tightness of the sealing elements
- The front panel integrity (display and keyboard)
- The mechanical fixing of the transmitter to the pipe or wall stand

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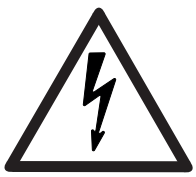
SAFETY CONVENTION



DANGER ELECTRIC SHOCK

WARNING

PRECAUTIONS

TECHNICAL CHARACTERISTICS

Electrical Characteristic

Converter classification: class I,
IP67 (where: 6 = totally protected against dust, 7 = Protected against the effects of temporary immersion) /
IP68 (where: 6 = totally protected against dust, 8 = continuous immersion 1.5 m; 1 h)
for aluminum and PA6 housing, installation category (overvoltage) II, rated pollution degree 2.

Power supply versions	Power supply voltage	Power supply frequency	Min Power	Max power
HV	100-240V~	45-66HZ	1,5 W (Sensor only)	12 W (all Loads)
LV	24-36V ⎓	//		
	24-36V~	45-66HZ		
LLV	12-48V ⎓	//		

- Voltage variations must not exceed ±10% of the nominal one.
- Input/output insulated
- The output 4-20mA (optional) is electrically connected to the ON/OFF outputs and the output power supply (24V ⎓).
- Version LV/LLV : inrush current < 20A
  Version HV : inrush current < 25A

Note: The devices powered at 24-36 V and 12-48 V must only be powered with power supplies compliant with the IEC61010 standard

Environmental Use Conditions

The transmitter can be installed internally or externally
Altitude: untill 4000m
Humidity range: 0-100%

AMBIENT TEMPERATURE				
	Aluminium		Reinf. Nylon	
	Min*	Max	Min*	Max
°C	-20	+ 60	-10	+ 50
°F	-4	+140	+14	+122

ATTENTION

The battery will not be charged outside the below limits:
T board SE58 M < 0 °C
T board SE58 M > 50 °C

If the transmitter is supplied in compact version (transmitter over the sensor), consider the ambient temperatures more restrictive, otherwise refer to the relevant manuals.
* For discontinuous use, a thermostat heat source installation may be necessary.

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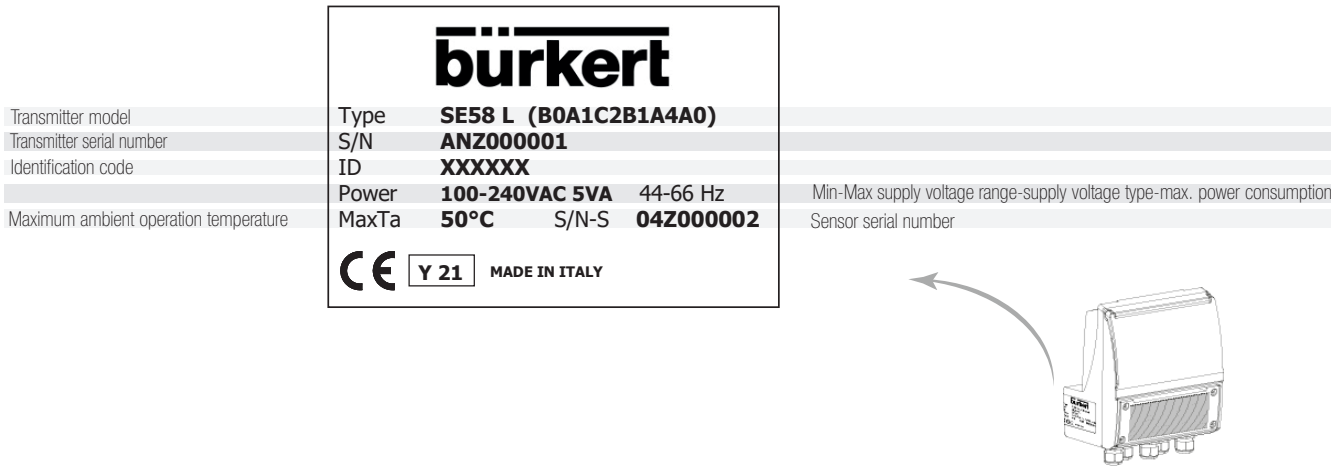
Data Plate

The device label contain the following information:



Maintenance

ATTENTION

In case of the maintenance involving the change of SE58 transmitter or sensor, an additional measurement deviation can occur.
To ensure the original accuracy announced in the datasheet, a flow calibration of the full instrument must be performed by Burkert.

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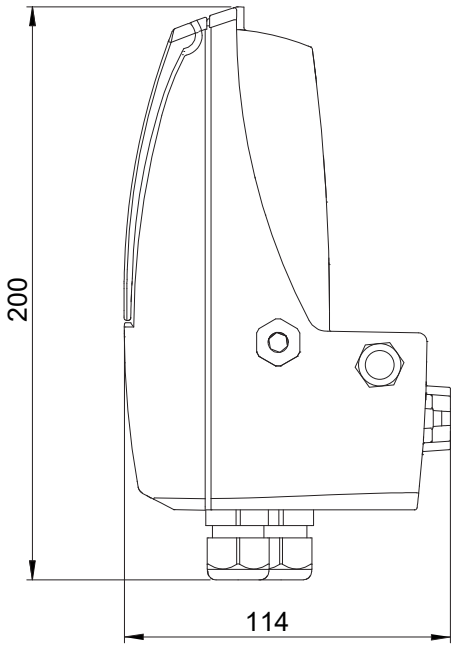
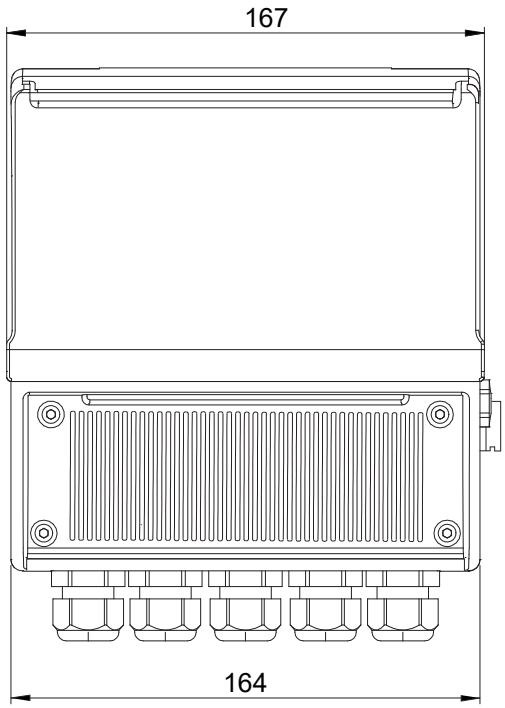
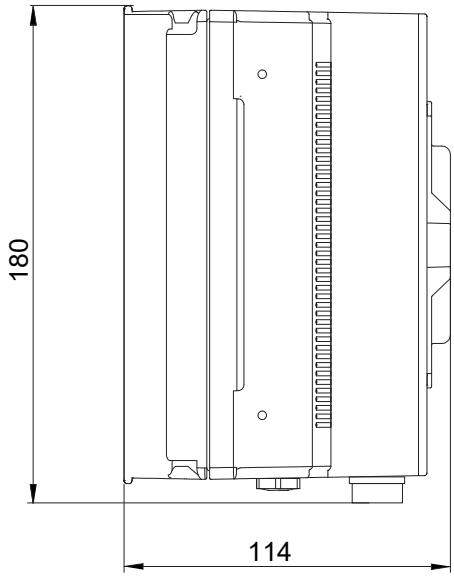
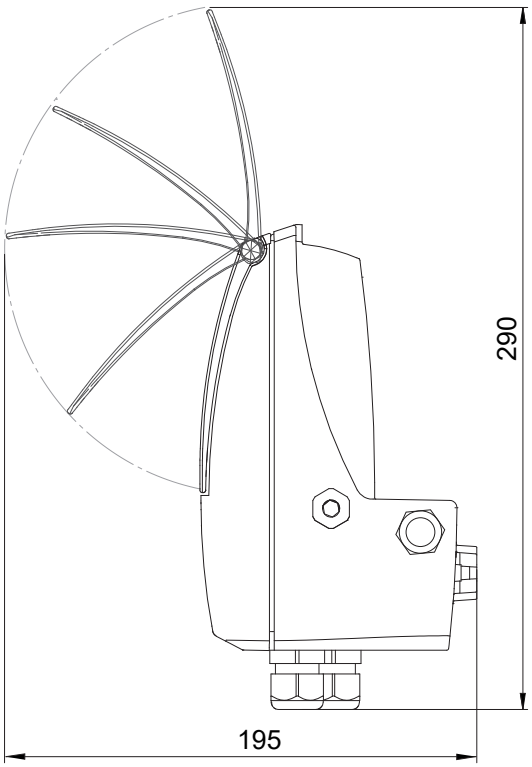
Dimensions









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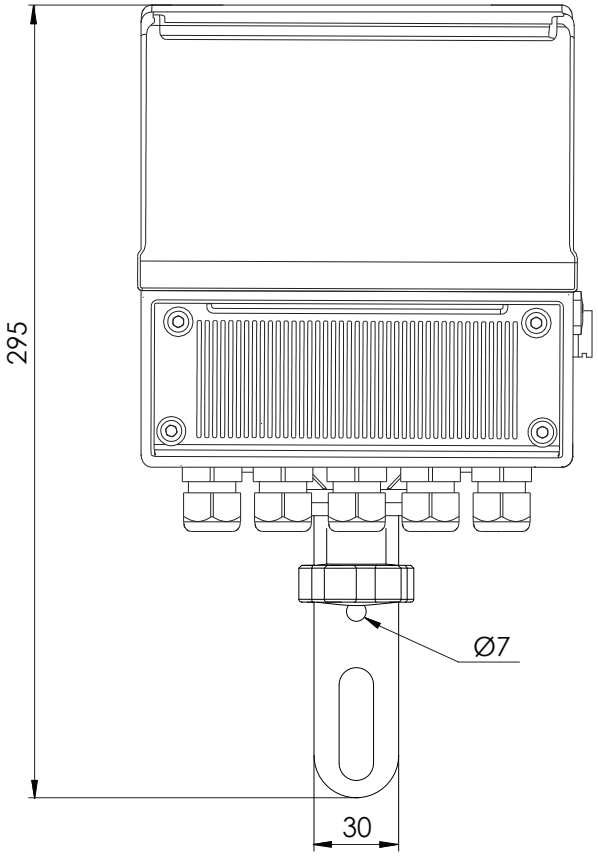
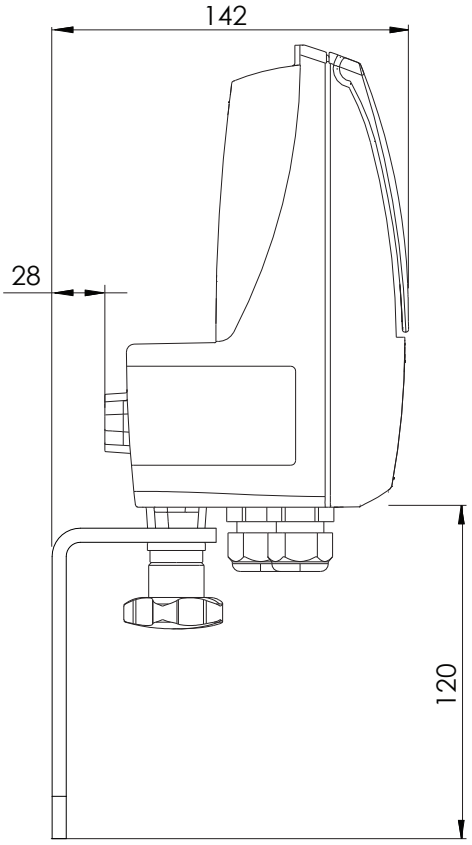
Remote version





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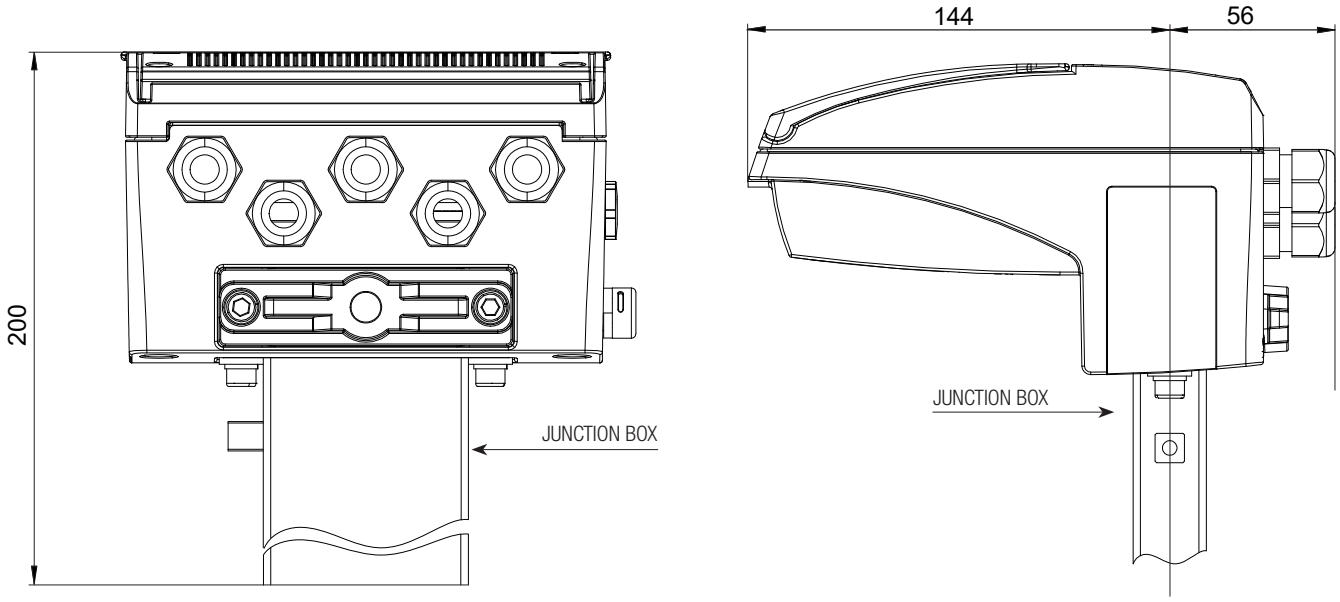
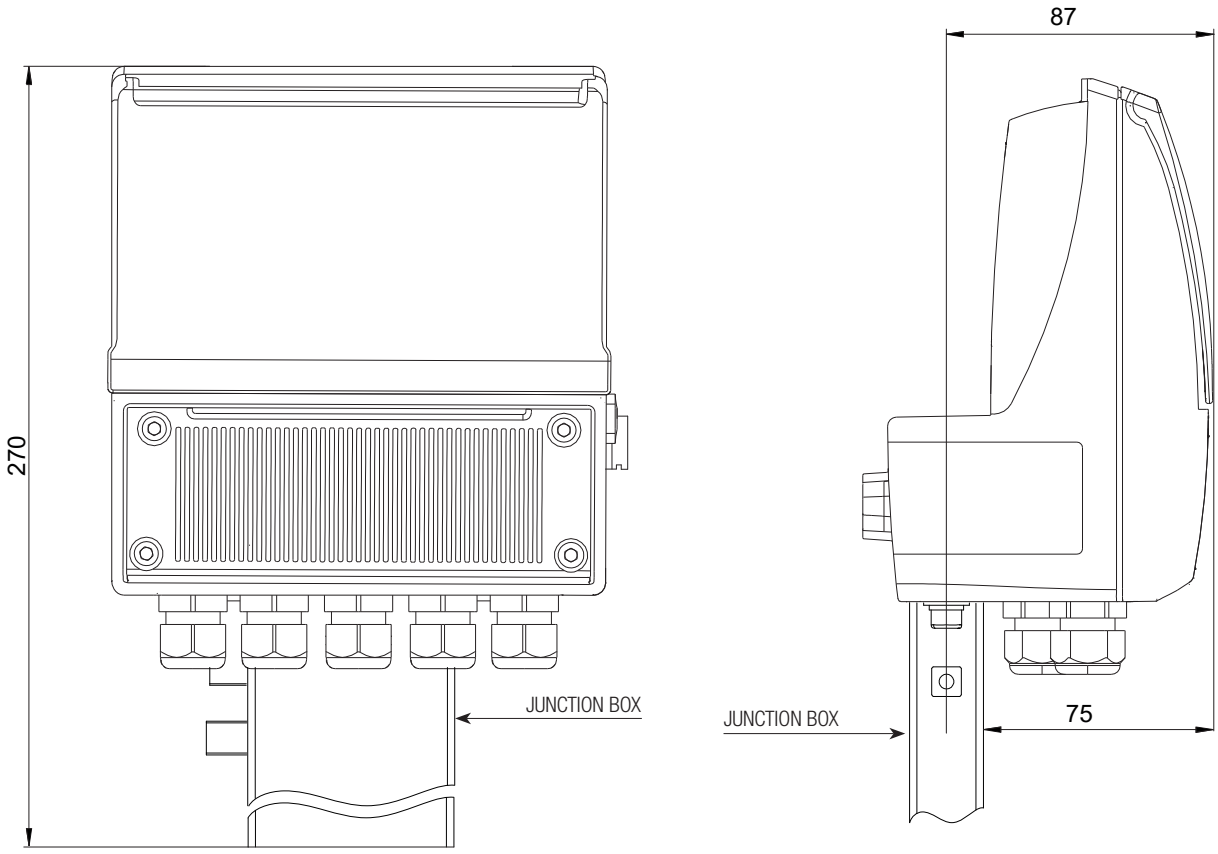
Horizontal version



Vertical version



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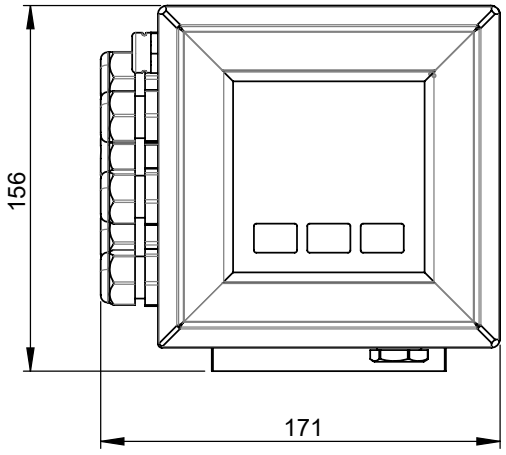
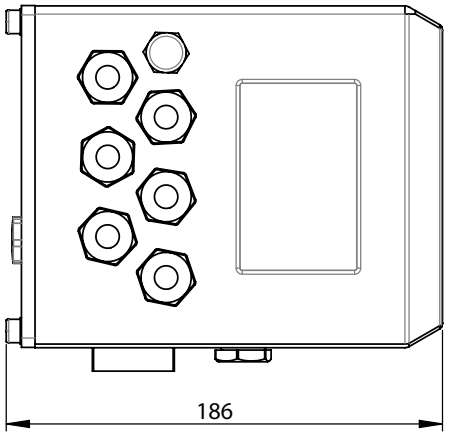
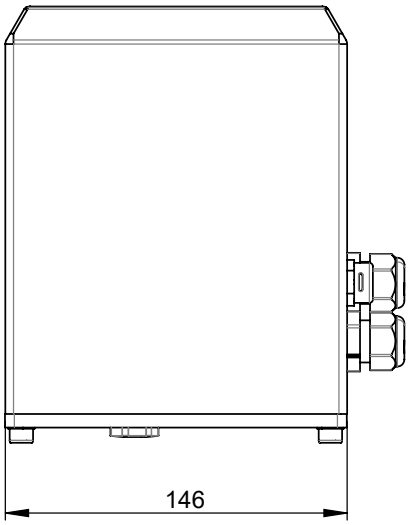
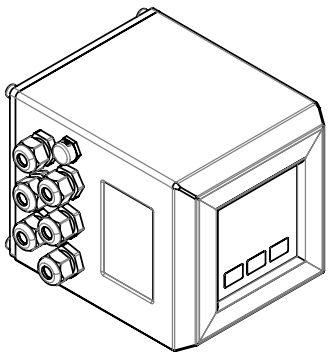
DIMENSIONS (STAINLESS STEEL VERSION)

Compact Version









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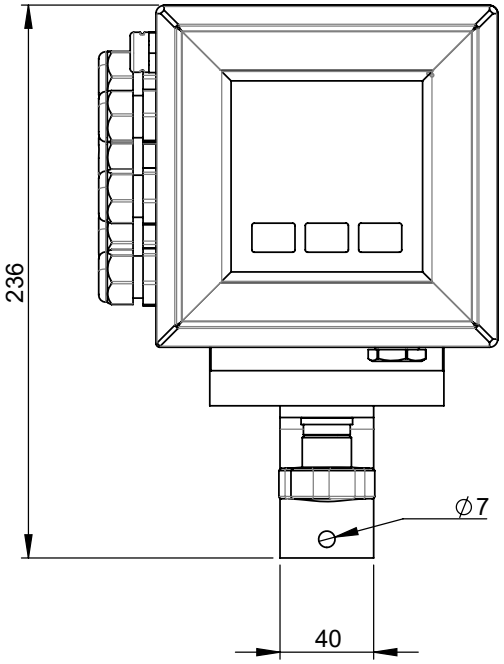
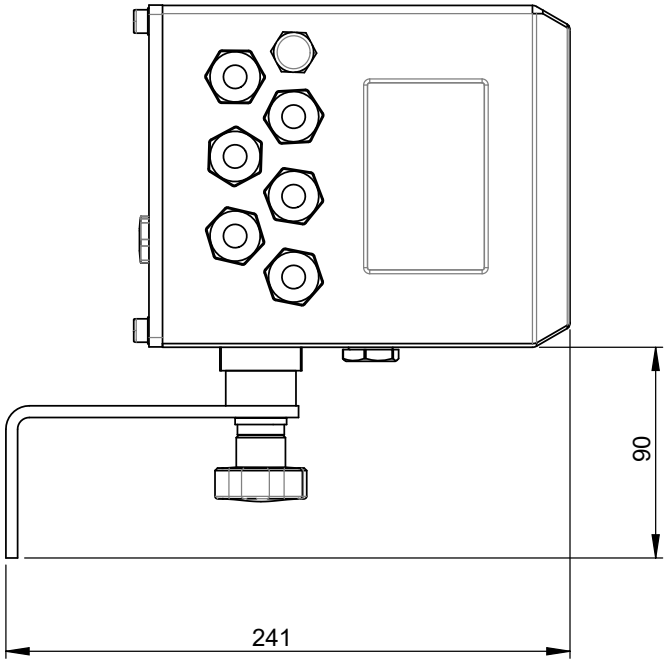
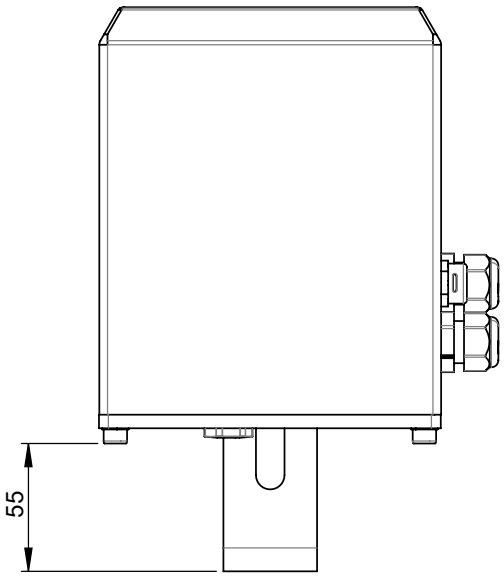
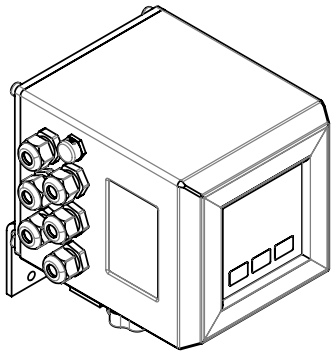
Separate Version









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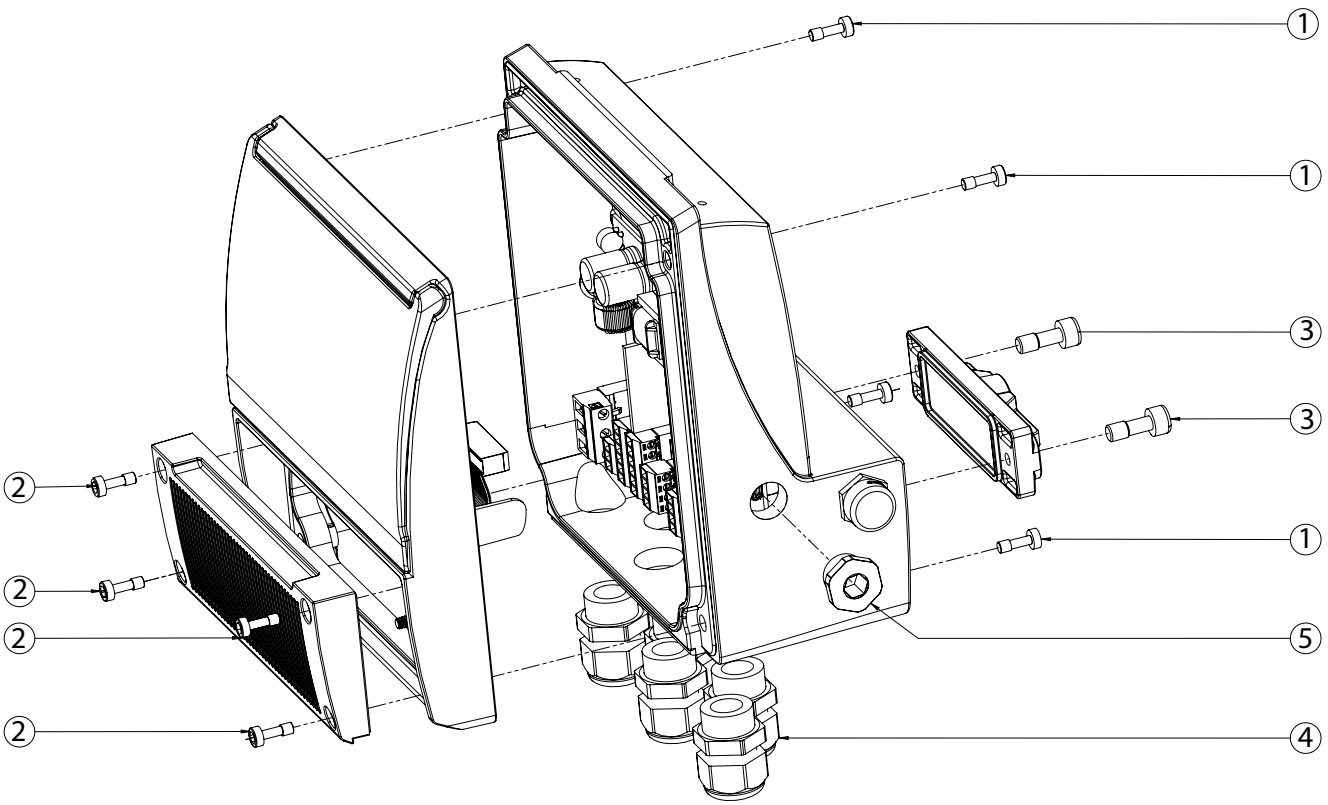
TORQUES

To guarantee the housing's IP degree the following torques are required:

HOUSING MATERIAL	Housing screws (1)	Screws Terminal block cover (2)	Screws for display frame	PCB Screws	Version Cap (3)	Cable Glands (4)	Cap USB-B (5)
ALUMINIUM HOUSING	6 Nm	5.5 Nm	3 Nm	0.8 Nm	8 Nm	4 Nm	4 Nm
PLASTIC HOUSING	2 Nm	2 Nm	2.5 Nm	0.8 Nm	7 Nm	4 Nm	4 Nm



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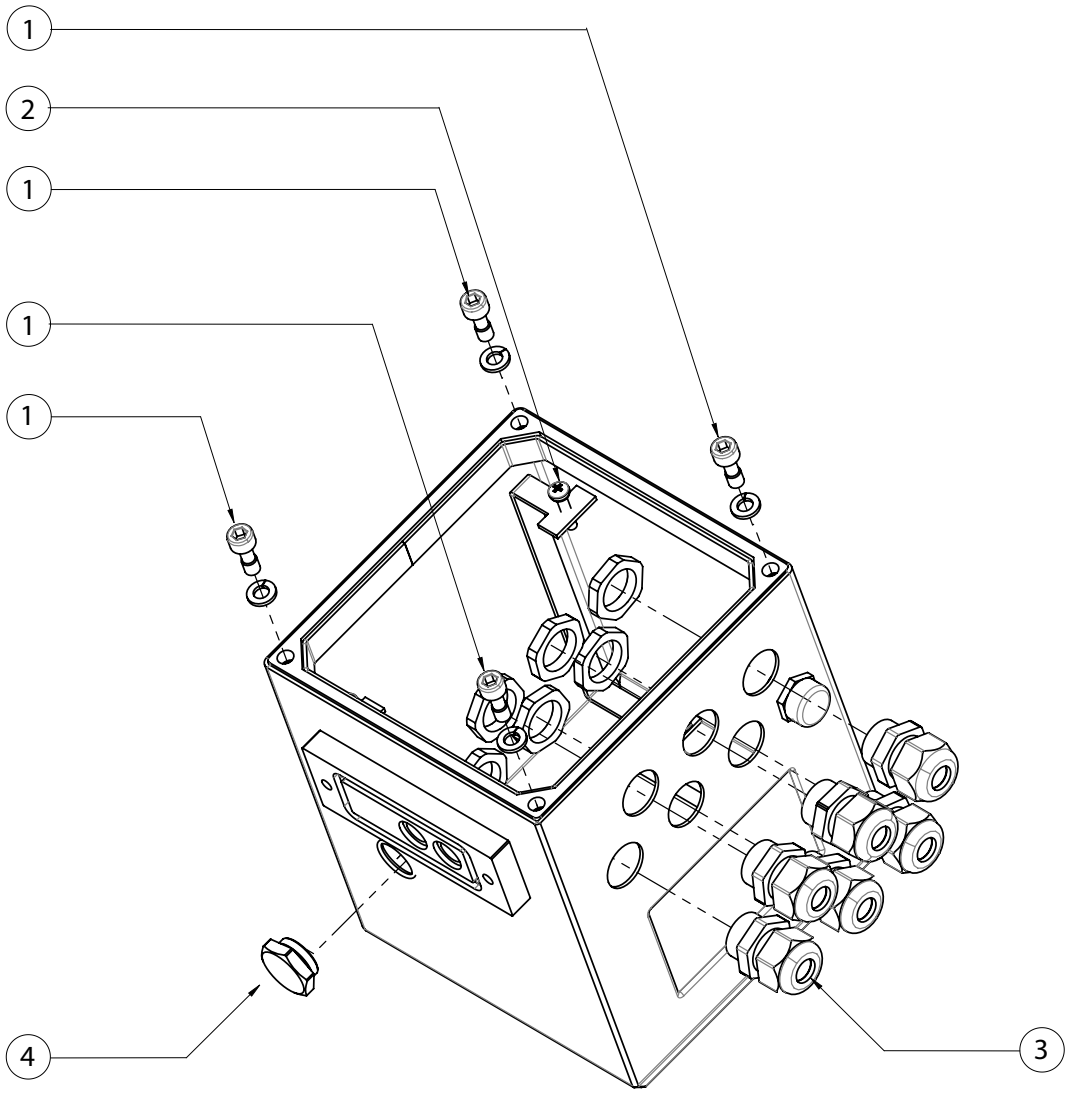
Stainless steel housing

HOUSING MATERIAL	Housing screws (1)	PCB Screws (2)	Cable Glands (4)	Cap USB-B (5)
Stainless steel HOUSING	2.5 Nm	0.8 Nm	4 Nm	2.5 Nm



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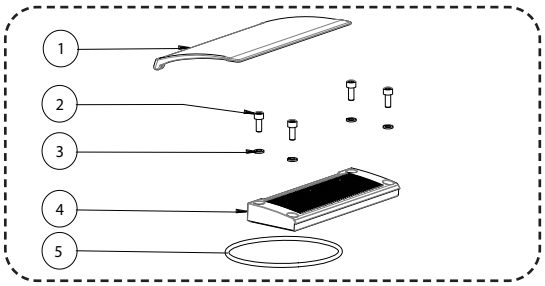
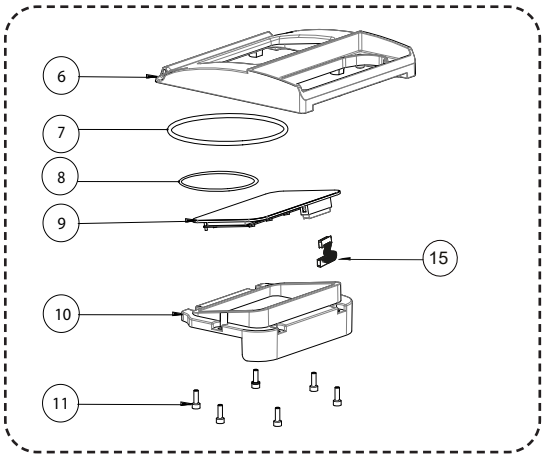
SE58 M CONSTRUCTION

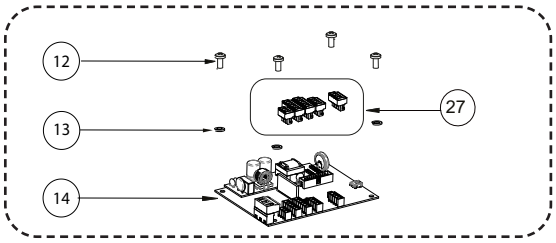
TERMINAL BLOCK COVER



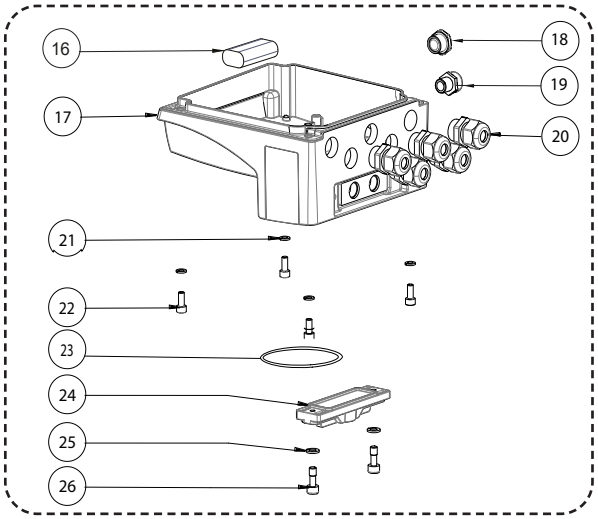
MAIN HOUSING COVER



PCB SE58 M



MAIN HOUSING



POS.	DESCRIPTION	
	PA6 VERSION	ALLUMINIUM VERSION
1	PROTECTION COVER	
2	VITE M4x12	VITE M5x12
3	GROWER Ø4	GROWER Ø5
4	TERMINAL COVER	TERMINAL COVER
5	O-RING-4400	
6	HOUSING COVER	HOUSING COVER
7	O-RING-4700 (HOUSING COVER)	
8	O-RING-117x3 (DISPLAY)	
9	DISPLAY	
10	FIXING DISPLAY FRAME (MATERIAL PA06)	
11	SELF-TAPPING SCREW 4x10	TRILOBO SCREW 4x10
12	SELF-TAPPING SCREW 4x10	TRILOBO SCREW 4x10
13	GROWER Ø4	SPRING WASHER Ø4
14	PCB SE58 M	
15	FLAT CABLE	
16	LITHIUM BATTERY	
17	PA6 MAIN HOUSING	ALUMINIUM MAIN HOUSING
18	PG9 CAP	
19	ANTICONDESE CAP	
20	PG11 CABLE GLAND CABLE DIAMETER: Ø5-Ø10mm	
21	GROWER Ø4	SPRING WASHER Ø5
22	SCREW M4x12	SCREW M5x12
23	O-RING-155	
24	VERSION CAP (MATERIAL PA06)	
25	GROWER Ø6	
26	SCREW M6x16	
27	TERMINAL BLOCK SOLID WIRE: 26-16 AWG / 0.129-1.31 mm^2 STRANDED WIRE: 26-16 AWG / 0.129-1.31 mm^2 TORQUE: 3.0 Lb.In / 0.34 Nm	

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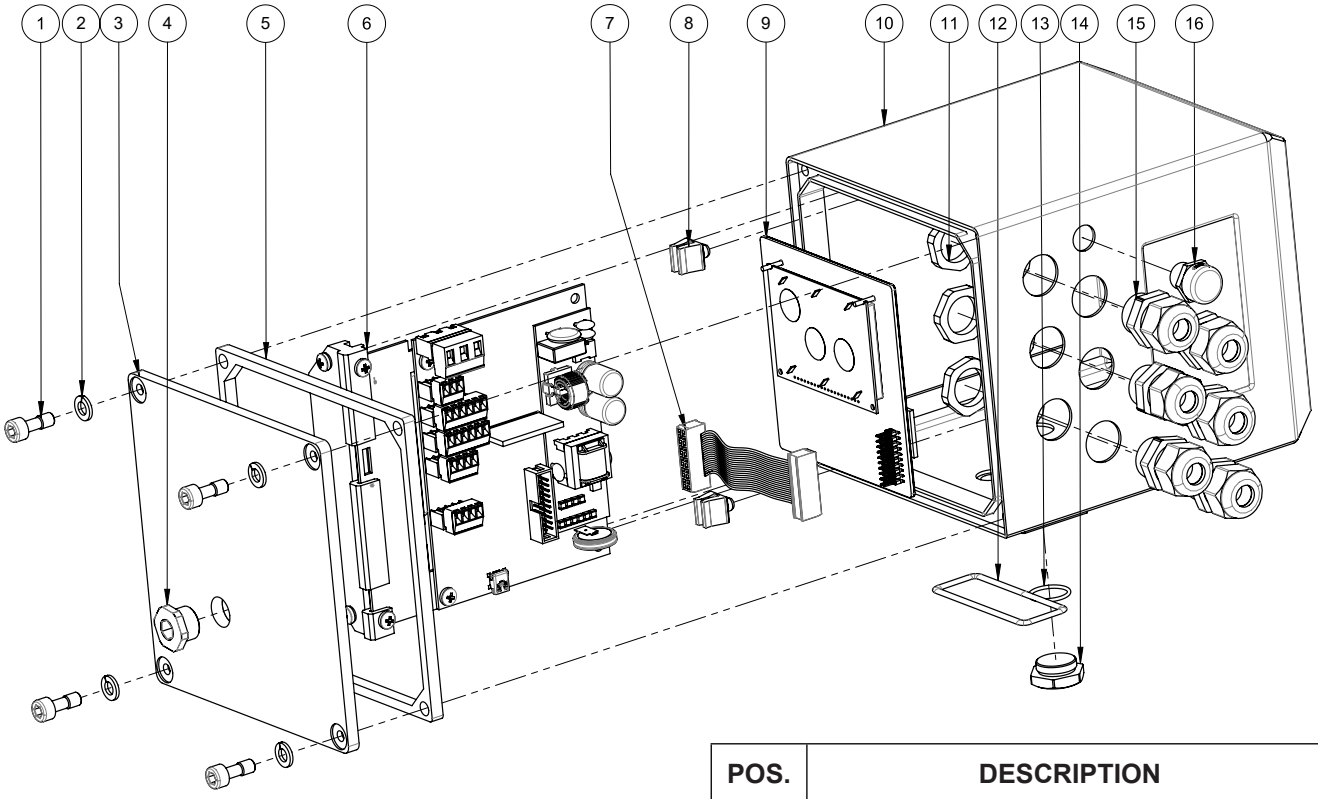
SE58 L CONSTRUCTION (STAINLESS STEEL VERSION)



POS.	DESCRIPTION
1	SCREW M6X16
2	GROWER Ø 6
3	POLISHED COVER
4	PG9 CAP IP68
5	GASKET FOR Stainless steel HOUSING
6	BOARD FRAME M3C
7	FLAT CABLE
8	BOARD FIXING CLIPS
9	DISPLAY/BLIND
10	POLISHED Stainless steel HOUSING
11	PG11 NUT
12	FLAT GASKET O-RING 155
13	O-RING ORM 0160-15 Ø16X1.5
14	Stainless steel CAP M18X0.75
15	PG11 CABLE GLANDS
16	ANTICONDENSATION CAP

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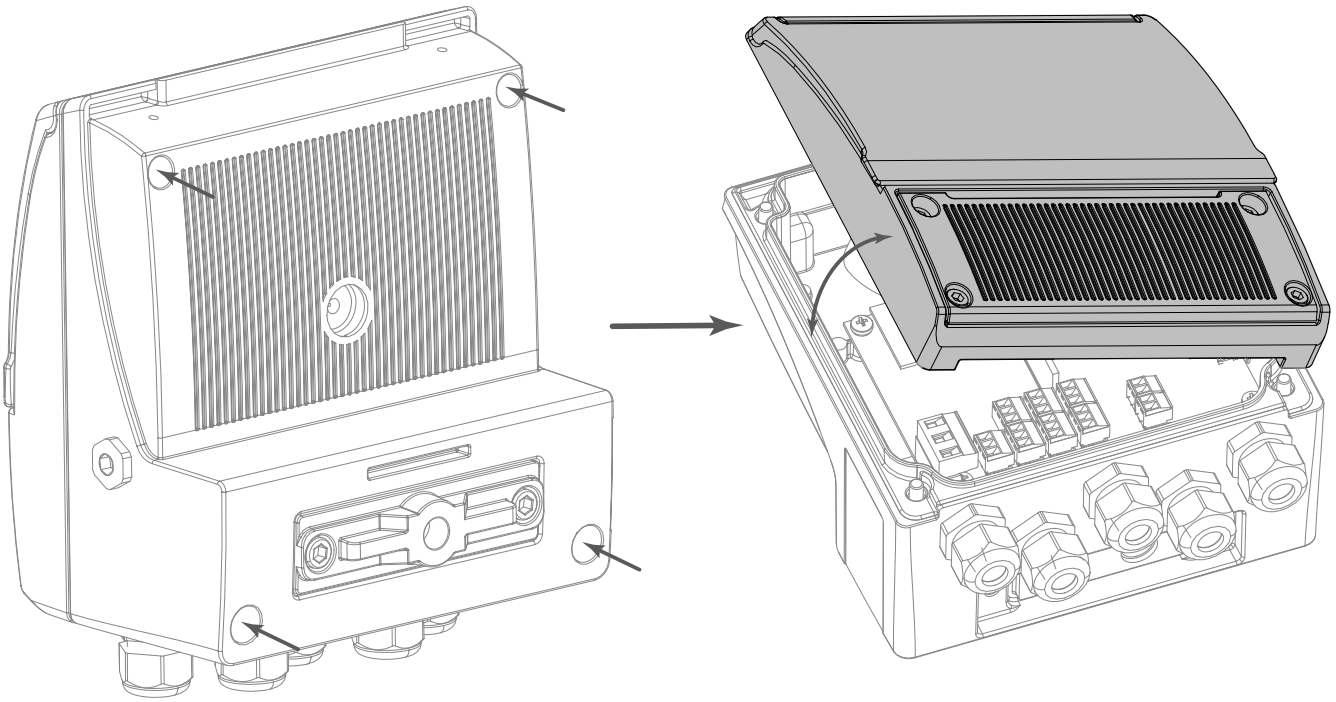
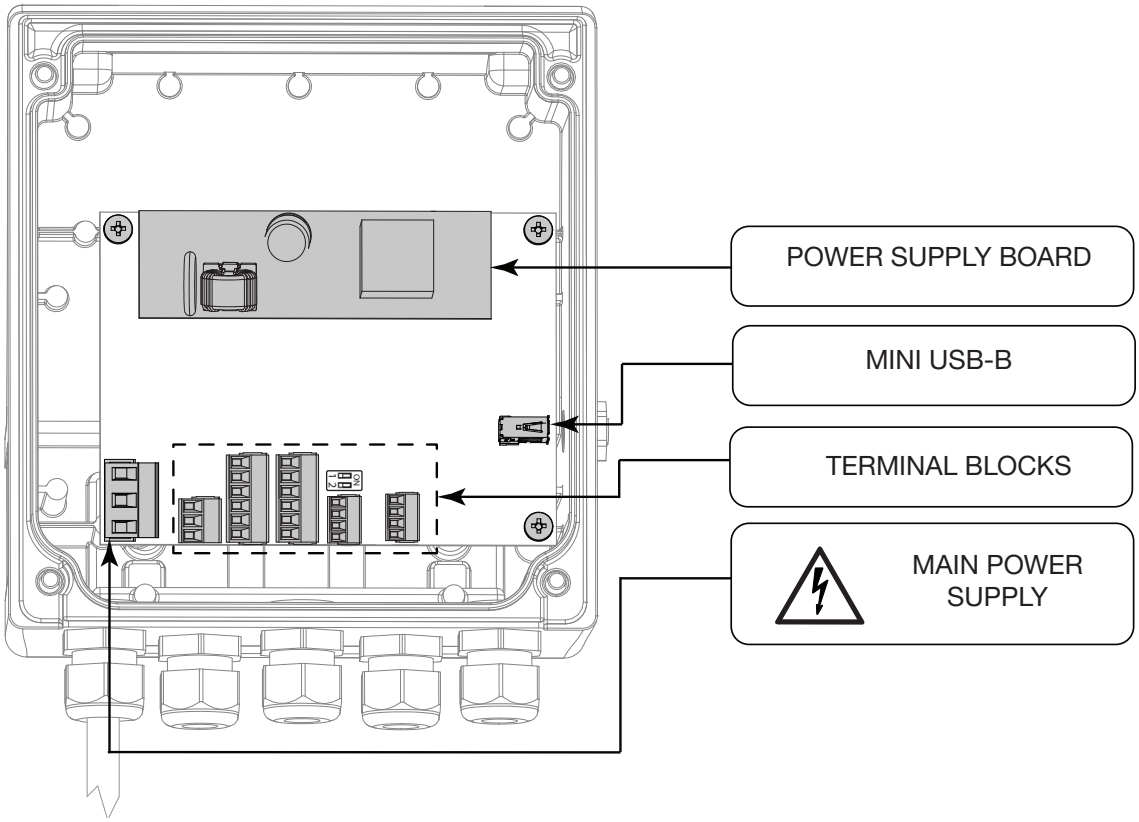
INTERNAL LAYOUT

Internal Transmitter Views

Remove the main housing cover by removing the 4 screws as shown here below.





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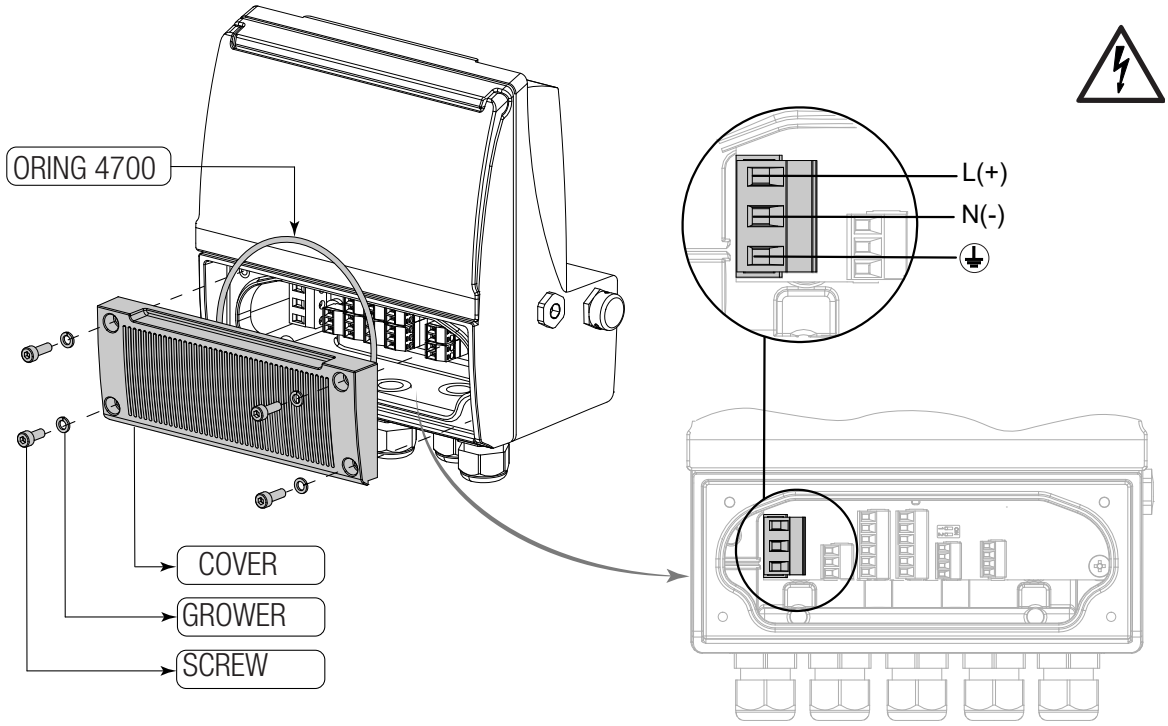
ELECTRICAL CONNECTION AND GROUNDING INSTRUCTIONS

Always ensure that the transmitter and the sensor are grounded (earthed) correctly. The grounding of the sensor and transmitter must ensure that the device and liquid are equipotential.



- Before connecting the power supply, verify that the main voltage is within the limits indicated on data plate.
- For the connections use only approved conductor, with fire-proof properties, whose section varies from 0.25 mm² to 1.50 mm², based on distance/power; additionally fix the power supply wires with an additional fastening system located close to the terminal.
- The power supply line must be equipped with an external protection for overload current (fuse or automatic line breaker).
- Provide in close proximity of the transmitter a magnetothermic circuit breaker easily accessible for the operator and clearly identified; whose symbols must conform to the electrical safety and local electrical requirements.
- Ensure that the component complies with the requirements of the standard for electrical safety distance.
- Check chemical compatibility of materials used in the connection security systems in order to minimize electrochemical corrosion. With aluminum housing should avoid direct contact between the ground connection cable and the aluminum housing. It is therefore recommended to connect the safety ground cable, by placing it between the washer and the metal bracket on the related terminal or use an eyelet terminal crimped on the ground protection cable.
- Sensor's hardwired inputs and outputs are connected to the transmitter through terminal blocks located inside the transmitter.
- To locate the terminal block loosen the 4 screws on the terminal block cover. When the front cover is lifted, the terminal block is visible. The terminal block is the hardwire connection of the transmitter to external equipment, including the sensor.
- The following pages give informations on the terminal block numbering, and the respective connecting of the sensor cables, and inputs/outputs.
- The mains power cables must have adequate values for the maximum current of the appliance, and the cable used must house the standards of the IEC 60227 standard or the IEC 60245 standard.

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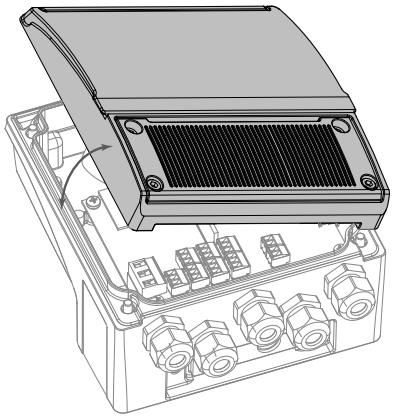
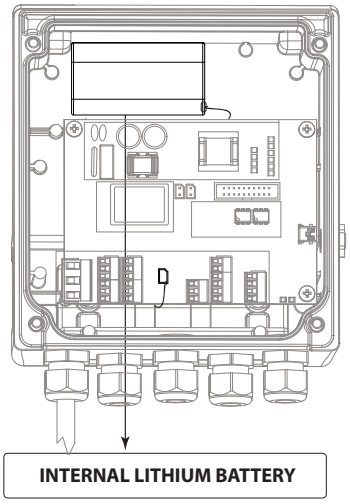
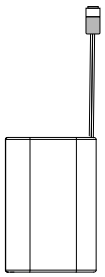
INTERNAL LITHIUM BATTERY

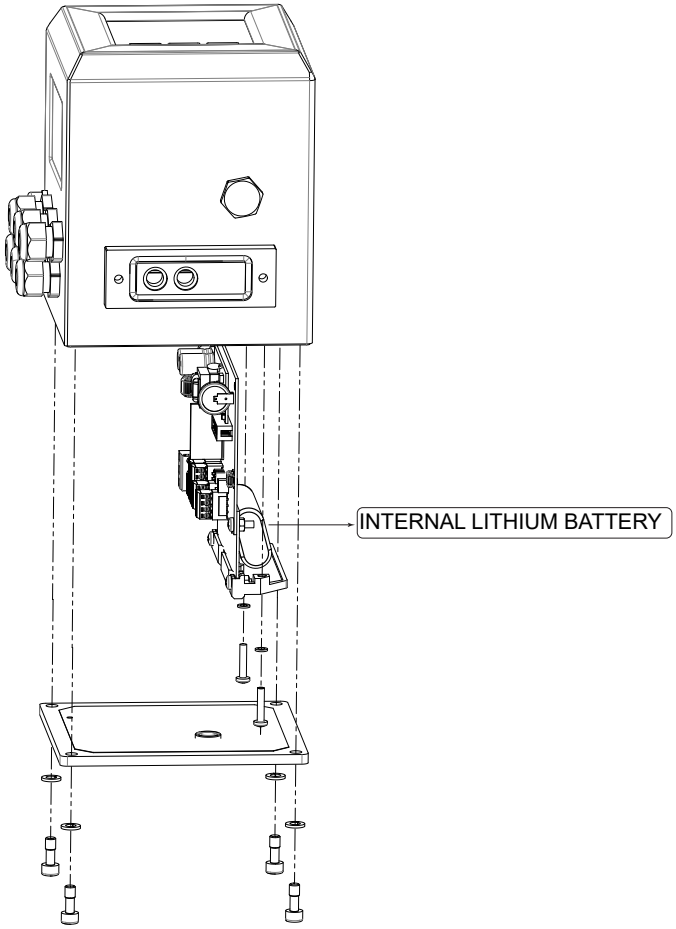
Aluminium and PA6 version







Stainless steel version



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ATTENTION!

- The internal lithium battery is rechargeable and should never be disconnected from the transmitter card when it is powered by the mains voltage. If this operation should be carried out it could irreparably damage the transmitter board.
- The internal lithium battery is recharged only when the transmitter is connected to the mains supply (LV, LLV, HV), battery charging condition, and not with the USB connection.
- During charging, the battery symbol appears on the MCP display and flashes blue; see “MEANING OF FLAGS” page 27 (the colors of the symbols can only be viewed in the virtual display of the MCP interface)
- When the battery charge falls below the minimum potential, battery low, the fixed red battery symbol appears; see “MEANING OF FLAGS” page 27 (the symbol colors can only be displayed in the virtual display of the MCP interface). Furthermore, in this charging condition below the minimum potential, the measurement does not start when the USB cable is connected.
- The thresholds that identify the condition of low battery and battery charging are established by the system according to the use and settings assigned and therefore there is no fixed values..
- The two battery low and battery charging icons can both be present as each one indicates a different condition.

GENERAL OPERATING NOTES

- If the mains voltage is disconnected from the transmitter with HV power supply, the flashing blue icon indicating the charging status can remain active for tens of seconds. This is due to the energy stored in the HV power supply and in the capacities of the circuit that discharge slowly.
- The battery voltage during charging does not rise immediately but gradually. This is related to the parameters set in the transmitter and detected by the controller chip.
- When the battery is physically disconnected the potential measured by the system is not true because the charging circuit checks the battery status by emitting impulses. These load the capacities in the circuit and the average value detected is not to be considered a reliable real value.
- The MCP command [SBCHS] indicates the percentage of charge and is not linear with respect to the battery voltage, however approximately it reads 0% with a voltage equal to about 3.2 V, while 100% occurs with about 4.1 V. These values are influenced by the temperature and the total operating time that worked the battery.

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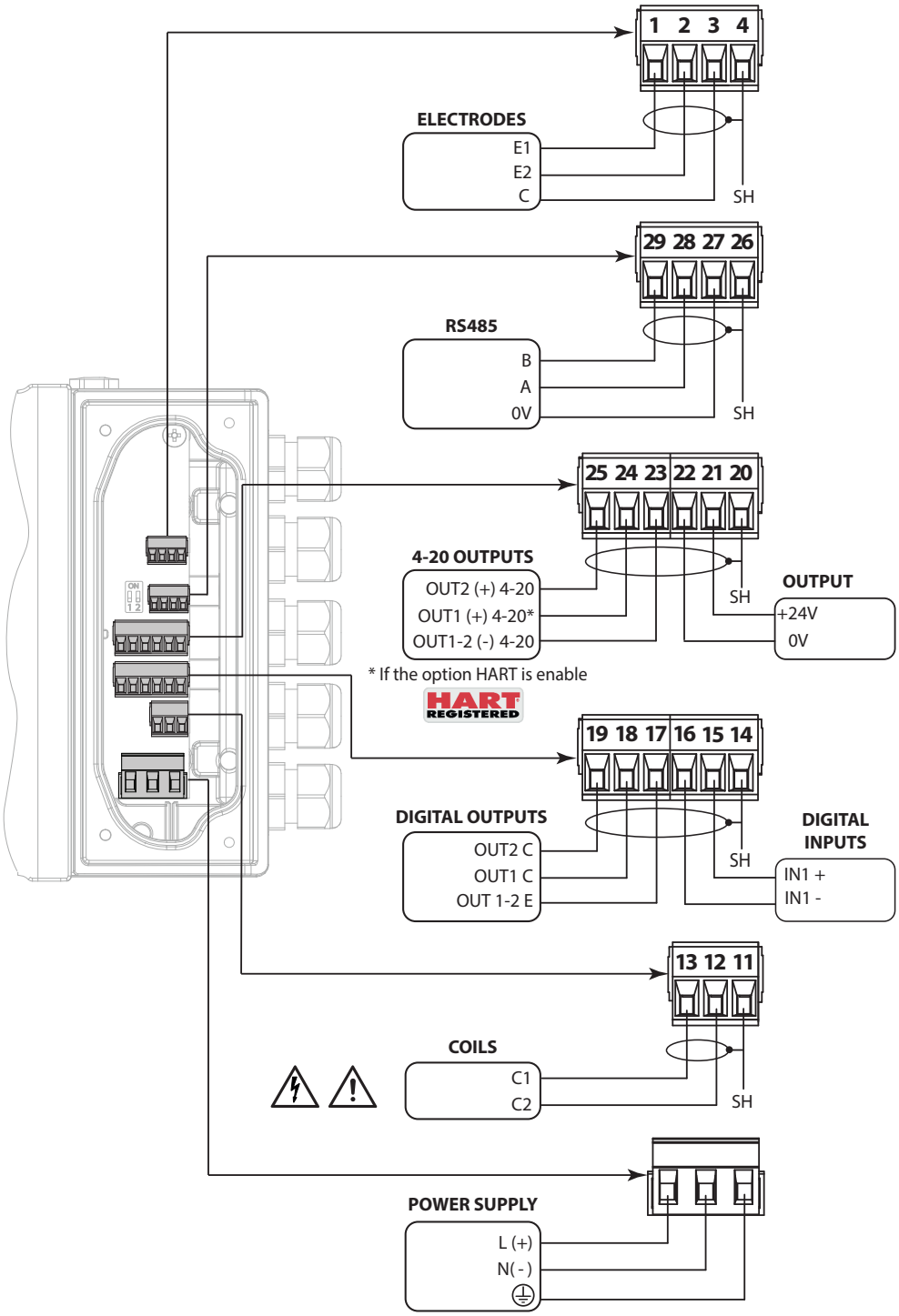
ELECTRICAL CONNECTION TRANSMITTER- SENSOR

Sudden movements of the electrodes cable could introduce noise.

SH = SHIELD OF CABLE internally connected to ground.



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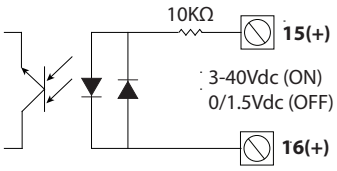
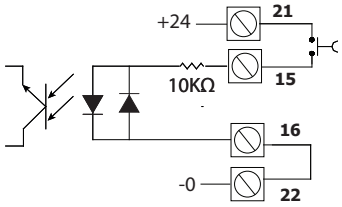
DIGITAL INPUT ON/OFF OPERATION

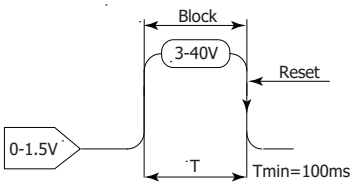
EXTERNAL POWER SUPPLY



INTERNAL POWER SUPPLY



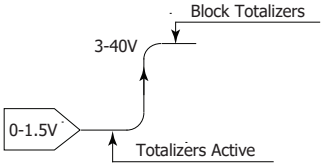
RESET TOTALIZERS



Necessary conditions for enabling the function

- POS. 6.1 see page 36 (T+; total positive set on)
- POS. 6.2 see page 36 (P+; partial positive set on)
- POS. 6.3 see page 36 (T-; total negative set on)
- POS. 6.4 see page 36 (P-; partial negative set on)

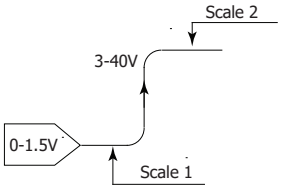
BLOCK TOTALIZERS



Necessary conditions for enabling the function

- POS. 6.5 see page 36 (Totalizer counting lock command set on)

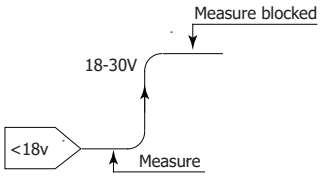
RANGE CHANGE



Necessary conditions for enabling the function

- POS. 6.8 see page 36 (Range change set on)

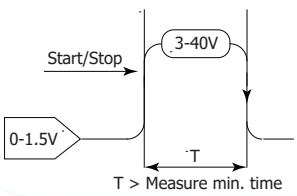
MEASURE LOCK



Necessary conditions for enabling the function

- POS. 6.6 see page 36 (Totalizer counting lock command set on)

BATCHING



Necessary conditions for enabling the function

- 7.1 Output 1 functions, Set to BATCHING

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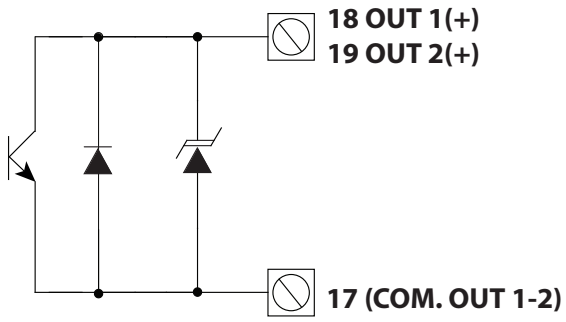
MUST BE
T > Tmin

Measure freq.	T MIN
50HZ	20ms
10HZ	100ms
5HZ	200ms
2HZ	500ms

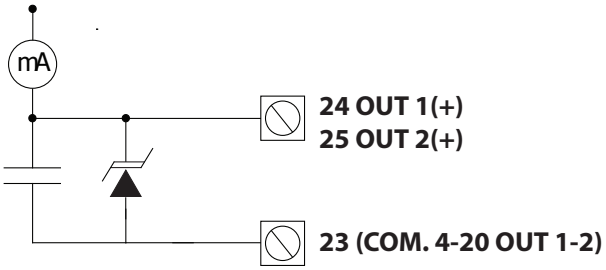
OUTPUTS WIRING

Digital outputs



- Opto-insulated output with floating collector and emitter terminals freely connectable
- Maximum switching voltage: 30 V ⎓
- Maximum switching current: 100mA @ 25 °C
- Maximum saturation voltage between collector and emitter @100mA: 1.2V ⎓
- Maximum switching frequency (load on the collector or emitter, RL=470 Ohm, VOUT=24V ⎓): 1250Hz
- Maximum reverse current bearable on the input during and accidental polarity reversion (VEC): 100mA
- Insulation from other secondary circuits: 500 V ⎓

Analog outputs



- Opto-insulated output
- Maximum load: 1000Ω
- Maximum voltage without load: 27 V⎓
- Refresh frequency is the same of the sample frequency of the connected sensor
- Protected against persistent over voltages to maximum 30 V

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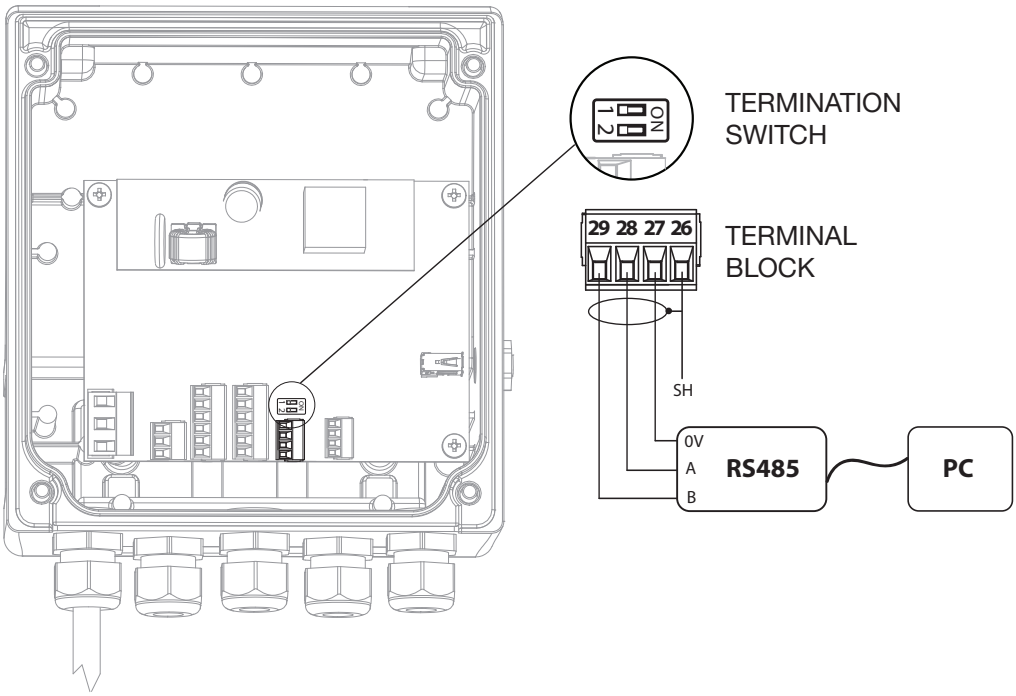
RS485 MODBUS MODULE (OPTIONAL)

Positioning to 'ON' the termination switches 1 and 2, a 120Ω resistance is activated in the RS485 circuit (see terminal block).



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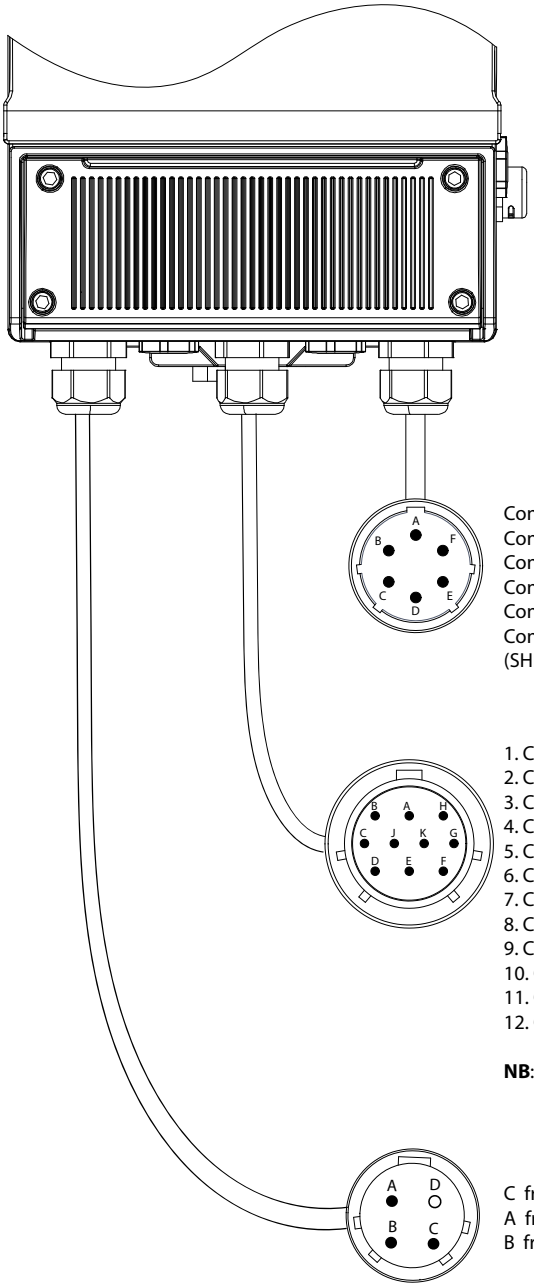
CONNECTORS MIL

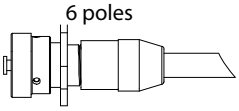
The following are the links of the MIL connectors IP68



SENSOR SIGNALS

Contact A from terminal 1 of the transmitter (electrode 1)
Contact F from terminal 2 of the transmitter (electrode 2)
Contact A from terminal 3 of the transmitter (COM. Elec.)
Contact B from terminal 13 of the transmitter (COIL 1)
Contact C from terminal 12 of the transmitter (COIL 2)
Contact D from terminal 4 and 11 of transmitter
(SHIELD electrodes - COILS)

Connector
6 poles

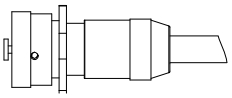


INPUT/OUTPUT

1. Contact B from terminal 24 of the transmitter (Out1 4-20 +)
2. Contact A from terminal 25 of the transmitter (Out2 4-20 +)
3. Contact H from terminal 23 of the transmitter (Out1-2 4-20 -)
4. Contact C from terminal 21 of the transmitter (+ 24V)
5. Contact J from terminal 22 of the transmitter (0V)
6. Contact K from terminal 15 of the inverter (IN1 +)
7. Contact G from terminal 16 of the transmitter (IN1-)
8. Contact D from terminal 19 of the transmitter (C Out2)
9. Contact E from terminal 18 of the transmitter (Out1 C)
10. Contact F from terminal 17 of the transmitter (Out1-2 E)
11. Contact C from terminal 28 of the transmitter (RS485 A)
12. Contact J from terminal 29 of the transmitter (RS485 B)

NB: the connections 4 and 5 exclude the use connections 11 and 12.

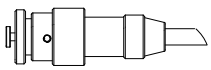
Connector
10 poles



POWER SUPPLY

C from terminal L power transmitter (+ dc)
A from terminal N power transmitter (-dc)
B from terminal GROUND Power transmitter

Connector
4 poles



NOTE: Military Connector 6 poles for sensor transmitter only provided in the remote version of the transmitter.

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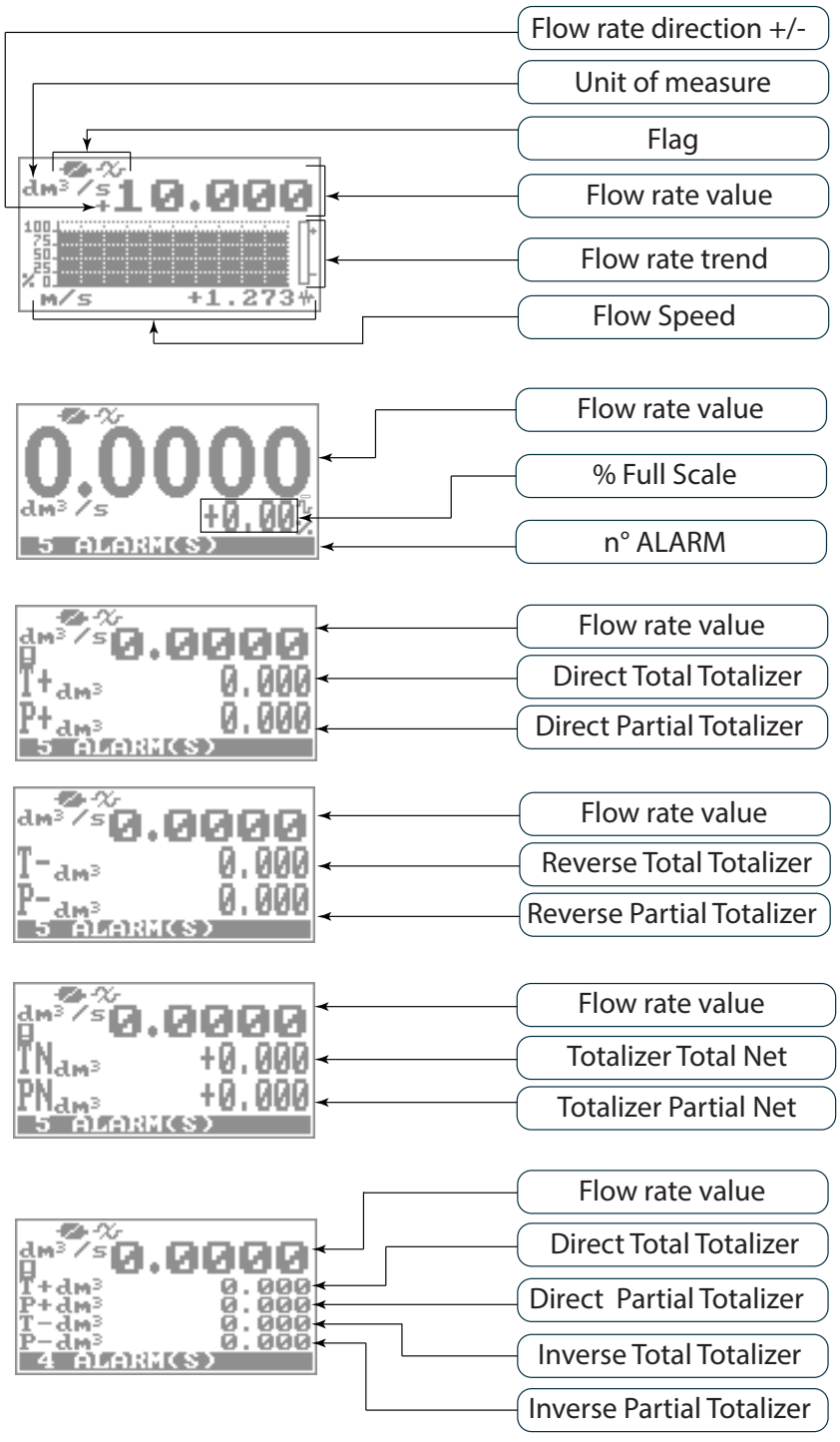
START VISUALIZATION PAGES

The direct exposure of the transmitter to the solar rays, could damage the liquid crystal display.
The visualization pages can be changed according to device's setup.

Push to change visualization



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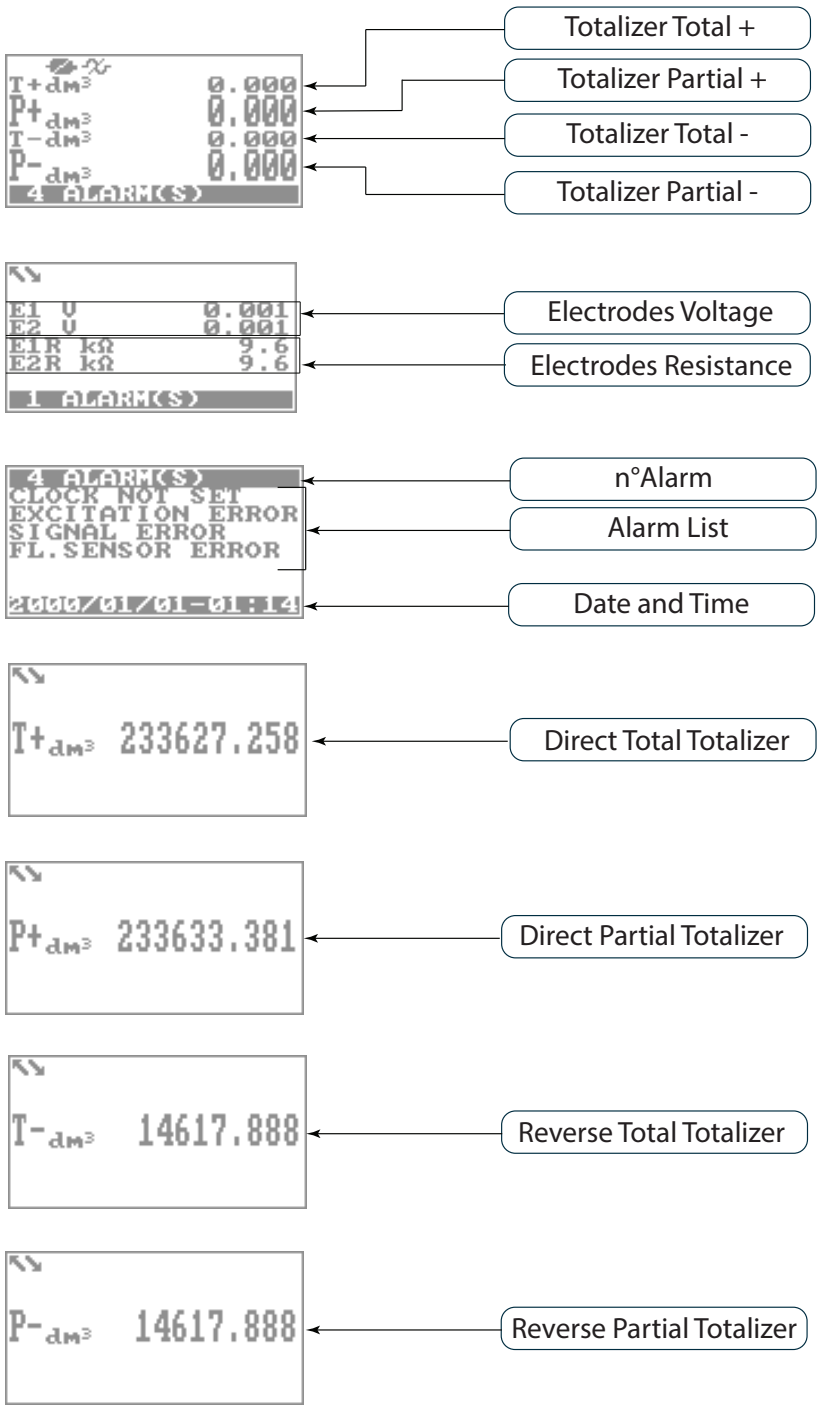
Push to change visualization



The visualization page about batching is described in the dedicated section “BATCHING” page 53

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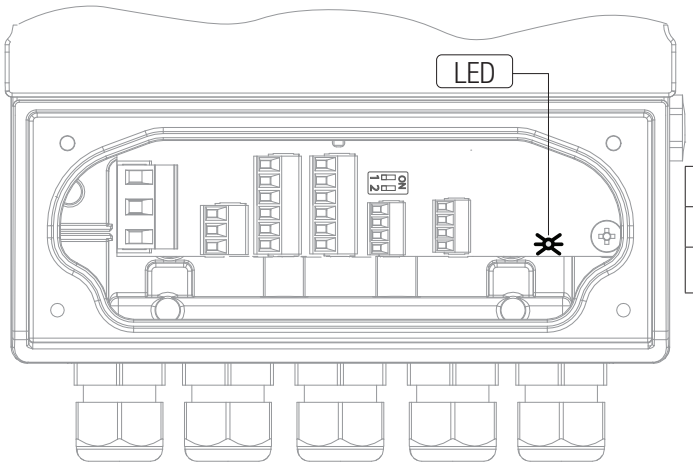
MEANING OF FLAGS

FLAG	DESCRIPTION	FLAG	DESCRIPTION
	EMPTY PIPE		MIN FLOW ALARM
	FILE UPLOAD		MAX FLOW ALARM
	FILE DOWNLOAD		VIRTUAL DISPLAY CONNECTED
	BATTERY RECHARGE (FLASHING) LOW BATTERY (FIXED)		FLOW RATE OVERFLOW
	FLOW RATE SIMULATION (FLASHING)		PULSE 1 OVERFLOW
	CALIBRATION (FLASHING)		PULSE 2 OVERFLOW
	GENERAL ALARM (FLASHING)		POWERED DEVICE WITH ONE CHARGERS BATTERY (MID-DIRECTIVE) or BATCHING IN PROGRESS
	GENERAL ALARM ONLY ON PHYSICAL DISPLAY (FLASHING)		
	SIGNAL ERROR		
	EXCITATION ERROR		

MEANING OF LED COLORS



LED Red: Alarm signal
LED Blue: USB communication enabled
LED Green: the system is working properly

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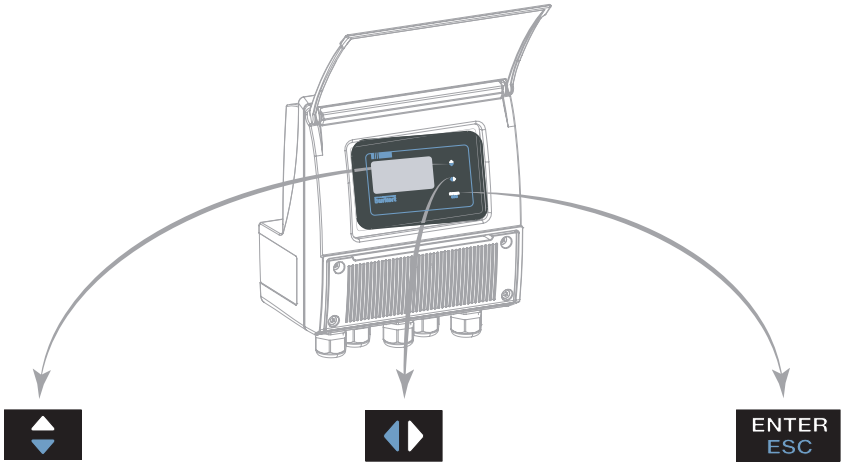
ACCESS TO THE CONFIGURATION MENU

The configuration can be done in two different ways:

- By keypad of transmitter
- By MCP interface (Virtual display of device)

Access Via Keypad



SHORT PRESSING (< 1 SECOND): Increases the numeric figure or the parameter selected by the cursor Returns to the previous subject on the menu.
LONG PRESSING (> 1 SECOND): Decreases the numeric figure or the parameter selected by the cursor. Proceeds to the next subject on the menu.

SHORT PRESSING (< 1 SECOND): Moves/positions the cursor rightward on the input field. Proceeds to the following subject of the menu. Change the display of the process data
LONG PRESSING (> 1 SECOND): Moves/positions the cursor leftward on the input field. Returns to the previous subject on the menu

SHORT PRESSING (< 1 SECOND): Enter /leave the selected function Enables the main menu for the device configuration Cancels the selected function under progress
LONG PRESSING (> 1 SECOND): Leaves the current menu Enables the totalizer reset request (when enabled) Confirms the selected function.

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ACCESS VIA MCP INTERFACE (VIRTUAL DISPLAY)

You can access the device configuration menu by MCP.
MCP is a software that can be installed on Microsoft Windows® and allows you to set all the functions of the transmtter and customize the menu. To use the MCP interface, see its own manual.

However any changes using MCP are not recommended, unless:

- after receiving corresponding training by burkert,
- done by professional,
- agreed by the end user, and done inline with the MCP manual

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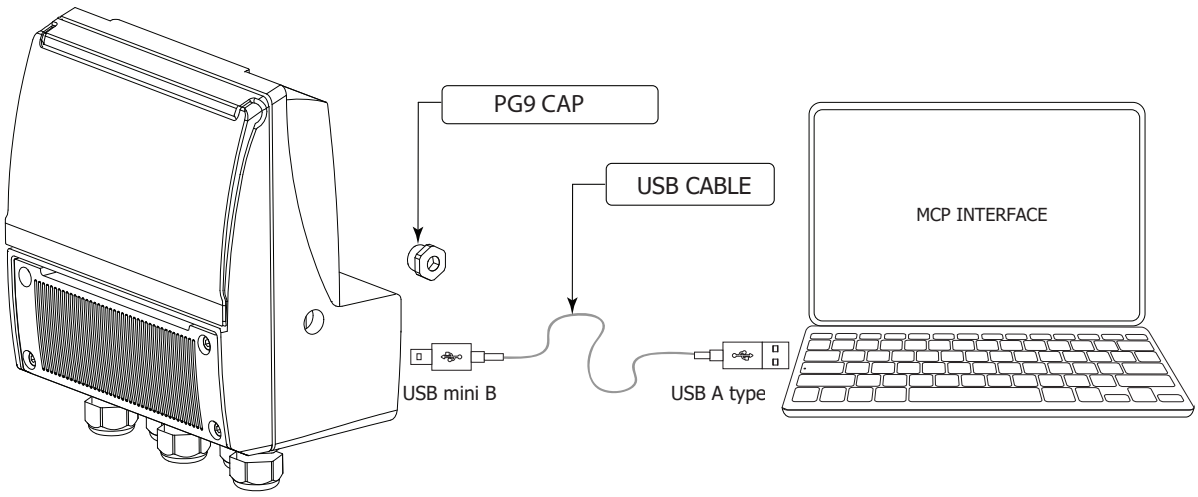
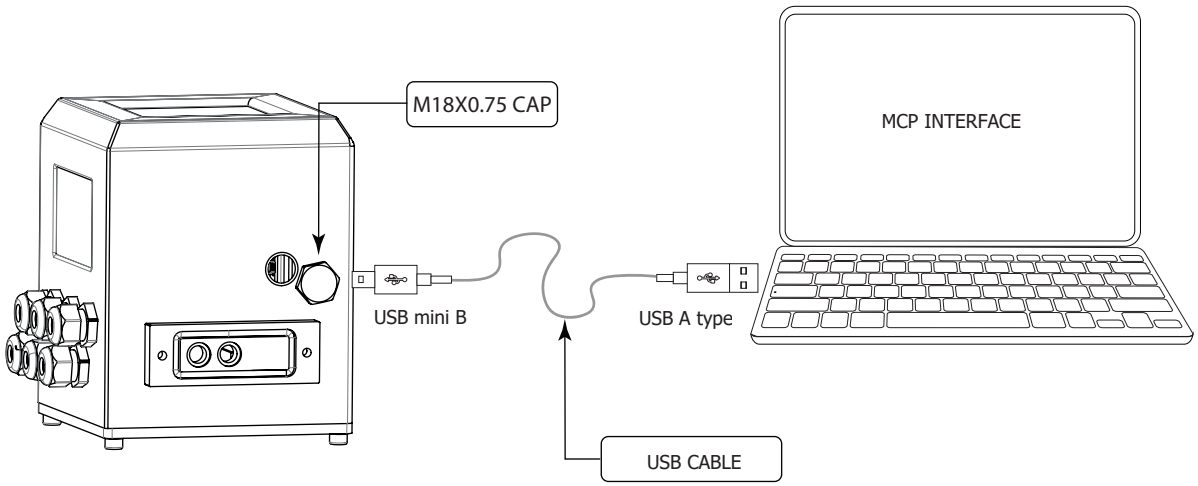
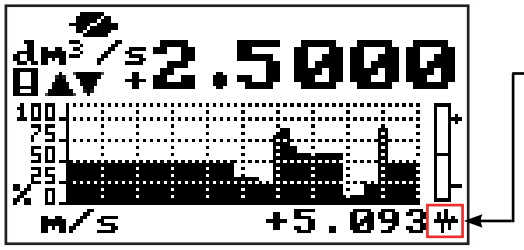
USB Position for PA6 and aluminium version



USB Position for stainless steel version



FLOW RATE VISUALIZATION



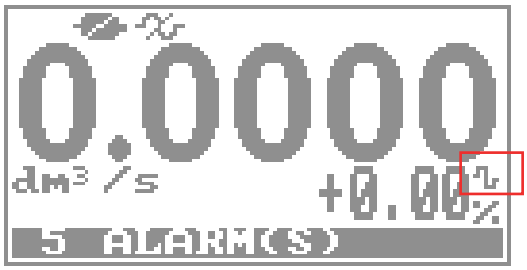
This symbol appears (red color on the virtual display) only when the overall noise is over 2.5% of flow rate.

The SE58 L can show a 5 digits display for flow rate units; this mean the maximum flow rate value that can be represented on the display is 99999 (no matter the positioning of the decimal point). The minimum is 0.0025. The representable measure unit depends on sensor flow rate and diameter; the permitted units are those, that permits the device full scale value not exceeding 99999.

Example for DN 300, Full scale value: 3m/s:

- **PERMITTED:** measure unit (example): l/s (216.00); m3/h (777.60); m3/s (0.2160)
- **NOT PERMITTED:** measure unit (example): l/h (777600)

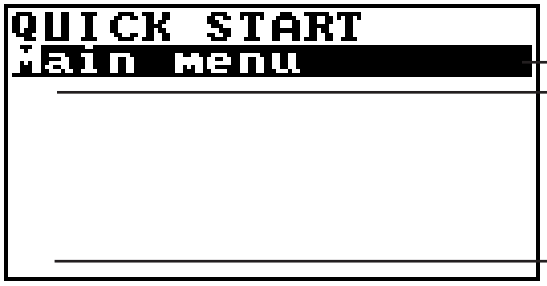
FLOW RATE ALERT



This **FLAG** becomes active when there is a flow variation (flow rate not stable).

QUICK START MENU

The **QUICK START MENU** allows to the user an immediate access to some of the most commonly used functions; through MCP software it is possible to customize this menu to make it suitable for a specific application.



Access to all functions

See programming functions section

The user has immediate access to the Quick Start menu when the transmitter is powered up by pressing the Enter key. If access to the quick start menu does not occur, then it could be disabled using the function “9.11” page 37 .

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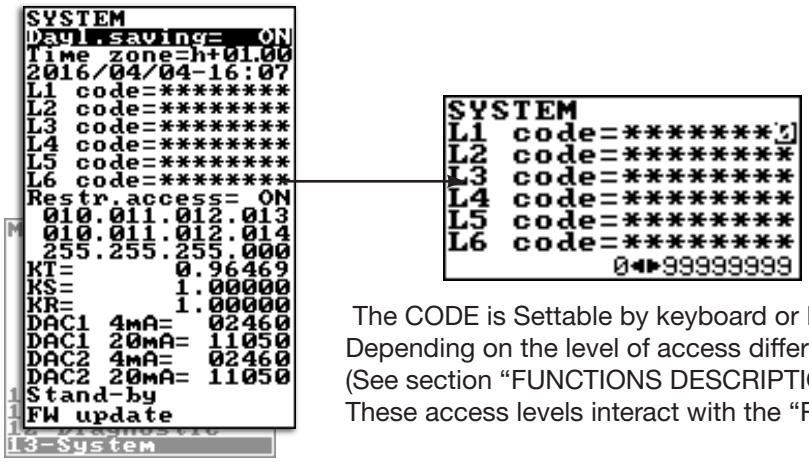
TRANSMITTER ACCESS CODE

The access for programming the device is regulated by six access levels logically grouped.
Every level is protected by a different code.

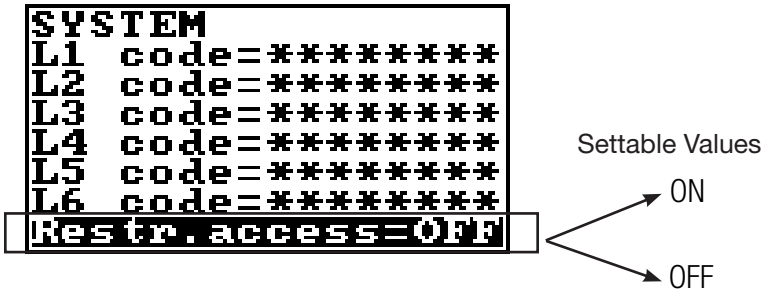
- Access Level 1-2-3-4 Freely programmable by user

Access Code Set : Menu 13 System



The CODE is Settable by keyboard or MCP interface.
Depending on the level of access different display functions will be visible.
(See section “FUNCTIONS DESCRIPTION” page 40)
These access levels interact with the “Restricted access”

Restricted Access Set : Menu 13 System



Restrict = ON: Access permitted only to functions provided for a specific level;
Example: If the operator has a code of access level 3, after having set it, he can change only the functions with level 3 access.

Restrict = OFF: It enables to change functions for the selected level and ALL the functions with lower access level.
Example: If the operator has the code of level 3, after having set it, he can change all the functions at level 3 and those at lower levels.

* **WARNING:** take careful note of the customized code, since there is no way for the user to retrieve or reset it if lost.

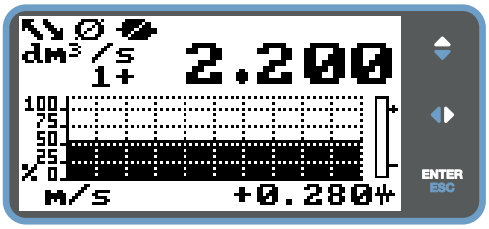
Factory preset access codes:

- L1: 10000000
- L2: 20000000
- L3: 30000000
- L4: 40000000

The following example shows how to change the full scale by Quick Start menu; the second illustrates how to change the function by the Main menu.

EXAMPLE: modifying the full scale value from 4dm³/s to 5dm³/s, from the "Quick start menu"

1

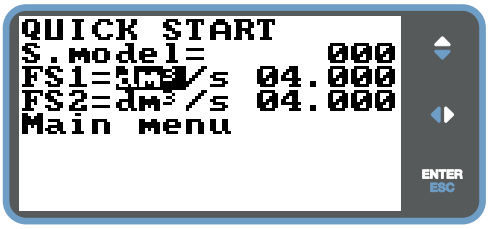


Press the ENTER button to access the Quick Start menu

2

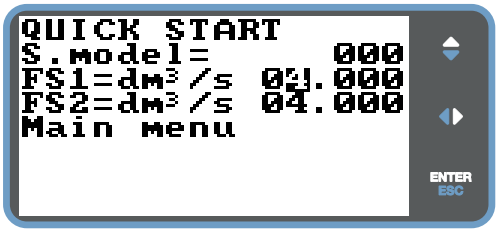
Select this function in the list to be edited

3



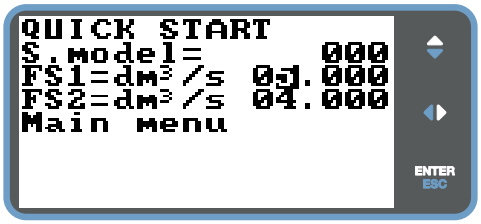
Press the ENTER button to select the function.

4



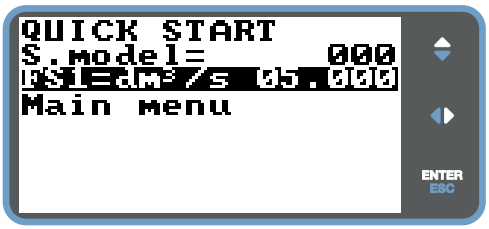
Select the value to be changed

5



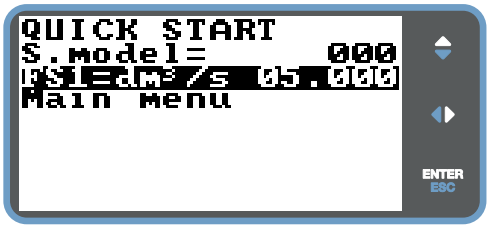
Change the value

6



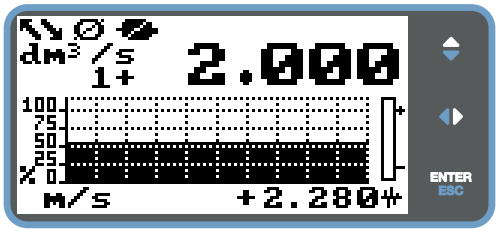
Confirm the new value

7



Long Push

8



Main Page

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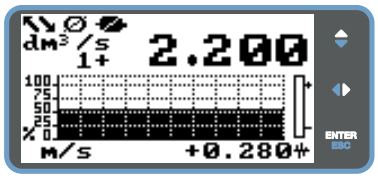
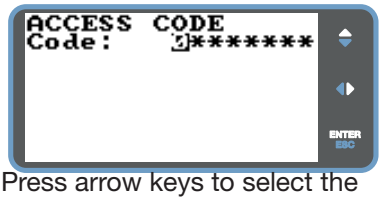
EXAMPLE: modifying the full scale value from 4dm³/s to 5dm³/s, from the “Main Menu” (quick start menu enabled)

1



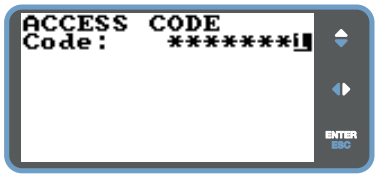
Press the ENTER button to access the Quick Start menu

2



Press arrow keys to select the cell in which to insert the number of the access code.

3



Press ENTER button to confirm value.

4

Select “Main Menu“

5

Press the ENTER button to access the Main Menu

6

Select function

7

Press the ENTER button to access the“Scale Menu“

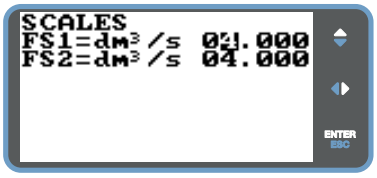
8

Press the ENTER button to access the “FS1“

9

Select the value to be changed

10

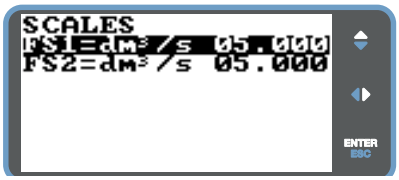


Change the value

11

Press the ENTER button Confirm the new value

12

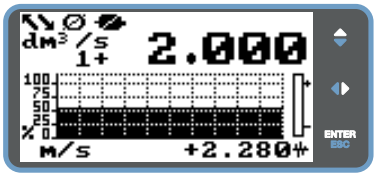


Press Esc

13

Press Esc

14



Main page

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FUNCTIONS MENU

The main menu is selected from the Quick start menu by pressing the key ENTER ESC and entering the access code, if it's required. Note: Some functions are displayed only with other functions active, or with optional modules.

SENSOR

SENSOR			
S. model =	0	1.1	Sensor's model
Lining =	UNSPEC.	1.2	Flow sensor lining material type
S. type =	FULL BORE	1.3	Sensor's type
U.type=	METRIC	1.4	Type of units for sensor's para.
Diam	mm 00025.0	1.5	Sensor's nominal/real diameter
KA =	+00.9637	1.6	Sensor's coefficient KA
KA- =	-04.4904	1.7	Sensor's coefficient KA Negative
KZ =	+0000000	1.8	Sensor coefficient KZ
KD=	+0000000	1.9	Sensor coefficient KD
Ins. position=	0	1.10	Insertion position
KP DinaWmic=	OFF	1.11	KP dynamic, coefficient for insertion
Ki=	01.8727	1.12	Sensor coefficient Ki
Kp=	01.0000	1.13	Sensor coefficient Kp
KC=	1.00000	1.14	Sensor coefficient KC
C.curr =	025.0	1.15	Sensor's excitation current
C.Reg.PB=	004	1.16	Current regulator Prop.Band
C.Reg.DR=	008	1.17	Current regulator Deriv.Const.
S. Freq.= Hz	50	1.18	Measure sampling frequency
Preamplif.	OFF	1.19	Enables the preamplifier
E.P Detect=	ON	1.20	Empty pipe detection
R max= kohm	0500	1.21	Maximum input resistance
El. Cleaning=	OFF	1.22	El.cleaning funct.signal level
S. cable=	m 000	1.23	Sensor's connecting cable length
S. err. delay=	010	1.24	Signal error delay (n. sample)
Sens. verify=	OFF	1.25	Automatic sensor verify enable
Zeropoint cal.		1.26	Pipe hydraulic zero calibration
KL	00.00000000	1.27	Coefficient KL values

UNITS

UNITS			
Diam.	mm	2.1	Sens.diameter unit of measure
S.cable	m	2.2	Sens.cable len.unit of measure
FR.unit	METRIC	2.3	Flow rate unit of measure type
PI1 unit	METRIC	2.4	Pulse 1 unit of measure type
PI2 unit	METRIC	2.5	Pulse 2 unit of measure type
T+ unit	METRIC	2.6	Total.T+ unit of measure type
T+ unit	g	2.7	Total.T+ unit of measure
T+ D.P	3	2.8	Total.T+ Decimal point position
P+ unit	METRIC	2.9	Total.P+ unit of measure type
P+ unit	g	2.10	Total.P+ unit of measure
P+ D.P	3	2.11	Total.P+ Decimal point position
T- unit	METRIC	2.12	Total.T- unit of measure type
T- unit	g	2.13	Total.T- unit of measure
T- D.P	3	2.14	Total.T- Decimal point position
P- unit	METRIC	2.15	Total.P- unit of measure type
P- unit	g	2.16	Total.P- unit of measure
P- D.P	3	2.17	Total.P- Decimal point position
Temp.unit	°C	2.18	Temperature unit of measure
Mass units	ON	2.19	Mass units enabling
Sg=kg/dm3	1.0000	2.20	Specific gravity coefficient

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SCALES

SCALES			
FS1 g/s	4908.7	3.1	Full scale flow rate for range 1
B.qty dm3	1.00000	3.2	Batching quantity
FS2 g/s	4908.7	3.3	Full scale flow rate for range 2
Pls1=g	1000.00	3.4	Output 1 pulse volume value
Tpls1=ms	0050.0	3.5	Output 1 pulse time value
Pls2=g	1000.00	3.6	Output 2 pulse volume value
Tpls2=g	0050.0	3.7	Output 1 pulse time value
Frq1=Hz	1000.00	3.8	Output 1 full scale frequency
Frq2=Hz	1000.00	3.9	Output 2 full scale frequency

MEAS.

MEASURES			
Damping	SMART	4.1	Measure damping digital filter
Cut-off= %	00.1	4.2	Measure cut-off threshold
DT Min.	ON	4.3	Automatic calibration verify
Autorange	ON	4.4	Automatic f.scale range change
H.imm.inp.	OFF	4.5	High immunity input noise filter

ALARMS

ALARMS			
Max+ = dm3/s	OFF	5.1	Max.pos.flow r.alarm threshold
Max- = dm3/s	OFF	5.2	Max.neg.flow r.alarm threshold
Min+= dm3/s	OFF	5.3	Min.pos.flow r.alarm threshold
Min-= dm3/s	OFF	5.4	Min.neg.flow r.alarm threshold
Hysteresis=%	03	5.5	Hysteresis threshold set for the minimum and maximum flow rate alarms
mA v.alarm=%	000	5.6	Current value in case of alarm
Hz v.alarm=%	000	5.7	Frequency value in case of alarm

INPUTS

INPUTS			
T+ reset	OFF	6.1	Totaliz.T+ reset input enable
P+ reset	OFF	6.2	Totaliz.P+ reset input enable
T- reset	OFF	6.3	Totaliz.T- reset input enable
P- reset	OFF	6.4	Totaliz.P- reset input enable
Count lock	OFF	6.5	Totaliz.count lock input enable
Meas.lock	OFF	6.6	Measure zero lock input enable
Calibration	OFF	6.7	Calibration func.input enable
Range change	OFF	6.8	Flow rate range change input en.

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OUTP.

OUTPUTS	
Out1	PULSES+
Out2	PULSES-
Out mA1	4_22 +/-
Out mA2	4_22 +/-
A1S	4.9087
A2S	4.9087

7.1	Output 1 function selection
7.2	Output 2 function selection
7.3	Analog current output 1 range
7.4	Analog current output 2 range
7.5	Full scale value for analog out1
7.6	Full scale value for analog out2

COMM.

COMMUNICATION	
HART pr.	05
HART O. C.	ON
Dev. Addr	001
Speed=bps	9600
Parity=	NO
Delay=ms	00
C. timeout	2
MBUS ID =	220483
MBUS Dev.T =	7

8.1	HART packet byte preambles
8.2	HART bus output control
8.3	Device communication address number
8.4	MODBUS link speed
8.5	MODBUS link parity
8.6	MODBUS reply delay
8.7	Maximum delay between chars (frames)
8.8	MeterBus Id.Number (Second.Add.)
8.9	MeterBus Device Type (Media)

HART REGISTERED

DISPLAY

DISPLAY	
Language	EN
Contrast	5
Disp.time=s	020
D.rate=Hz	5
Disp. Fn.	1
Disp.lock	ON
Part. Tot	ON
Neg. Tot.	ON
Net tot.	ON
Disp.date	ON
Quick start	ON

9.1	Language for all messages
9.2	Display Contrast adjustment
9.3	Display/keyboard inactivity time
9.4	Display refresh rate
9.5	Display function number
9.6	Display function selection lock
9.7	Partial totalizer enable
9.8	Negative totalizer enable
9.9	Net totalizer enable
9.10	Time and date display enable
9.11	Quick start menu enable

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DATA LOGGER

DATA LOGGER			
D.logger en.	ON	10.1	Data logger sampling enable
Meas. units	ON	10.2	Measure units recording enable
Field separat.	;	10.3	Field separator character
Decimal separ.	.	10.4	Decimal separator character
Interv.	01:01:00	10.5	Sampling interval
Log T+	ON	10.6	Totaliz.T+ logging enable
Log P+	ON	10.7	Totaliz.P+ logging enable
Log T-	ON	10.8	Totaliz.T- logging enable
Log P-	ON	10.9	Totaliz.P- logging enable
Log TN	ON	10.10	Tot.Net Total logging enable
Log PN	ON	10.11	Tot.Net Partial logging enable
Log Q (UM)	ON	10.12	Flow rate in unit of meas.enable
Log Q (%)	ON	10.13	Flow rate in percentage enable
Log AL.EV	ON	10.14	Alarm events logging enable
Log STR	ON	10.15	Sensor's test results log.enable
Log BTS	ON	10.16	Board temperatures logging en.
Log IBV	ON	10.17	Internal board volt. log.enable
Log EDC	ON	10.18	Electrodes DC voltage log.enable
Log EAC	ON	10.19	Electrodes AC voltage log.enable
Log EIZ	ON	10.20	Electrodes impedance log.enable
Log SCV	ON	10.21	Sensor's coils values log.enable

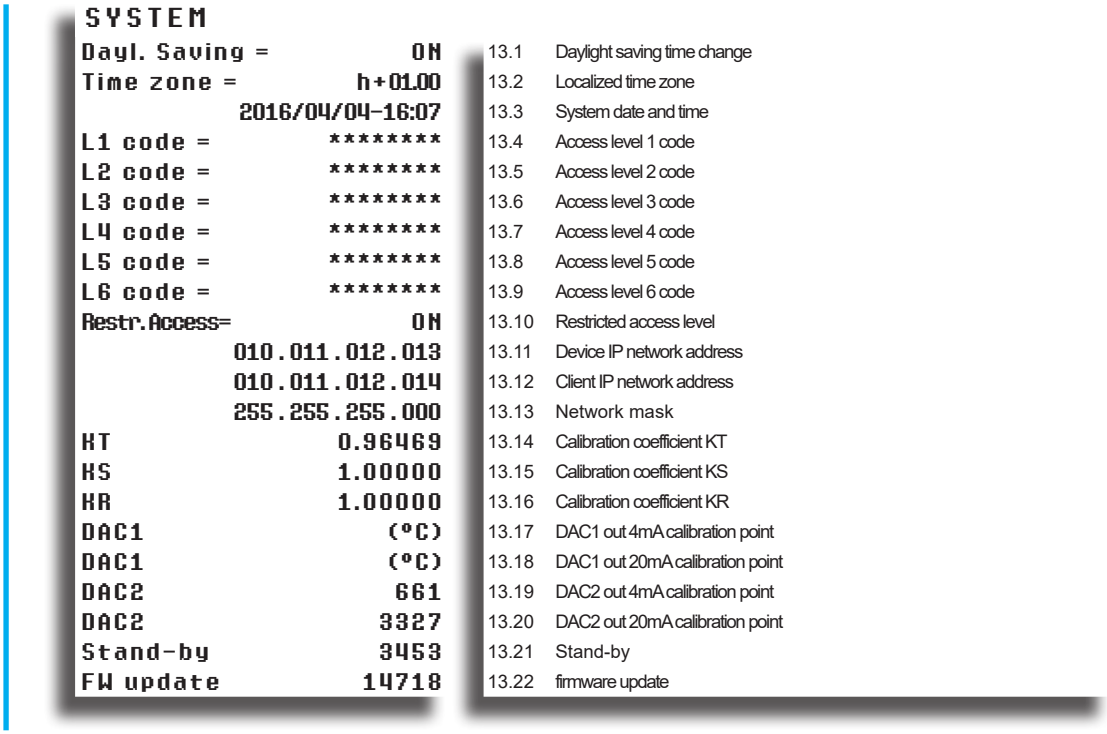
FUNCT.

FUNCTIONS		
T+ reset	11.1	Totaliz.T+ reset function
P+ reset	11.2	Totaliz.P+ reset function
T- reset	11.3	Totaliz.T- reset function
P- reset	11.4	Totaliz.P- reset function
Load Sens. F. def	11.5	Load sensor factory default val.
Load Conv. F. def	11.6	Load converter factory def. val.
Save Sens. F. def	11.7	Save sensor factory default val.
Save Conv. F. def	11.8	Save converter factory def. val.
Calibration	11.9	Internal circuit calibration

DIAGN.

DIAGNOSTIC			
Self test		12.1	Self test diagnostic function
Test display		12.2	Function tests physical display
Sens. verify		12.3	Sens.verify diagnostic function
Flow sim. =	ON	12.4	Flow rate simulation function
Display measures		12.5	Display internal measured value
Disp. Comm. Vars		12.6	Display comm. diagnostic values
Display graphs		12.7	Display measures as graphs
Gen. sens. set		12.8	Generic sensor parameters set
SD card info		12.9	Sd card status information
Firmware info		12.10	Firmware version information
S/N=	999001	12.11	Board serial number (read only)
WT=	002:21:00 : 22	12.12	Total working time (read only)

SYSTEM



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FUNCTIONS DESCRIPTION

Here below the explanation on how the rows of menu are described.

Menu visualized on the transmitter (from 1 to 13)

MENU 1 - SENSOR

(POS. 1.1) *Sensor MODeL*	[S. model xxx]	*AL4*	[SMODL]

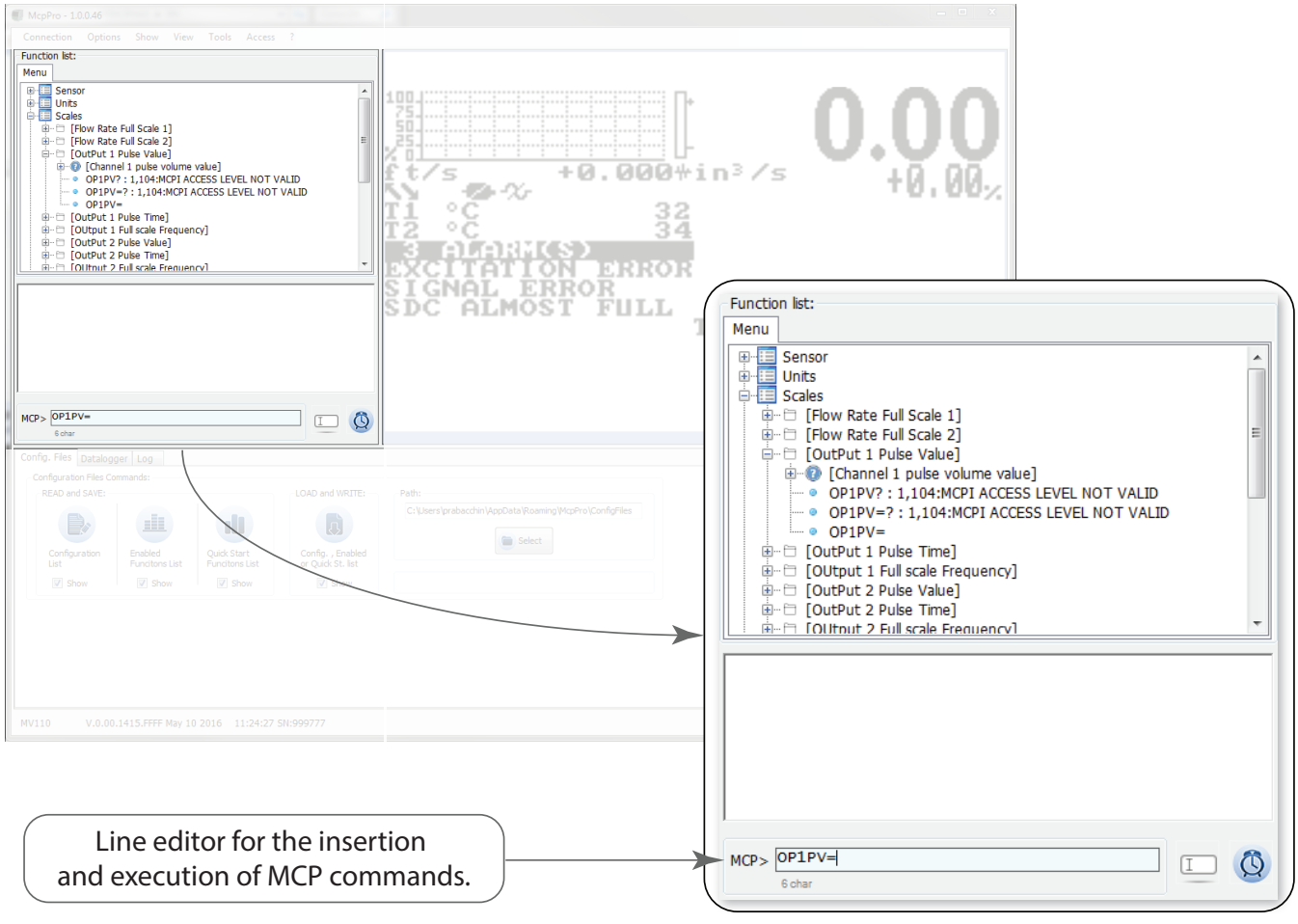
Access level

MCP command

Function as shown on device display

Command MCP acronym

The following picture describes where to find the MCP functions, using MCP-software.
For more details see MCP manual.



Line editor for the insertion and execution of MCP commands.

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MENU 1 - SENSOR

(POS. 1.1) Sensor MODeL	*[S. model xxx]*	AL4	[SMODL]

Enter the first two characters of the serial number of the sensor as on the sensor label.

(POS. 1.2) LIning MAterial Type	*[Lining= UNSPEC.]*	AL4	[LIMAT]

Flow sensor lining material type. (PFA; PU-TDI; ALON; PEEK; HR; PP; PA-11; PTFE-HT; PTFE)

(POS. 1.3) Sensor TYPE	*[S. type= FULL BORE]*	AL4	[STYPE]

Select the sensor type of full-bore or insertion.

(POS. 1.4) Sensor Units TYPe	*[U.type= METRIC]*	AL4	[SUTYP]

Select type of measure unit of sensor's parameter. Values metric or imperial (inch).

(POS. 1.5) Pipe DIaMeter Value	*[Diam.= mm xxx]*	AL4	[PDIMV]

Select the nominal diameter of the sensor (0-2500). ND is written on the sensor label.

(POS. 1.6) CoeFFicient KA	*[KA= + xx.xxx]*	AL4	[CFFKA]

KA factor: calibration coefficient

(POS. 1.7) CoeFficient KA Negative	*[KA= - xx.xxx]*	AL4	[CFKAN]

KA factor: calibration coefficient for negative flow. This function is showed only if at least 1 negative KL value is set.

(POS. 1.8) CoeFFicient KZ	*[KZ= +/- xxxxx]*	AL4	[CFFKZ]

Calibration Factor KZ

(POS. 1.9) CoeFFicient KD	*[KD= +/- xxxxx]*	AL4	[CFFKD]

Calibration Dynamic Factor.

(POS. 1.10) Sensor Insertion POSition	*[Ins.position= x]*	AL4	[SIPOS]

This function is active with POS.1.3 on "Insertion". See the insertion sensor manual for more details

(POS. 1.11) CoeFFicient Kp	*[KP dynamic= ON/OFF]*	AL4	[CFFKP]

This function is active with POS. 1.3 see page 35 set on insertion. See manual of insertion sensor for more details

(POS. 1.12) CoeFFicient Ki	*[Ki= +/- xx.xxx]*	AL4	[CFFKI]

This function is active with POS. 1.3 see page 35 set on insertion. See manual of insertion sensor for more details

(POS. 1.13) CoeFFicient Kp	*[Kp = +/- xxxxx]*	AL4	[SIDKP]

This function is active with POS. 13.1 see page 39 set on insertion. See manual of insertion sensor for more details

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(POS. 1.14) CoeFFicient KC	*[KC= +/- xx.xxx]*	AL4	[CFFKC]

Calibration Factor. This function is activated if the sensor model is NOT present on the sensors table standard parameters

(POS. 1.15) Coils EXCitation Current	*[C.Curr.= mA xxx.x]*	AL4	[CEXCC]

Coils' excitation current. This function is activated if the sensor model is NOT present on the sensors table standard parameters

(POS. 1.16) Coils Regulator PRoportional Band	*[C.Reg.PB= xxx]*	AL4	[CRPRB]

Current regulator parameter. This function is activated if the sensor model is NOT present on the sensors table standard parameters

(POS. 1.17) Coils Regulator DERivative constant	*[C.Reg. DK = xxx]*	AL4	[CRDER]

Current regulator parameter. This function is activated if the sensor model is NOT present on the sensors table standard parameters

(POS. 1.18) PREamplifier INstalled	*[Preamplif.= ON]*	AL4	[PREIN]

This function enable/disable the presence of the preamplifier. The use of the preamplifier inhibit the possibility to use BIV and Empty Pipe Detection.

(POS. 1.19) Sampling FREQuency	*[S.Freq.= Hz xx]*	AL4	[SFREQ]

Measure sampling frequency. This function is activated if the sensor model is NOT present on the sensors table standard parameters.

(POS. 1.20) Empty Pipe Detection ENable	*[E.P.Detect= ON]*	AL4	[EPDEN]

Enables the empty pipe detection function. This function is useful to keep the meter lock to zero when the pipe becomes empty.

(POS. 1.21) Empty Pipe Detection THreshold	*[R max= Kohm xxxx]*	AL4	[EPDTH]

Maximum resistance value at the inputs (electrodes) determine the empty pipe condition. This feature is enabled only if the "1.19" page 35 Empty Pipe Detection is ON.

(POS. 1.22) ELectrodes CLeaNing	*[El. cleaning=AVG]*	AL4	[ELCLN]

This function is useful to keep the electrodes clean; the allowed values are: OFF, minimum, average and maximum. It is not recommended to use this function when the liquid has a conductivity less than 100µS/cm (set to OFF).

(POS. 1.23) Sensor CAble LeNgth	*[S.cable=m xxx]*	AL4	[SCALN]

Lenght of cable between sensor and transmitter on remote version.

(POS. 1.24) Signal Error ALarm Time	*[S.err.delay=m xxx]*	AL4	[SEALT]

Delay before generating error. This function is useful to prevent unexpected lock to zero of measure caused by sporadic events (empty pipe, excitation error, signal error)

(POS. 1.25) Automatic Sensor VeriFy Enable	*[Sens. verify= OFF]*	AL3	[ASVFE]

Enable the Automatic sensor verification (see BIV optional function).

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(POS. 1.26) SET KJ value	*[Zero point cal.]*	[SETKJ]

This feature appears only when the process conditions are as follow:
measure filters recommended (Damping) set to SMART 2 second / 5 second
stable flow rate and lower than 0.1% of the absolute scale (10 m/s)
It must have elapsed at least 10 minutes after the last significant change of flow rate
When the above conditions are met, the zero point calibration function will appear on the display, press the "Enter / ESC" and automatically the procedure will start.
NOTICE: Be sure that the sensor is completely full of liquid and perfectly still. Even subtle movements of the fluid can cause significant errors, therefore proceed with great care.

(POS. 1.27) SET KL values	*[KL=XX +/- XXXXXXXXX]*	AL4	[SETKL]

Linearization coefficient for negative flow, reserved to the service. This command is only shown if SMODL = 000.

MENU 1 - SENSOR: ONLY MCP FUNCTIONS

Sensor Coils TiMe A	*[MCP ONLY]*	AL4	[SCTMA]

Reference sensor coil time A

Sensor Coils TiMe B	*[MCP ONLY]*	AL4	[SCTMB]

Reference sensor coil time B

Sensor Coils RESistance	*[MCP ONLY]*	AL4	[SCRES]

Reference sensor coil resistance

Sensor E1 Reference Resistance	*[MCP ONLY]*	AL4	[SE1RR]

Resistance value of E1 electrodes

Sensor E2 Reference Resistance	*[MCP ONLY]*	AL4	[SE2RR]

Resistance value E2 electrodes

Sensor Coils Temperature ReFerence	*[MCP ONLY]*	AL4	[SCTRF]

Sensor data reference temperature. Temperature measured on the coils of the sensor at the time of saving the device reference data for B.I.V. function. The temperature is expressed in celsius degrees, and refers to the owns sensor temperature.
Note: the temperature must be estimated on the basis of the place of the sensor installation.

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MENU 2 - UNITS

WARNING: The totalizer value is updated and changed depending on the setting of unit value.
The scale change may cause accuracy loss depending of rounding up.
For example, if T +=0,234 liters with 3 decimals, it become T += 0.001 m^3 losing 0.234 liters in rounding up.

(POS. 2.1) Sensor Diameter Unit of Measure	*[Diam.= mm]*	AL2	[SDIUM]

Sensor diameter unit of measure (mm or inch)

(POS. 2.2) Sensor CAble length Unit of Measure	*[S.Cable= m]*	AL2	[SCAUM]

Sensor cable length for remote version. Select m or foot.

(POS. 2.3) Flow Rate Unit of Measure Type	*[FR unit= METRIC]*	AL2	[FRMUT]

Flow rate type measure unit. Select metric or not metric (Imperial units)

(POS. 2.4) PuLse 1 Unit of measure Type	*[PL1 unit= METRIC]*	AL2	[PL1UT]

This function is active with POS. 7.1 see page 37 enable.
This function changes the choice of measure unit POS. 3.4 see page 36
Pulse 1 type measure unit: metric or not metric (Imperial units).

(POS. 2.5) PuLse 2 Unit of measure Type	*[PL2 unit= METRIC]*	AL2	[PL2UT]

This function is active with POS. 7.2 see page 37 enable.
This function changes the choice of measure unit POS. 3.6 see page 36
Pulse 2 type measure unit: metric or not metric Imperial units).

(POS. 2.6) Totalizer Total Positive Unit of measure Type	*[T+ unit= METRIC]*	AL2	[TTPUT]

Setting total positive totalizer measure unit type: metric or not metric Imperial units).
This function changes the values measure unit on POS. 2.7 see page 35

(POS. 2.7) Totalizer Total Positive Unit of Measure	*[T+ unit= dm^3]*	AL2	[TTPUM]

Setting total positive totalizer measure unit.
This function visualized on visualization pages.

(POS. 2.8) Totalizer Total Positive Decimal Point position	*[T+ D.P.= x]*	AL2	[TTPDP]

Setting total positive totalizer decimal point position.
Example: T+D.P.= 3 visualized value T+dm^3 0.000 / T+D.P.= 2 visualized value T+dm^3 0.00

(POS. 2.9) Totalizer Partial Positive Unit of measure Type	*[P+ unit= METRIC]*	AL2	[TPPUT]

This function is active with POS. 9.7 see page 37 enable.
Setting partial positive totalizer measure unit type: metric or not metric (Imperial units).
This function changes the values measure unit on POS. 2.10 see page 35 .
It is visualized on visualization pages.

(POS. 2.10) Totalizer Partial Positive Unit of Measure	*[P+ unit= dm^3]*	AL2	[TPPUM]

Setting partial positive totalizer measure unit.
This function visualized on visualization pages.

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(POS. 2.11) Totalizer Total Positive Decimal Point position *[P+ D.P.= x]* *AL2* **[TPPDP]**

Setting partial positive totalizer decimal point position.
Example: P+D.P.= 3 visualized value P+dm³ 0.000 / P+D.P.= 2 visualized value P+dm³ 0.00

(POS. 2.12) Totalizer Total Negative Unit of measure Type *[T- unit= METRIC]* *AL2* **[TTNUT]**

This function is active with POS. 9.8 see page 37, enabled.
Setting total negative totalizer measure unit type: metric or not metric (Imperial units).
This function changes the values measure unit on POS. 2.13 see page 35.
It is visualized on visualization pages.

(POS. 2.13) Totalizer Total Negative Unit of Measure *[T- unit= dm³]* *AL2* **[TTNUM]**

Setting total negative totalizer measure unit.
This function visualized on visualization pages.

(POS. 2.14) Totalizer Total Negative Decimal point position *[T- D.P.= x]* *AL2* **[TTNDP]**

Setting total negative totalizer decimal point position.
Example: T- D.P.= 3 visualized value T- dm³ 0.000
T- D.P.= 2 visualized value T- dm³ 0.00

(POS. 2.15) Totalizer Partial Negative Unit of measure Type *[P- unit= METRIC]* *AL2* **[TPNUT]**

This function is active with POS. 9.8 see page 37, enable.
Setting partial negative totalizer measure unit type: metric or not metric (Imperial units).
This function changes the values measure unit on POS. 2.16 see page 35
It is visualized on visualization pages.

(POS. 2.16) Totalizer Partial Negative Unit of Measure *[P- unit= dm³]* *AL2* **[TPNUM]**

Setting partial negative totalizer measure unit.
This function visualized on visualization pages.

(POS. 2.17) Totalizer Partial Negative Decimal Point position *[P- D.P.= x]* *AL2* **[TPNDP]**

Setting partial negative totalizer decimal point position.
Example: P- D.P.= 3 visualized value P-dm³ 0.000
P- D.P.= 2 visualized value P-dm³ 0.00

(POS. 2.18) TeMPerature Unit of Measure *[Temp. unit= C°]* *AL2* **[TMPUT]**

Setting temperature measure unit.

(POS. 2.19) MaSS Units Enable *[Mass units= ON/OFF]* *AL2* **[MSSUE]**

Enable or disable the selection of mass unit of full scale set.

(POS. 2.20) Volume to Mass Specific Gravity Coefficient *[Sg= Kg/dm³ x.xxxx]* *AL2* **[VMSGC]**

Setting specific gravity coefficient. This function is active with POS. 2.19 see page 35, enabled.

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MENU 3 - SCALE

(POS. 3.1-3) Flow Rate Full Scale 1-2 *[FS1-2= l/s xxxx.x]* AL2 [FRFS1-FRFS2]

The FS2 (full scale flow rate 2) is active with POS. 6.6 see page 36, enabled.
The full scale is used to indicate the maximum meter's flow rate. The full scale should be chosen carefully as its parameters are used for several other parameters.There are three fields to fill in order to set this parameter, from left to right: 1) measure unit, 2) time unit of measure and 3) numeric value. The selection is made by positioning the cursor on the field to modify. To change the unit of measure type (metric, Imperial units, mass or volume) see POS. 2.3 see page 35 and POS. 2.19 see page 35 and POS. 2.20 see page 35. The value of full scale 1 and 2 depends on nominal diameter POS. 1.4 see page 35. The following tables show the units of measure available and the conversion factor by comparison with 1dm3 and 1kg. The transmitter accepts any kind of combination of units of measure satisfying both the following conditions:
Numeric field values 99999
1/25 fsmax ≤ numeric field value ≤ fsmax.
Where fsmax is the maximum full scale value corresponding to the sensor, equal to a 10m/s liquid speed. The measure units are shown as appear on the display. The imperial units units are diversified by using capital and small characters.

METRIC	
cm^3	Cubic centimeter
ml	Milliliter
l	Liter
dm^3	Cubic decimeter
dal	Decalitre
hl	Hectolitre
m^3	Cubic meter
ML	Mega Liter

NOT METRIC	
in^3	Cubic inch
Gal	American gallon
ft^3	Cubic foot
bbl	Standard barrel
BBL	Oil barrel
hf^3	Hecto cubic feet
KGL	American Kilo gallon
kf^3	Kilo cubic feet
ttG	Ten thousand gallons
IGL	Imperial gallon
IKG	Imperial Kilo gallon
Aft	Acre foot
MGL	Mega gallon
IMG	Imperial mega gallon

MASS UNIT NOT METRIC	
Oz	Ounce
Lb	Pound
Ton	Short tons

MASS UNIT METRIC	
g	Gram
kg	Kilogram
t	Ton

When a measure mass unit is set, the specific gravity function is automatically enabled by the system. Please, note that the mass measure is heavily affected by the temperature. With certain liquids this may cause significant measurement errors. The following measure of time units can be selected: s = second, m = minute, h = hour, d = day .

NOTES FOR USING THE MCP INTERFACE

The command FRFS1 =? and command FRS2 = ?, edited by MCP software, return a list of only the unit compatible with the nominal diameter set.

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(POS. 3.2) BaTching QuanTitY	*[B.qty=xxxxx]*	*AL2*	[BTQTY]

This function is enabled when output1 is set to “BATCHING”.
It allows to set the unit of measure and the batching quantity.

(POS. 3.4-3.6) OutPut 1-2 Pulse Value	*[Pls1-2= dm³ x.xxxxx]*	*AL2*	[OP1PV-OP2PV]

The functions on POS. 7.1 see page 37 and POS. 7.2 see page 37, if enabled and set on pulse value, allow to set a defined amount of volume to get one pulse.
To set pulse value set the 2 fields, from left to right: 1)unit of measure, 2) numeric value.
The selection is performed by positioning the cursor in the field that has to be modified.
To change the unit type (metric, imperial) see menu 2 units.
The value of Pls1-2 depends on nominal diameter (max. flow rate) units.
The available units are described in the function POS. 1.4 see page 35.

(POS. 3.5-3.8) OutPut 1-2 Pulse Time	*[Tpls1-2= ms x.xxxxx]*	*AL2*	[OP1PT OP2PT]

When the pulse value is defined, also the duration of the pulse shall be set. It’s expressed in milliseconds and the range is from 0.4 to 1250 ms. Be carefull to set a right value of pulse duration, according to the receiver. It shall be compatible with the external device which receives the pulses.
ATTENTION: If the pulse is too long receiver’s coils may burn out or if the pulse is too short, the counter may not be able to recognize the pulses.

(POS. 3.8-3.9) OUtput 1-2 Full scale Frequency	*[Frq1-2= x.xxxxx]*	*AL2*	[OU1FF-OU2FF]

Frq1 and Frq2 are activated with POS. 7.1 see page 37 and POS. 7.2 see page 37 enabled and set to the value freq+/-/+-. Setting duration of the pulse generated on channel 1 and 2.

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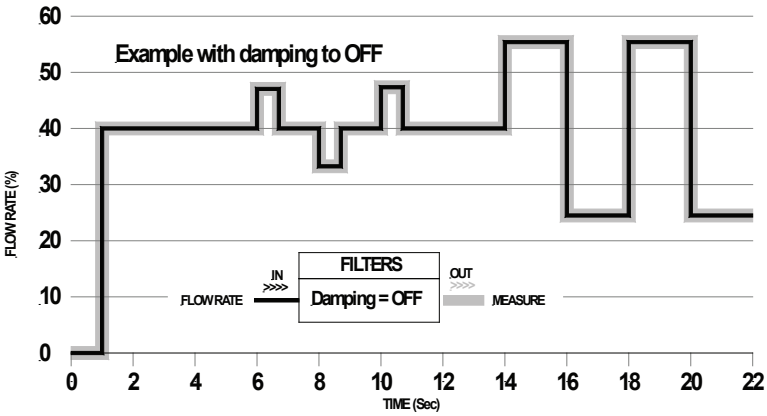
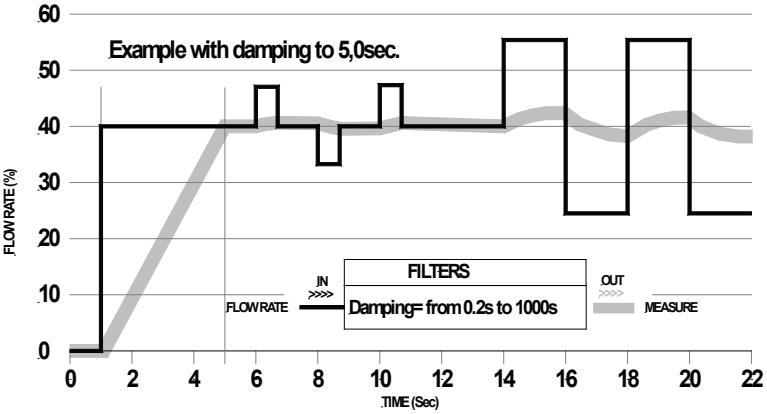
MENU 4 - MEASURE

(POS. 4.1) Measure Filter DaMPing *[Damping=OFF/SMART/(TIME)]* *AL3* **[MFDMP]**

This section of manual is extremely important because the correct setting of the filters allows to obtain a proper response of the device to the measured flow rate and the specific requirements of use; as a general rule, consider that, starting from Damping = OFF (no filter applied to the measure), successive values, introduce increasing damping. The following diagrams show the device's response to changes in flow rate from 0 to 100%, using the different settings of the damping function.
The SMART is an adaptive filter that adapts automatically to most of the processes (recommended value), making the response of the meter very ready to fast changes of flow and at the same time extremely precise and stable for slow variations. It may be convenient to use a constant damping filter time, where there is a pulsating flow (for example generated by peristaltic pumps). With longer times you get a mean value stable, while with short times the measure will closely follow the flow pulses, but consequently more unstable. NOTE: If the rechargeable battery is active, the damping could be set only in "SMART".



Damping function (OFF). the meter follows the trend of fast changes in flow.



Damping mode based on time (from 0.2s to 1000s) The measure is averaged over a number of samples determined by the value assigned to the dampening function. When the damping parameter is expressed in seconds, the filter works damping the measurement noise and sudden change of flow rate. Increasing the parameter of damping increases the stability of the measurement.

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(POS. 4.2) Measure Filter CUt-off Threshold	*[Cut-off=% xxx]*	AL3	[MFCUT]

Setting the low flow cut-off threshold. This function is useful to avoid that when the flow is close to zero, tiny movements of liquid (due for example to vibrations of the pipe) can cause an increasing of the totalizers. The allowed range for this function is 0-25% of full scale set. For most applications a value between 0.5 and 1% is recommended.

(POS. 4.3) Auto CAlibration Verify Enable	*[Cal.verify=ON]*	AL3	[ACAVE]

This function enables an automatic verification of board's coefficients. As the transmitter performs continuously a large number of tests, we recommend to use this function only in presence of wide range of temperature. Instead it is NOT recommended to use it when the device is used in metering applications (batch).

(POS. 4.4) Auto RaNGe Enable	*[Autorange=ON/OFF]*	AL3	[ARNGE]

Enables the automatic change of scale. The meter may have two different working ranges in order to suit to the variable process conditions. In order to get the best results out of this function it is important that the range N.2 (Fs2), if enabled, is bigger than the range N.1 (Fs1). When the flow rate increases and reaches the 100% of the full scale 1, then the meter automatically switches to scale 2. When the flow rate decreases again reaching a value on scale 2 equal to the 90% of full scale N.1, then the active scale is 1 again. Allowed values for this parameter: ON/OFF.
Notice: when the autorange is enabled, It's not allowed to use the manual range change (POS. 6.6 see page 36). This function does NOT increase the accuracy of the measure; it aims to increase the resolution of 4/20 mA when the meter work at very low flow rates (typical case the flow rate of water distribution with daytime flow much higher than the night flow). N.B: this function is disabled if the batching function is active

(POS. 4.5) High Immunity INPuts	*[H.imm. inp.]*	AL4	[HIINP]

This function (INPut High Immunity filter) introduces a hardware filter to be used ONLY IN CASE OF ABSOLUTE NECESSITY, when the measure is absolutely unstable or it is NOT possible to make the measure, and every possible attempt to reduce or eliminate the noise do not give a positive result, with particular attention of device ground connection. When this function is activated (HIINP = ON) the measure will be influenced by an unavoidable error estimated around 1%.

MENU 4 - MEASURE: ONLY MCP FUNCTIONS

Measure Filter Cut-off Threshold 2	*[MCP ONLY]*	AL3	[MFCT2]

Setting the low flow cut-off threshold, it is similar to the function in 4.2. The value of this function is NOT visible on display but only with MCP command.

DYNamic Sample Analysis	*[MCP ONLY]*	AL4	[DYNSA]

DYNamic Sample Time	*[MCP ONLY]*	AL4	[DYNST]

Reserved to the service

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MENU 5 - ALARMS

(POS. 5.1) Flow Rate Alarm maX Positive	*[Max+=technical unit XXX]*	AL3	[FRAXP]

Maximum value alarm set for positive flow rate set (expressed in technical units). When the flow rate value exceeds such a threshold, then an alarm message is generated. Setting this parameter to zero disables the alarm generation.

(POS. 5.2) Flow Rate Alarm maX Negative	*[Max-=technical unit XXX]*	AL3	[FRAXN]

Maximum value alarm set for negative flow rate set (expressed in technical units). When the flow rate value exceeds such a threshold, then an alarm message is generated. Setting this parameter to zero disables the alarm generation.

(POS. 5.3) Flow Rate Alarm miN Positive	*[Min+=technical unit XXX]*	AL3	[FRANP]

Minimum value alarm set for positive flow rate set (expressed in technical units). When the flow rate value falls below such a threshold, then an alarm message is generated. Setting this parameter to zero disables the alarm generation.

(POS. 5.4) Flow Rate Alarm miN Negative	*[Min-=technical unit XXX]*	AL3	[FRANN]

Minimum value alarm set for negative flow rate set (expressed in technical units). When the flow rate value falls below such a threshold, then an alarm message is generated. Setting this parameter to zero disables the alarm generation.

(POS. 5.5) Alarm Thresholds HYSteresis	*[Hysteresis=% XX]*	AL3	[ATHYS]

Hysteresis threshold set for the minimum and maximum flow rate alarms. The value of this parameter is expressed as percentage of the full scale value and may be set from 0 to 25%.

(POS. 5.6) Output Current Alarm Condition Value	*[mA V.alarm = % XXX]*	AL3	[OCACV]

The output current signal can be specified by the user in case of failure of either, empty pipe, coils interrupted, or ADC error. The signal current is set as a percentage (0 to 125%) of the 0/4-20mA current. 125% corresponds to 24mA and does not depend on the selected range (0-20/4-20mA).
The NAMUR NE43 recommendation asks for a alarms signalling value for the current output lower than 3.6mA (<18%) or bigger than 21mA (>105%). It would then be preferable to set the value of this function at the 10%, so that the current value in case of the a.m. cases would be 2 mA, allowing the following diagnostics:

- current < 2mA - 5%: line interrupted, power supply failure or faulty transmitter;
- 2mA -5% < current < 2mA + 5%: hardware alarm;
- 4mA < current < 20mA: normal working range;
- 20mA < current < 22mA: out of range, measure above 100% f.s.

(POS. 5.7) Output Frequency Alarm Condition Value	*[Hz V.alarm=%XXX]*	AL3	[OFACV]

This function is active with POS. 7.1 see page 37 and POS. 7.2 see page 37 enable to (FREQ.+, FREQ.-, FREQ.±) To set the frequency value assigned to the on/off output in one or more of the following alarm cases: Empty pipe; Coils interrupted ; ADC error. Allowable range is from 0 to 125% of the frequency full scale value. Although there are no specific rules regulating cases such as these, it would be convenient to use the failure information as follows:
0% Hz < frequency <100% f.s.: normal working range;
100% f.s. < frequency < 210% f.s.: overflow, measure above the 100% of the f.s.;
115% f.s. < frequency < 125% f.s.: hardware alarm condition.

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MENU 6 - INPUTS

WARNING!
This menu is not enabled when the batching function is active.

(POS. 6.1-2) Volume Totalizer Total /Partial Positive reset Enable	*[T/P+/RESET=ON/OFF]*	AL3	[VTTPE] [VTPPE]

When one of this function is enabled, the related positive totalizer may be reset through the on/off input.

(POS. 6.3-4) Volume Totalizer Total /Partial Negative reset Enable	*[T/P-/RESET=ON/OFF]*	AL3	[VTTNE] [VTPNE]

When one of this function is enabled, the related negative totalizer may be reset through the on/off input.

(POS. 6.5) Totalizers Count Lock Input Enable	*[COUNT LOCK= ON/OFF]*	AL3	[TCLIE]

Totalizers counting lock command enable. When this function is active, applying a voltage on the on/off input terminals the system stops the totalizers no matter which is the flow rate.

(POS. 6.6) MeaSure Lock Input Enable	*[Meas.lock=ON/OFF]*	AL3	[MSLIE]

When this function is active (ON), applying a voltage on the on input terminals, the measurement is stopped, the meter will display zero flow.

(POS. 6.7) CALibration Input Enable	*[Calibration=ON/OFF]*	AL3	[CALIE]

calibration cycle. ATTENTION: If the voltage pulse is less than 1 sec., the meter performs a calibration cycle to compensate possible thermal drifts. If the voltage pulse is more 1 sec, the meter performs a zero calibration measure. To perform the calibration it is absolutely necessary for the sensor to be full of liquid and that the liquid is perfectly still. Even very small movement of the liquid may affect the result of the calibration, and, consequently, the accuracy of the system.

(POS. 6.8) Scale Range Change Input Enable	*[RANGE CHANGE=ON/OFF]*	AL3	[SRCIE]

Range change external command enable. When this function is enabled, applying a voltage on the on/off input terminals the meter switches to the second measuring range (Fs2).
N.B.: the autorange doesn't allow to use the manual range change see (POS. 4.4 see page 36).

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MENU 7 - OUTPUTS

(POS. 7.1) OUTput 1 Function	*[Out1=XXXXXX]*	AL3	[OUT1F]

Function choice corresponding to digital Output 1. The functions are listed in the table below.

(POS. 7.2) OUTput 2 Function	*[Out2=XXXXXX]*	AL3	[OUT2F]

Function choice corresponding to digital Output 2. The functions are listed in the table below.

FUNCTIONS FOR OUTPUTS 1 AND 2

- **OFF:** DISABLE
- **MAX AL. +:** MAX DIRECT FLOW RATE OUTPUT (ENERGIZED = AL. OFF)
- **MIN AL. +:** MIN DIRECT FLOW RATE OUTPUT (ENERGIZED = AL. OFF)
- **MAX/MIN+/-:** MAX/MIN DIRECT FLOW RATE OUTPUT (ENERGIZED = AL. OFF)
- **MAX AL.-:** MAX INVERSE FLOW RATE OUTPUT (ENERGIZED = AL. OFF)
- **MIN AL.-:** MIN INVERSE FLOW RATE OUTPUT (ENERGIZED = AL. OFF)
- **MAX/MIN-:** MAX/MIN INVERSE FLOW RATE OUTPUT (ENERGIZED = AL. OFF)
- **P.EMPTY:** EMPTY PIPE ALARM OUTPUT (ENERGIZED = AL. OFF)
- **HARDWARE AL.:** SUM OF ALL ALARMS ”energized interrupted ” AND ”error input signal ”
- **OVERFLOW:** OUT OF RANGE ALARM OUTPUT (ENERGIZED = FLOWRATE OK)
- **ALL ALARMS:** SUM OF ALL ALARMS POSSIBLE
- **EXT. COMM:** OUTPUT MAY TAKE A STATE DEPENDENT ON AN EXTERNAL CONTROL REMOTELY VIA MCP
- **FLOW RATE SIGN.:** FLOW DIRECTION (ENERGIZED WHEN FLOW IS NEGATIVE)
- **SCALE:** INDICATION SCALE
- **FREQ.+:** FREQUENCY POSITIVE FLOWRATE
- **FREQ.-:** FREQUENCY NEGATIVE FLOWRATE
- **FREQ.+/-:** FREQUENCY POSITIVE/NEGATIVE FLOWRATE
- **PULSES.+:** PULSE POSITIVE FLOW RATE
- **PULSES.-:** PULSE NEGATIVE FLOW RATE
- **PULSES+/-:** PULSE NEGATIVE/POSITIVE FLOW RATE
- **BATCHING:** IT’S POSSIBLE TO SET A QUANTITY OF VOLUME THAT HAVE TO BE DELIVERED DURING AN ACTUATOR (VALVE) OPENING-CLOSING CYCLE

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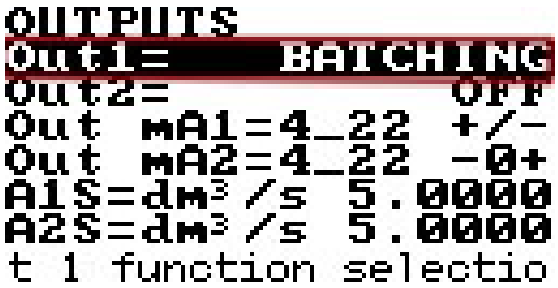
BATCHING

Through this function, It's possible to set the volume quantity that must be delivered, managing the opening and the closing of the valve.

To activate it, follow these instructions:



1. Enter to the main menu;
2. Select Output menu;
3. Set the Out1 function on "BATCHING"

With batching activated, the display visualizes one main page:

The batching parameters settings can be customized according to what the device use and application is thought to.

FUNCTION	FUNCTION N° POS.	SETTING
Cut-off	"4.2" page 36	It must be set so that the flow is stably zero when the valve is closed
Damping	"4.1" page 36	It must be set on the minimum value allowed. If T batching ≤ 1s, filters must be disabled

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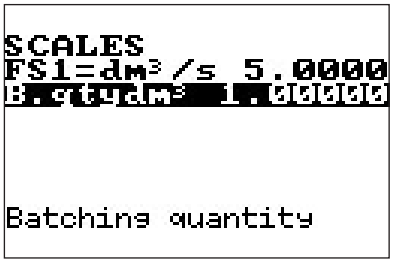
BATCHING QUANTITY SETTINGS:

By display	Enter to the 3. Scale menu; Set the B.qty (batching quantity) value	
By MCP command	"BTQTY?" Through this command it can be set both the unit measure or the quantity (see MCP manual)	VALUES: 0:'ml'|1:'cm3'|2:'l'|3:'dm3'|4:'dal'|5:'hl'|6:'m3'|7:'Ml',0.00001 <> 99999.9
By ModBus interface	Using the ModBus command 16 (see MODbus manual)	

BATCHING OPERATIONS:

ACTION:	OPERATION:	NOTES:
Start/stop by display	Press "UP" key on the keyboard	When the batching process is manually stopped, the OUT1 function is disabled and the batching cycle is interrupted with the valve closing. Every time the batching cycle starts, the set quantity counter and the alarms are reset.
Start/stop by MCP	Type MCP command "BTACT"	
Start/stop by input	External signal connected to digital input 1. N.B: The signal must be a pulse and its duration must be greater than the time of the measurement cycle. See "DIGITAL INPUT ON/OFF OPERATION" page 21	
Start/stop by ModBus	Send the MODbus command 5 (see MODbus manual)	
Visualize batching status by display	Batching in progress symbol on the display 	
Visualize batching status by MCP	Type the MCP command "BTACT?" If = 0 the actuator is closed If = 1 the actuator is open (batching in progress)	

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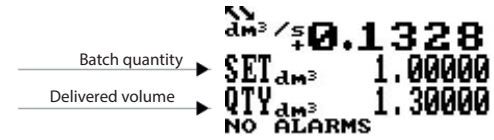
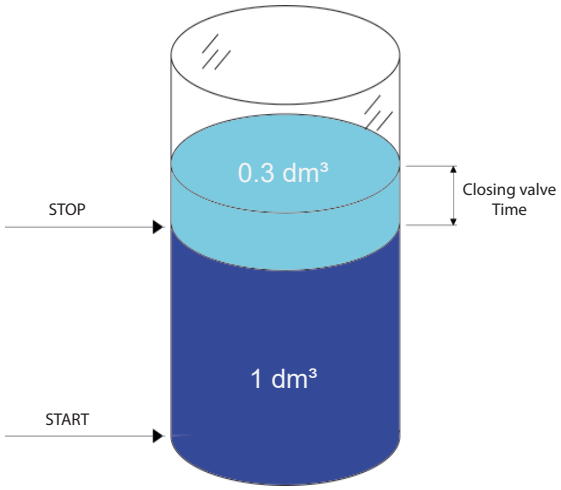
The batching process automatically stops the valve when the batching quantity reaches the set value. If the delivered volume doesn't match to the required one, it's necessary to notice empirically the value to set. In this way It is possible to compensate any "delays" in the process after the stop signal.

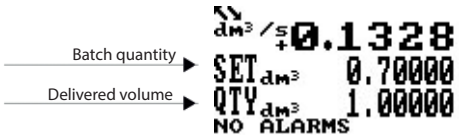
EXAMPLE WITH DELIVERED VOLUME = 1 dm³

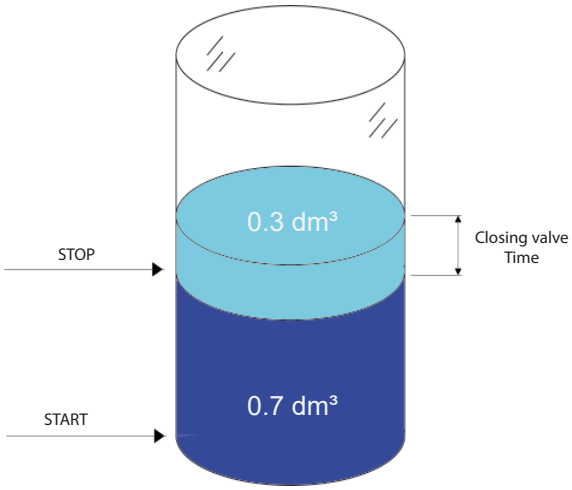
BATCH VALUE NOT ADJUSTED





VALUE AJDUSTED TO COMPENSATE THE BATCH OVER VALUE (0,3 dm³)





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BATCHING ALARMS

NAME	DESCRIPTION	NOTES
Batching time-out	It activates after 4 seconds from the start command, when any flow is detected	Active alarms automatically close the valve (actuator) Both alarms can be visualized remotely, setting the usc2 function on "HARD W. AL" or "ALL ALARMS"
Overflow	It activates when the batching quantity is more than 20% of the set one.	

Visualize alarms via display:
The presence of a dosage alarm is highlighted by the message: "ALARM"

Visualize alarms via MCP:
Batching page: The presence of a batching alarm is highlighted by the message: "ALARM"
Alarms page: The presence of a batching alarm is highlighted by the message: "BATCHING ERR."

ATTENTION!! DISABLED FUNCTIONS WHEN BATCHING IS ACTIVATED

"1.19" page 35
"4.3" page 36
"4.4" page 36
"9.7" page 37
"9.8" page 37
"9.9" page 37
"12.3" page 38

(POS. 7.3-4) Analog Output 1/2 ConFiguration *[Out mA1/2=X_XX XXX]* *AL3* [AO1CF] [AO2CF]

This function sets the current output 1 and 2. This function is optional and will not appear unless the option has been requested. There are three fields to modify this function:
Scale zero: 4 or 0mA
Full scale: 20 or 22mA
Field: + = positive, - = negative, blank = both, -0+ = central zero scale
The values corresponding to the scale points are shown in the following chart:

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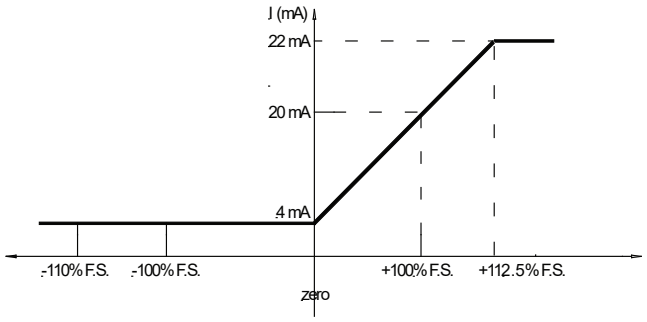
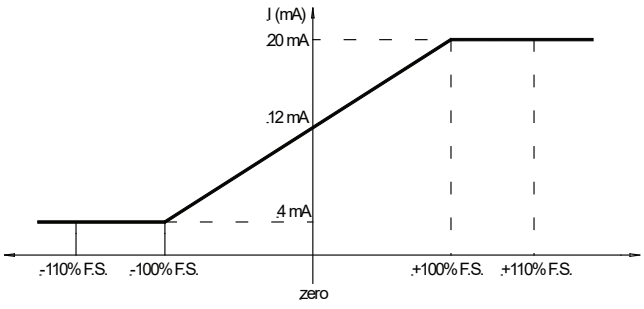
CURRENT VALUES IN mA ASSOCIATE TO THE % FULL SCALE VALUE					
POSSIBLE FIELD	REVERSE FLOW VALUE		ZERO	DIRECT FLOW VALUE	
	≤-210%	-100%	0%	+100%	≥+210%
Out.mA = 0 ÷ 20 +	0	0	0	20	20
Out.mA = 0 ÷ 22 +	0	0	0	20	22
Out.mA = 4 ÷ 20 +	4	4	4	20	20
*Out.mA = 4 ÷ 22 +	4	4	4	20	21.6
Out.mA = 0 ÷ 20 -	20	20	0	0	0
Out.mA = 0 ÷ 22 -	22	20	0	0	0
Out.mA = 4 ÷ 20 -	20	20	4	4	4
Out.mA = 4 ÷ 22 -	21.6	20	4	4	4
Out.mA = 0 ÷ 20	20	20	0	20	20
Out.mA = 0 ÷ 22	22	20	0	20	22
Out.mA = 4 ÷ 20	20	20	4	20	20
Out.mA = 4 ÷ 22	21.6	20	4	20	21.6
Out.mA = 0 ÷ 20 –0+	0	0	10	20	20
Out.mA = 0 ÷ 22 –0+	0	1	11	21	22
**Out.mA = 4 ÷ 20 –0+	4	4	12	20	20
Out.mA = 4 ÷ 22 –0+	2	4	12	20	22

In hardware alarm conditions “HARDW AL.” (interrupted coils, empty pipe, measure error) the current value is programmed by the function “mA v.fault” (pos. 5.6) and it is expressed as percentage of a fixed current range, where: 0% = 0mA and 210% = 22mA.

* Example 1: out 4-22 +



** Example 2: out 4-20 –0+



(POS. 7.5) Analog Output 1 Full Scale *[A1S= dm/s x.xxxx]* AL3 [AO1FS]

It allows to set the full scale value for analog output 1 independently from the main scale of the device.

(POS. 7.6) Analog Output 2 Full Scale *[A2S= dm/s x.xxxx]* AL3 [AO2FS]

It allows to set the full scale value for analog output 2 independently from the main scale of the device.

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MENU 8 - COMMUNICATION

(POS. 8.1) HART Preamble	*[HART pr.=XXXXXX]*	AL3	[HARTP]

Number of preamble (Hart function)

(POS. 8.2) HaRT Output Control	*[HART O.C=ON/OFF]*	AL3	[HRTOC]

Hart bus output control 4-20mA.

(POS. 8.3) DeVice ADDress	*[Dev. Addr=XXXXXX]*	AL3	[DVADD]

Device communication address number.

(POS. 8.4) MoDBus SPeed	*[Speed=XXXXXX]*	AL3	[MDBSP]

Modbus link speed.

(POS. 8.5) MoDBus PArity	*[Parity=XXXXXX]*	*AL3*	[MDBPA]

Modbus link parity.

(POS. 8.6) MoDBus DeLay	*[Delay=XXXXXX]*	AL3	[MDBDL]

Modbus replay delay.

(POS. 8.7) MoDBus Chars Timeout	*[C. timeout=X]*	AL3	[MDBCT]

Maximun delay between chars (frames).

(POS. 8.8) MeTerbus Identifier NumbeR	*[MBUS ID=220483]*	*AL3*	[MTINR]

MeterBus Identifier Number (Secondary.Address)

(POS. 8.9) MeTerbus Device TYpe	*[MBUS Dev.T=7]*	*AL3*	[MTDTY]

MeterBus Device Type (Media)

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MENU 9 - DISPLAY

(POS. 9.1) Layout LANGuage	*[Language= ITA/EN]*	AL1	[LLANG]

Choice of the language. There are 8 languages available: **GB** = English, **IT** = Italian, **TR** = Turkish, **PL** = Polish, **DE** = German, **FR** = French, **PT** = Portuguese, **ES** = Spanish.

(POS. 9.2) Display CoNTRast	*[Contrast= x]*	AL1	[DCNTR]

Display contrast set. The contrast can change according to the room temperature. The allowed range is from 0 to 9.

(POS. 9.3) KeyBoard TiMeout Time	*[Disp. time=s xxx]*	AL1	[KBTMT]

This function set display/keyboard inactivity. The set values are from 020 to 255 second.

(POS. 9.4) DISplay Refresh Frequency	*[D.rate=Hz xx]*	AL1	[DISRF]

Frequency of the display data update. This parameter effects only the display layout and not the response time of the meter itself. The possible choices are: 1/2/5/10 Hz.

(POS. 9.5) DISplay Function Number	*[Disp.fn= x]*	AL2	[DISFN]

This function sets the display of the page making it visible when you start the display. For each display page is associated with a number that corresponds to the position.

(POS. 9.6) Display function LOcK Enable	*[Disp.lock= x]*	AL2	[DLOKE]

This function locks the scrolling of the display pages selected by the setting. POS. 9.5 see page 37 function.

(POS. 9.7) Partial TOTalizers Enable	*[Part. tot= ON]*	AL2	[PTOTE]

This function enables the display of partial totalizer in visualization pages

(POS. 9.8) NEGative value Totalizers Enable	*[Neg. tot= ON]*	AL2	[NEGTE]

This function enables the display of negative totalizer in visualization pages

(POS. 9.9) Net Value ToTalizers Enable	*[Net. tot= ON]*	AL2	[NVTTE]

This function enables the display of net totalizer in visualization pages

(POS. 9.10) Date And Time Display Enable	*[Disp.Date= ON]*	AL2	[DATDE]

This function enables the display of date and time in visualization pages

(POS. 9.11) Quick STart Menu Enable	*[Quick start= ON]*	AL2	[QSTME]

This function enables the quick start menu.

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MENU 10 - DATA LOGGER

(POS. 10.1) Data LOGger Enable	*[D.logger en= /OFF]*	AL3	[DLOGE]

This function enables data logger.

The following functions are activated by [D.loger en= ON]

(POS. 10.2) Data Logger Units of Measure Enable	*[Meas. units= ON]*	AL3	[DLUME]

Measure unit recording enable

(POS. 10.3) Data Logger Field Separator Character	*[Field separ.= ;]*	AL3	[DLFSC]

This function will set the separator character between data logger data.

(POS. 10.4) Data Logger Decimal Separator Character	*[Decim.separ.= .]*	AL3	[DLDSC]

This function will set the separator character between data logger number value.

(POS. 10.5) Data LoGger Sample Interval	*[Interv.= xx:xx:xx]*	AL3	[DLGSI]

Sampling interval. This function set the log frequency. [Interv.= Hours : Minutes: Seconds]

(POS. 10.6) Data logger Totalizer Total Positive Enable	*[Log T+= ON]*	AL3	[DTTPE]

Enable logging of total direct totalizer.

(POS. 10.7) Data logger Totalizer Partial Positive Enable	*[Log P+= ON]*	AL3	[DTPPE]

Enable logging of partial direct totalizer.

(POS. 10.8) Data logger Totalizer Total Negative Enable	*[Log T-= ON]*	AL3	[DTTNE]

Enable logging of total reverse totalizer

(POS. 10.9) Data logger Totalizer Partial Negative Enable	*[Log P-= ON]*	AL3	[DTPNE]

Enable logging of partial reverse totalizer

(POS. 10.10) Data Logger totalizer Total Net Enable	*[Log TN= ON]*	AL3	[DLTNE]

Enable logging of total net totalizer

(POS. 10.11) Data Logger totalizer Partial Net Enable	*[Log PN= ON]*	AL3	[DLPNE]

Enable logging of partial net totalizer

(POS. 10.12) Data logger Flow rate in Technical Units Enable	*[Log Q(UM)= ON]*	AL3	[DFTUE]

Enable logging of flow rate in measure unit

(POS. 10.13) Data logger Flow rate in PerCentage Enable	*[Log Q(%)= ON]*	AL3	[DFPCE]

Enable recording of the flow rate as a percentage of full scale value set.

(POS. 10.14) Data logger ALarm Events Enable	*[Log AL.EV= ON]*	AL3	[DALEE]

Enable logging of alarm events

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(POS. 10.15) Data logger Sensor Test Results Enable	*[Log STR= ON]*	AL6	[DSTRE]

Enable logging of sensor test results

(POS. 10.16) Data logger Board TemperatureS Enable	*[Log BTS= ON]*	AL6	[DBTSE]

Enable logging of board temperature

(POS. 10.17) Data logger Internal Board Voltages	*[Log IBV= ON]*	AL6	[DIBVE]

Enable logging of internal board voltage

(POS. 10.18) Data logger Electrodes DC Voltages Enable	*[Log EDC= ON]*	AL6	[DEDVE]

Enable logging of electrodes DC voltage

(POS. 10.19) Data logger Electrodes AC voltages Enable	*[Log AEC= ON]*	AL6	[DEAVE]

Enable logging of electrodes AC voltage

(POS. 10.20) Data logger Electrodes Source Impedance Enable	*[Log EIZ= ON]*	AL6	[DESIE]

Enable logging of electrodes impedance

(POS. 10.21) Data logger Sensor Coils Values Enable	*[Log SCV= ON]*	AL6	[DSCVE]

Enable logging of sensor coils value

MENU 10 - DATA LOGGER: ONLY MCP FUNCTIONS

LoG All Information Enable	*[MCP ONLY]*	AL6	[LGAIE]

Log all events information. This function save in the event file all MCP commands.

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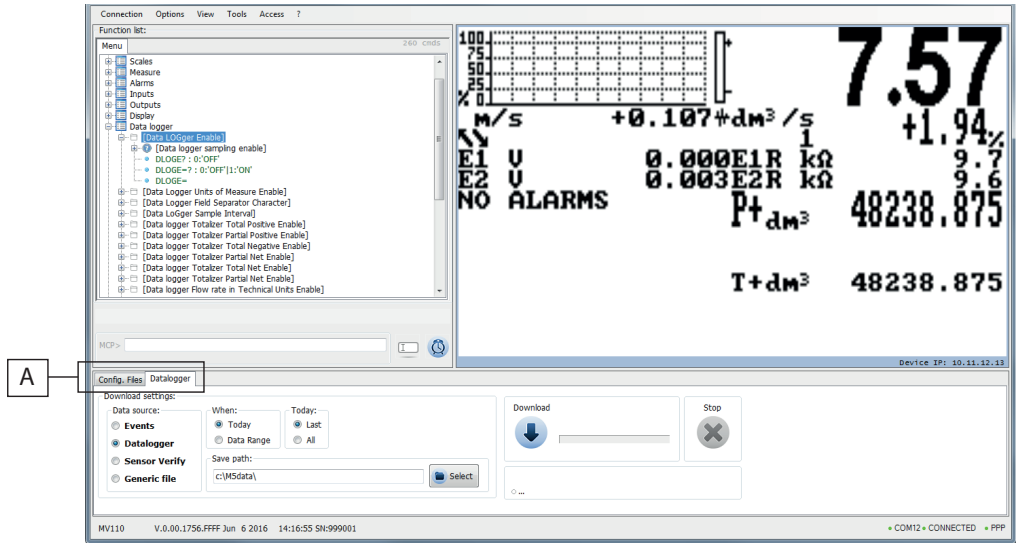
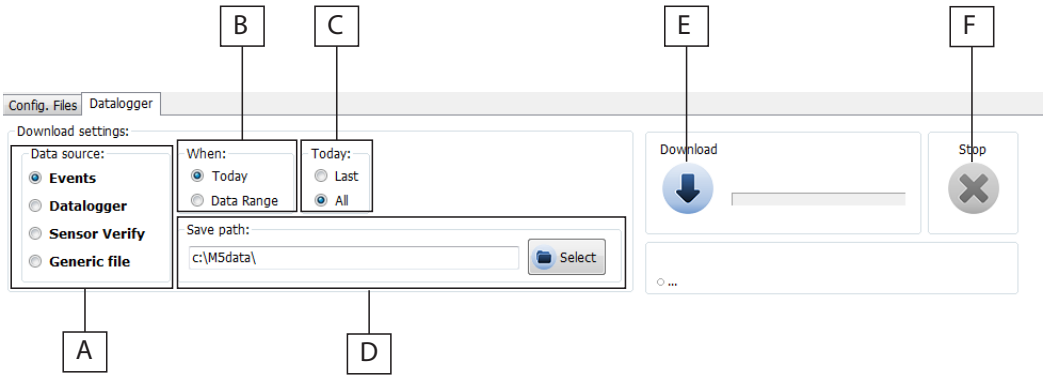
LOGGED DATA EVALUATION (ONLY MCP)

Data are stored on micro SD card; the organization is based on “tree-structure”: the system create a daily folder where it save events and data logger . The data can be downloaded by MCP interface.

MCP INTERFACE



Click tab-control data logger to view files.
The sampling data backup depends on the value set by the POS function 10.4 page 25.



A=Data source
Events: Save the file system events (Example F-RAM hardware data [WORKING AREA] [SUCCESSFULLY LOADED])
Data logger: Save files of the enabled data logger function.
Sensor Verify
Generic file: Save a specific file in the SD card

B=When
Today; It indicates the download file for the current day
Data range; this option allows you to select the date range for download.

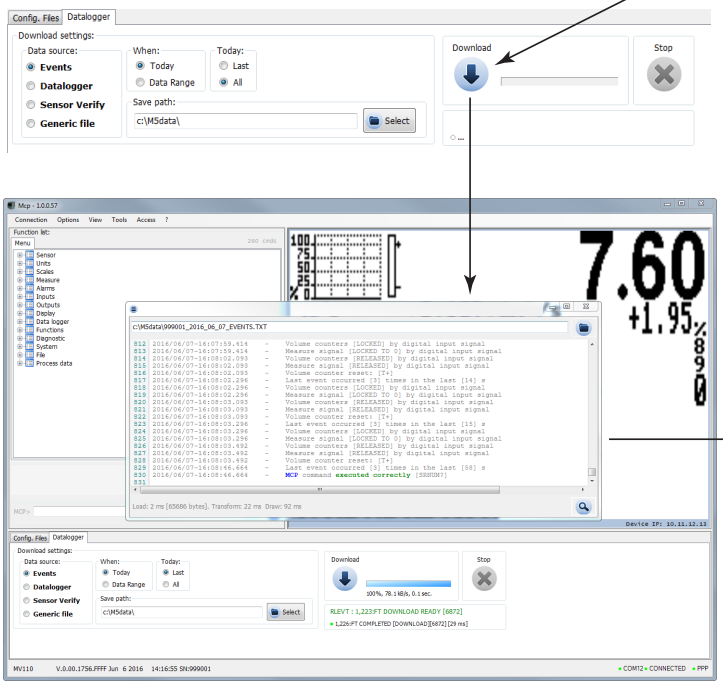
C=Today
Last; this option allows to download the latest files, recordered after the last download
All; this option allows the download of all the current day of the file

D=Save path:
This option allows you to save files to the folder on your PC

E=Download:
Button to start the download process

F=Stop:
Button to stop the download process

Example: Download Events



To download all the events of the current day in a specific folder, set the below parameters as follows:
Data source: Events
When: Today
Today: All
Save path: C: / .....
The parameters are set then click the Download button.

Once the download is completed, a window containing the list of today's events appears. The file is saved in the specified folder in .txt format .

Example: Download Data Logger

Note: it is recommended the date synchronization between transmitter and PC to perform correctly the events and logger reading operations.

To download all the data of the current day in a specific folder, set the below parameters as follows:
Data source: DATALOGGER
When: Today
Today: All
Save path: C: / .....
The parameters are set then click the Download button.

View downloaded files setting download data logger.
Note: The fields are in a fixed position, regardless if the above fields are active or not. The disabled fields are empty (delimited by the separator but without data).

N°Record. View progressively the number of registered records.	N.RECORD n°
Date. The recording date viewing for each record.	DATE dd/mm/yy
Hours. Time recording viewing for each record.	HOURS 00:00:00
Total positive totalizer value. Form Fields when the send flag is active on the totalizer T+.	U.M. dm3 T+ 0
Partial positive totalizer value. Form Fields when the send flag is active on the totalizer P+.	U.M. dm3 P+ 0
Total negative totalizer value. Form Fields when the send flag is active on the totalizer T-.	U.M. dm3 T- 0
Partial negative totalizer value. Form Fields when the send flag is active on the totalizer P-.	U.M. dm3 P- 0
Total net totalizer value. Form Fields when the send flag is active on the totalizer TN.	U.M. dm3 TN 0
Partial net totalizer value. Form Fields when the send flag is active on the totalizer PN	U.M. dm3 PN 0
Flow rate. Form Fields present when the send flag is on the flow in units of measurement.	U.M. dm3/s FLOWRATE 0
Flow rate %. Form fields present when the flag of alarm recording is active (only N ° of present total alarms)	U.M. % FLOWRATE % 0
N ° active alarms. Form fields present when the flag of alarm recording is active (only N ° of present total alarms)	U.M. AL N.ACTIVE ALLARM 0
Loss of current measured during insulation test. Available value when recording the sensor test data is active.	U.M. mA CPTI 0
Time rise A. Available value when recording the sensor test data is active.	U.M. ms TRISE A 0
Time rise B. Available value when recording the sensor test data is active.	U.M. ms TRISE B 0
Sensor test error code. Available value when recording the sensor test data is active.	U.M. ERR CETS 0

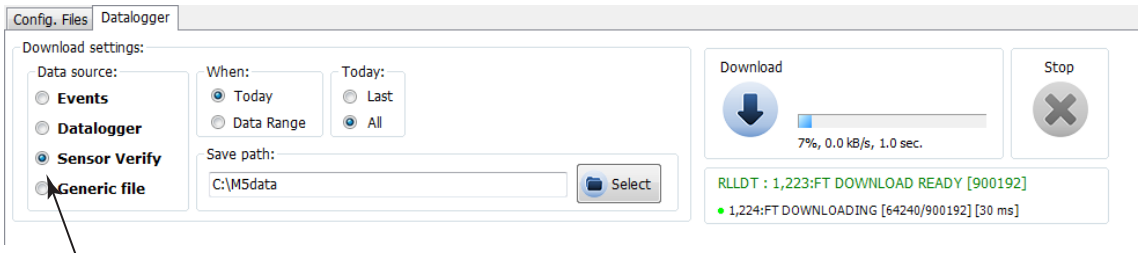
Visualization of downloaded file. Access Level 2 (diagnostic level) is required in order to download this type of file.

	AD	AE	AF	AG	AH	AI	AJ	AK	AL	AM	AN	AO	AP	AQ	AR	AS	AT	AU	AV	AW	AX	AY	AZ	BA	BB	BC	BD	BE	BF	BG	BH	BI	BJ	BK	BL	BM
	U.M.	ET1 V	U.M.	E2 V	U.M.	VD (E1-E2)	U.M.	VC (E1+E2)/2	U.M.	CM LF NOISE	U.M.	DIF LF NOISE	U.M.	ADC LF NOISE	U.M.	ADC HF NOISE	U.M.	ET1 R	U.M.	E2 R	U.M.	EXCITATION CUR	U.M.	R.COILS	U.M.	T.COILS	U.M.	T1	U.M.	T2	U.M.	T. CPU	U.M.	V CPU	U.M.	AVCC+
Voltage measured on electrode E1. Form fields when is active the recording of data on the input voltage (diagnostic value).	V	0																																		
Voltage measured on electrode E2. Form fields when is active the recording of data on the input voltage (diagnostic value).			V	-0.023																																
Differential voltage between the two electrodes. Form fields when is active the recording of data on the input voltage (diagnostic value)					V	0																														
Common mode voltage in the electrodes. Form fields when is active the recording of data on the input voltage (diagnostic value).							V	0																												
Noise at low frequency measured on the electrodes. Form fields when is active the recording of data on the input signal noise levels (diagnostic value).									V	0																										
Differential low frequency noise measured on the electrodes. Form fields when is active the recording of data on the input signal noise levels (diagnostic values).											V	0																								
Low-frequency noise measured input ADC. Form fields when is active the recording of data on the input signal noise levels (diagnostic values).													mV	0																						
High frequency noise measured input ADC. Form fields when is active the recording of data on the input signal noise levels (diagnostic values).															mV	0																				
Measured equivalent resistance on the electrode 1. Form fields when is active the recording of data on the electrode resistance measurements (diagnostic values).																	kohm	0																		
Measured equivalent resistance on the electrode 2. Form fields when is active the recording of data on the electrode resistance measurements (diagnostic values).																			kohm	0																
Coils excitation current. Form fields when is active the recording of data related to the sensor excitation circuit measures (diagnostic value)																					mA	0														
Measured resistance of the excitation circuit (coil + cable). Form fields when is active the recording of data relative to the sensor excitation circuit measures (diagnostic values).																							ohm	0												
Temperature measured on the sensor coils (indirect measurement). Form fields when the data transmission flag is active relative to the sensor excitation circuit measures (diagnostic values).																									°C	0										
Temperature T1 (Board Sensor 1: located close to the amplifier input). Form fields when the data transmission flag on board the internal temperature measurement is active (diagnostic values).																											°C	0								
Temperature T2 (Board sensor 2: located close to the power supply module). Form fields when the data transmission flag on board the internal temperature measurement is active (diagnostic values).																													°C	0						
CPU temperature. Form fields when the data on the board's internal power supply voltage measurements flag is ON (diagnostic value).																															°C	0				
Primary power supply of CPU. Form fields when the data on the board's internal power supply voltage measurements flag is ON (diagnostic value).																																	V	0		
Positive supply voltage of analog circuits. Form fields when the data on the board's internal power supply voltage measurements flag is ON (diagnostic values).																																			V	0

Negative supply voltage of the analog circuits. Form fields when the data on the board's internal power supply voltage measurements flag is ON (diagnostic values).	V	0	U.M.	AVCC-	0	BN BO
Voltage measured on the battery B1 (NOT rechargeable battery). Fields when the data on the board's internal power supply voltage measurements flag is ON (diagnostic values).			U.M.	BAT1V	0	BP BQ
Voltage measured on the battery B2 (or rechargeable battery). Form fields when the data on the board's internal power supply voltage measurements flag is ON (diagnostic values).	V	0	U.M.	BAT2V	0	BR BS
% Battery charge. Form fields when the data on the board's internal power supply voltage measurements flag is ON (diagnostic values).	%	0	U.M.	% BATTERY CHARGE	0	BT BU

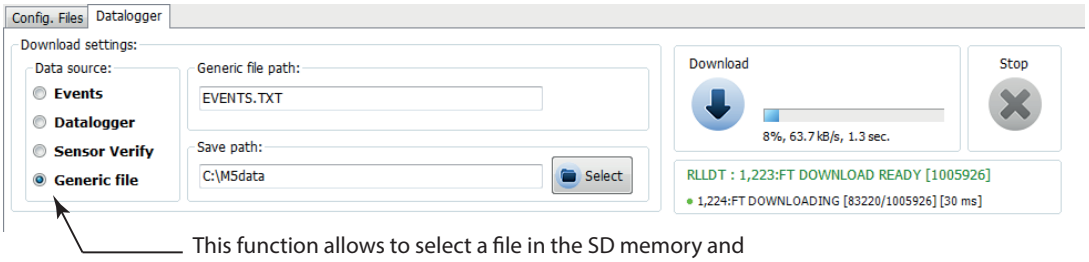
Example: Sensor Verify

The function "Sensor Verify" creates the "STESTLOG.CSV" file.
If enabled (by order code) the transmitter will perform every hour a measure of sensor parameters and record a line on the file "STESTLOG.CSV"; it is even possible a manual verification by the command "sens.verify" on the menu "Diagnostic" or through the MCP command "SVERC".



To download all the sensor measure for the current day in a specific folder, set the below parameters as follows:
Data source: Sensor Verify
When: Today
Today: All
Save path: C: / .....
The parameters are set then click the Download button.

Example: Generic File



This function allows to select a file in the SD memory and download it. In the "Generic file path" specify the file name contained in the SD and indicate "Save path" where to save the file. Set these values to proceed with the download by clicking the "download".

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MENU 11 - FUNCTION

The following functions are activated by first pressing the “ENTER” and then the “ESC” when the screen appears “confirm” to start the function.

(POS. 11.1) Volume Totalizer Total Positive Reset	*[T+ RESET= ON]*	AL3	[VTTPR]

This function allows to reset the total positive totalizer for direct flow rate (+)

(POS. 11.2) Volume Totalizer Partial Positive Reset	*[P+ RESET= ON]*	AL3	[VTPPR]

This function allows to reset the partial positive totalizer for direct flow rate (+)

(POS. 11.3) Volume Totalizer Total Negative Reset	*[T- RESET= ON]*	AL3	[VTTNR]

This function allows to reset the total negative totalizer for direct flow rate (-)

(POS. 11.4) Volume Totalizer Partial Negative Reset	*[P- RESET= ON]*	AL3	[VTPNR]

This function allows to reset partial negative totalizer for direct flow rate (-)

(POS. 11.5) Load Factory Default Sensor Data	*[Load sens.f.def= ON]*	AL3	[LFDSD]

This function resets the parameters of the sensor factory default. To Load the saved files see function (11.7).

(POS. 11.6) Load Factory Default Converter Data	*[Load conv.f.def= ON]*	AL3	[LFDCD]

This function resets the parameters of the transmitter factory default. To Load the saved files see function (11.8).

(POS. 11.7) Save Factory Default Sensor Data	*[Save sens.f.def= ON]*	AL6	[SFDSD]

This function saves the parameters of the sensor factory default.

(POS. 11.8) Save Factory Default Converter Data	*[Save conv.f.def= ON]*	AL6	[SFDCD]

This function loads the data from a transmitter to another.

(POS. 11.9) CALibration Immediate Command	*[Calibration]*	AL5	[CALIC]

Perform manually a board calibration. Press Enter and the message “ EXECUTE?” will be visualized on the display then press long the key Enter to proceed. Press any other key to cancel the operation.
If the sensor table is valid, the calibration is performed also when one of the following parameters have been changed:
SENSOR DIAMETER -> Menu Sensor1
SENSOR MODEL -> Menu Sensor1
Exc. CURRENT -> Menu Sensor1
S. Freq. -> Menu Sensor1
To check the calibration status, active or inactive, type the command MCP Calic? and check as follows:
CALIC = 1 calibration in progress
CALIC = 0 calibration terminated

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MENU 11 - Function: ONLY MCP FUNCTIONS

Sensor ReFerence Data Save	*[MCP ONLY]*	AL4	[SRFDS]

Saving the sensor reference data. “meter data” page 81

MENU 12 - DIAGNOSTIC

(POS. 12.1) AutoTeSt Immediate Command	*[Self Test]*	AL3	[ATSIC]

Meter auto-test function. This function stops the normal functions of the meter and performs a complete test cycle on the measure input circuits and on the excitation generator. To activate this function, after select it, push key Enter, at the question: “CONFIRM EXEC.?” Long Push the same key to start auto-test, or any other key for cancel the operation. At the end of operation the transmitter will revert to one of the initial visualization pages. This function is automatically performed when switching on the device. This function restarts the transmitter.

(POS. 12.2) Test display	*[Test display]*	AL1	NO MCP COMMAND

This function allows to do a physical test of the graphical display. During this operation, 4 sequences are displayed to test the correct functioning of the device.

(POS. 12.3) Sensor VERify Command	*[Sens. verify]*	AL3	[SVERC]

This function performs a manual sensor verification (if BIV is active)

(POS. 12.4) Measure SIMulation ENable	*[Flow sim=ON]*	AL3	[MSIEN]

Flow rate simulation enabling. With this function it is possible to generate an internal signal that simulates the flow rate, allowing the outputs and all the connected devices test.

After enabling it, a ‘▲▼’ appears in the top left of the screen and the flow rate simulation can be:

- set: by pushing the key Enter from one of visualization pages, to set the required % flow rate (Fl.rate=%) and the same key to confirm the value;
- finished: by pushing the key Enter from visualization pages and then by long pushing the same key.

(POS. 12.5) Diagnostic Measure VaLueS	*[Display measures]*	AL5	[DMVLS]

This Function shows the values of the various internal parameters as listed below :

VCPU:V	5.01	LFN_COM:V	0.000
VPS:V	5.41	LFN_DIF:V	0.000
VUSB:V	4.53	HFN_ADC:mV	0.000
+AVCC:V	+10.1	LFN_ADC:mV	0.001
-AVCC:V	-9.9	MEAS_NB:	0
VBATT:V	0.000	CAL_I:mV	16.503
IBATT:A	0.000	CAL_U:mV	530.778
VIN1:V	-8.071	CAL_G:	32.1622
VIN2:V	-8.065	CAL_O:mA	-0.055
VIN_C:V	-8.068	CAL_C:mA	-0.055
VIN_D:V	-0.006	CAL_R0:	1.00000
C_C:mA	25.00	CAL_R1:	1.00000
C_V:V	5.0	CAL_R2:	1.00000
C_VPK:V	5.5	CAL_R3:	1.00000
C_R:Ω	201.9	SYS_F:MHz	50.0512
C_PWR:W	0.126	CURR_K:	0.00000
C_T:°C	--.-	PROC1:%	46.4
C_RT:ms	0.00	PROC2:%	7.3
C_LK:mA	0.000	PROC3:%	3.8
C_ST:	1	PROC4:%	29.8
S.VER.RSLT:	0000	PROC5:%	12.6
E1R:kΩ	0.0	CPU_T:°C	+33.12
E2R:kΩ	0.0		

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(POS. 12.6) Diagnostic Communication VaLueS *[Disp. comm. vars]* AL5 [DCVLS]

Create a list of diagnostic values on the device communication.

PPP link status →
MCPI socket status →

```
PPP_STATUS:   NETW   E_IP_HDR5:        3
MCPI_S:  ESTABLISH   E_IP_HDR6:        0
RxCNT:       1477149 E_IP_HDR7:        0
TxCNT:       6515456 E_IP_HDR8:        0
E_SR_LINK:         0 E_IP_HDR9:        0
E_PAKTLEN:         0 E_TCPHDR1:        0
E_NETLAYR:         0 E_TCPHDR2:        0
E_TSPLAYR:         0 E_UDPHDR1:        0
E_ARPHDR1:         0 E_UDPHDR2:        0
E_ARPHDR2:         0 E_UDPHDR3:       92
E_IP_HDR1:         0 E_ICMPHDR:        0
E_IP_HDR2:         0
E_IP_HDR3:         0
E_IP_HDR4:         0
```

Following are the states for the PPP link and MCPI to connect the device.

PPP link status:

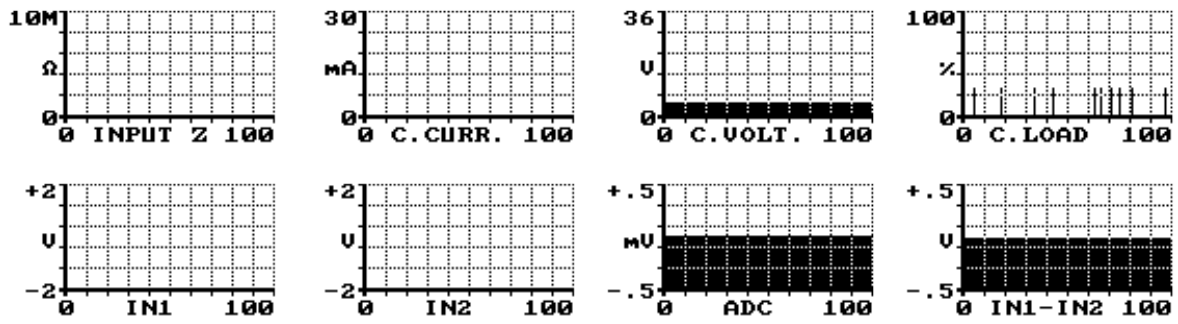
“UNDT” = undetermined
“DEAD” = dead, link down, persistent condition
“LCP” = LCP phase, transition condition
“AUTH” = Authentication phase, transition condition
“IPCP” = IP and DNS addressess assign phase, transition condition
“NETW” = network established (normal persistent condition when the link is UP)
“TERM” = link termination request, transition condition

MCPI link status:

“CLOSED” = socket closed
“ACCEPT” = socket awaiting for new connection
“ESTABLISH” = link established
“CLS_WAIT” = waiting for closure
“LAST_ACK” = last ACK sent
“FIN_WAIT” = (see TCP/IP RFC documentation)
“TIME_WAIT” = (see TCP/IP RFC documentation)

(POS. 12.7) OscilloSCOPe function *[Display graphs]* *AL5* [OSCOP]

This function displays graphs of input Z, C. current, C. Volt, C.Load, Input 1, Input 2, Input1-Input 2, Analog to Digital Transmitter.



(POS. 12.8) Generic sensor set *[Gen.sens. set]* *AL5* NO MCP COMMAND

Automatic finding of a parameter set for a generic sensor.

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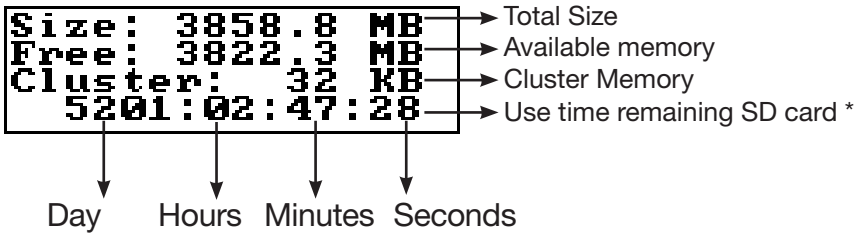
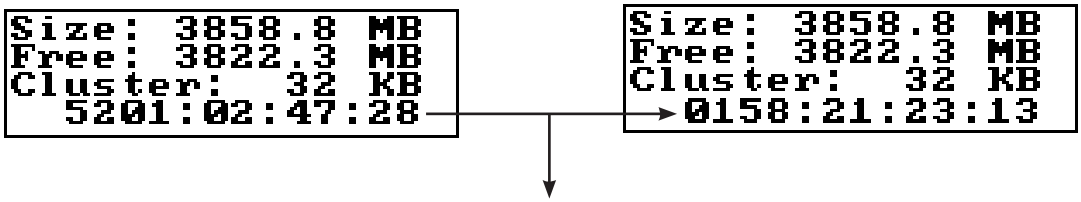
(POS. 12.9) SD memory STAtus *[SD card info]* *AL0* [SDSTA]

This function shows the status of the SD card as shown in the following figure.



The statistical calculation is performed every time the command SDSTA is invoked. The statistical data are updated AUTOMATICALLY every day (24 hours) or manually each time the function is called to display or send the SDSTA command. However, given that for the detection is necessary a minimum of one hour, the data will not be recomputed before this time interval.



The SD card must be replaced only by the service or authorized personnel. The card must have this characteristics:

Interface	SD 3.0, Class 10, UHS-I
Connector	Standard microSD 8 pin
Outline Dimensions	11 x 15 x 1 mm
Sequential Read Performance (MB/s)	> 10 MB/s
Density Range	4GB to 32GB (SDHC only)
Data Retention	> 5 years
Endurance	> 3000 P/E cycles
Operating Temperature	-25 to +85 °C
MTBF	≥ 3,000,000 hours (0 - 30°C)
Voltage	2.7 – 3.6 V
Power Consumption	Read typically <160 mA - Write typically < 130 mA, Idle typically < 300 uA

(POS. 12.10) MODel and Software Version *[Firmware info]* *AL0* [MODSV]

Firmware info version/revision

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(POS. 12.11) SeRial NUMber	*[S/N= xxxxxx]*	*AL0*	[SRNUM?]

View Board serial number. (read only)

(POS. 12.12) Total WorKing TiMe	*[WT= xxxx: xx: xx: xx]*	*AL0*	[TWKTM?]

View Total working time device. (read only)

MENU 13 - SYSTEM

(POS. 13.1) DaYlight Saving Time Enable	*[Dayl. Saving= ON]*	AL2	[DYSTE]

Daylight saving time change.

(POS. 13.2) Time ZONE	*[Time zone=h+xx.xx]*	AL2	[TZONE]

Set time for geographic area

(POS. 13.3) Date and TIME	*[xxxx/xx/xx-xx:xx]*	AL2	[DTIME]

Set to system date and time

(POS. 13.4-5-6-7-8-9) Level n° Access CoDe	*[Ln xxxxxxxx]*	---	[L1ACD]-> [L6ACD]

This function enables or disables, for each access level code, the main menu functions.
Each level unlocks the functionality of the lower level. (Function POS. 13.10 see page 39)
L1 code= ******** Access level value code 1 L4 code= ******** Access level value code 4
L2 code= ******** Access level value code 2 L5 code= ******** Access level value code 5
L3 code= ******** Access level value code 3 L6 code= ******** Access level value code 6

(POS. 13.10) ReStricted Access Rule Enable	*[Restr. access= ON]*	AL6	[RSARE]

Enable Or disable access level code. If active displays only the functions related to the level entered access.

IP ADDRESS SETTING (13.11-12-13)

(POS. 13.11)Device IP address	*[XXX.XXX.XXX.XXX]*	AL3	[DIPAD]

Device IP network address

(POS. 13.12) Client IP address	*[XXX.XXX.XXX.XXX]*	AL3	[CIPAD]

Client IP network address

(POS. 13.13) Network mask	*[XXX.XXX.XXX.XXX]*	AL3	[NETMS]

Network mask.

Caution: Changes to the functions of the points 13.11-13.12-13.13 are enabled after the device restart (see function 12.1 Self test for restart transmitter).

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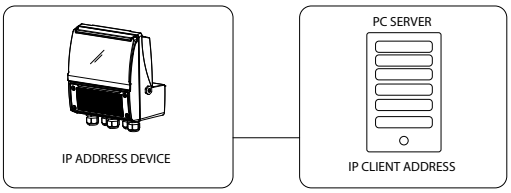


(POS. 13.14) CoeFFicient KT	*[KT=X.XXXXX]*	*AL6*	[CFFKT]

Gain correction coefficient (calculated automatically)

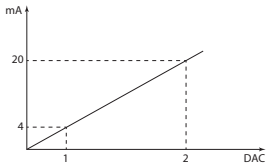
(POS. 13.15) CoeFFicient KS	*[KS=X.XXXXX]*	*AL5*	[CFFKS]

Correction coefficient constant deviceal

(POS. 13.16) CoeFFicient KR	*[KR=X.XXXXX]*	*AL5*	[CFFKR]

Correction coefficient constant deviceal

DIGITAL ANALOG Transmitter (Correction Parameters)(13.17-18-19-20)



The diagram shows how the DAC4-20mA parameters are setup. The DAC1 value corresponds to 4 mA corresponding to a zero flow rate, while the value of 20mA corresponds to a 100% of the flow rate.

(POS. 13.17) Current output 1 Calibration Point 1	*[DAC1 4mA =XXXXX]*	AL5	[C1CP1]

DAC1 out 4mA calibration point. (current output1 calibration point 1)

(POS. 13.18) Current output 1 Calibration Point 2	*[DAC1 20mA=XXXXX]*	AL5	[C1CP2]

DAC1 out 20mA calibration point. (current output1 calibration point 2)

(POS. 13.19) Current output 2 Calibration Point 1	*[DAC1 4mA=XXXXX]*	AL5	[C2CP1]

DAC2 out 4mA calibration point. (current output2 calibration point 1)

(POS. 13.20) Current output 2 Calibration Point 2	*[DAC2 20mA=XXXXX]*	AL5	[C2CP2]

DAC2 out 20mA calibration point (current output2 calibration point 2)

(POS. 13.21) Stand-BY	*[STAND-BY]*	AL3	[SSTBY]

Enable the transmitter standby state. It is enabled by selecting chargeable battery in hw config

(*POS. 13.22) FirmWare UPDate*	*[FW update]*	AL4	[FWUPD]

Enable firmware update. The firmware can be uploaded to the SD card (name.file).
MCP interface is activated by the command FWUPD = name.file

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MENU 13 - SYSTEM: ONLY MCP FUNCTIONS

Unique Identity KEY	*[MCP ONLY]*	AL0	[UIKEY]

Device Unique Identity key

HardWare SET	*[MCP ONLY]*	AL0	[HWSET]

Device hardware configuration

HardWare CODe	*[MCP ONLY]*	AL0	[HWCOD]

Device hardware code

CALibration eXecution status Memory	*[MCP ONLY]*	AL6	[CALXM]

CALXM=1 device calibrated correctly
CALXM=0 Invalid calibration / Calibration not completed (invalid calibration (if the function is zero, start the calibration function, MCP CALIC command).

RTC Adjustment Coefficient	*[MCP ONLY]*	AL2	[RTCAC]

RTC is used to set a correction factor for the internal clock.

For setting the correction date and time with MCP press 

Function CODe Selection	*[MCP ONLY]*	AL0	[FCODS]

Select the function code

FuNction Enable State Selection	*[MCP ONLY]*	AL6	[FNESS]

Select the enable state of function

All FuNctions State Selection	*[MCP ONLY]*	AL6	[AFNSS]

Select enable state of all function

Quick Start FuNction Selection	*[MCP ONLY]*	AL6	[QSFNS]

Select function for quick start menu

Quick Start All Functions Selection	*[MCP ONLY]*	AL6	[QSAFS]

Select ALL function transmitter for quick start menu.

Quick start function Status LiST	*[MCP ONLY]*	AL6	[QSLST]

List quick start group functions

Function enable Status LiST	*[MCP ONLY]*	AL6	[FSLST]

List enable status of functions

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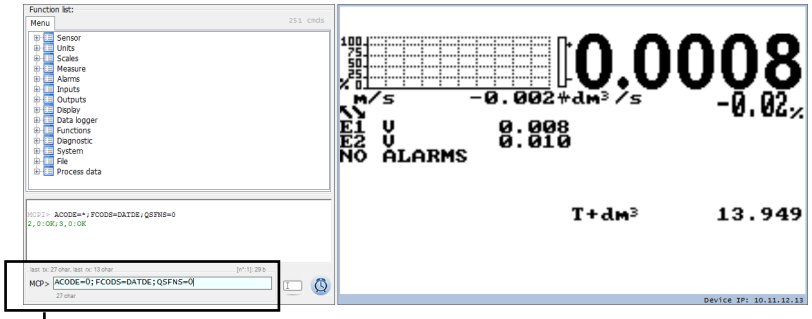
Access CODE	*[MCP ONLY]*	AL0	[ACODE]

Input the right access code

Example set quick start menu function for mcp.



ACODE=0; FCODS=[MCP COMMAND]; QSFNS=1

- Access Code
- INSERT MCP Command of the function to be activated in the QS menu.
- Quick Start FuNction Selection

LINK Terminate	*[MCP ONLY]*	AL0	[LTERM]

Terminate the PPP data link

MCPI session QUIT	*[MCP ONLY]*	AL0	[MQUIT]

Quit the MCPI connection

Functions LIST	*[MCP ONLY]*	AL0	[FLIST]

View list of all available transmitter functions.

Functions LISt Compact	*[MCP ONLY]*	AL0	[FLISC]

View compact list of all available transmitter functions.

Functions Menu SELection	*[MCP ONLY]*	AL0	[FMSEL]

Select menu for functions list

ConFiguration LiST	*[MCP ONLY]*	AL0	[CFLST]

Configuration parameter list. The list with the status / values of the transmitter parameter.

Volume Totalizer Total Positive Set	*[MCP ONLY]*	AL4	[VTTPS]

This function allows to set the value of total positive totalizer

Volume Totalizer Partial Positive Set	*[MCP ONLY]*	AL4	[VTPPS]

This function allows to set the value of partial positive totalizer

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Volume Totalizer Total Negative Set	*[MCP ONLY]*	AL4	[VTTNS]

This function allows to set the value of total negative totalizer

Volume Totalizer Partial Negative Set	*[MCP ONLY]*	AL4	[VTPNS]

This function allows to set the value of partial negative totalizer

Volume Total Positive Overflow Set	*[MCP ONLY]*	AL4	[VTPOS]

This function allows to set the overflow value of the total positive totalizer

Volume Partial Positive Overflow Set	*[MCP ONLY]*	AL4	[VPPOS]

This function allows to set the overflow value of the partial positive totalizer

Volume Total Negative Overflow Set	*[MCP ONLY]*	AL4	[VTNOS]

This function allows to set the overflow value of the total negative totalizer

Volume Partial Negative Overflow Set	*[MCP ONLY]*	AL4	[VPNOS]

This function allows to set the overflow value of the partial positive totalizer

CPU MaX.recorded temperature	*[MCP ONLY]*	AL6	[CPUMX]

CPU maximum recorded temperature

CPU MiN.recorded temperature	*[MCP ONLY]*	AL6	[CPUMN]

CPU minimum recorded temperature

Board T1 MaX.recorded temperature	*[MCP ONLY]*	AL6	[BT1MX]

T1 maximum recorded temperature

Board T1 MiN.recorded temperature	*[MCP ONLY]*	AL6	[BT1MN]

T1 minimum recorded temperature

Board T2 MaX.recorded temperature	*[MCP ONLY]*	AL6	[BT2MX]

T2 maximum recorded temperature

Board T2 MiN.recorded temperature	*[MCP ONLY]*	AL6	[BT2MN]

T2 minimum recorded temperature

Calibration OFset Register 0	*[MCP ONLY]*	AL6	[COFR0]

Calibration offset register 0

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Calibration GAin Register 0	*[MCP ONLY]*	AL6	[COFR1]

Calibration offset register 1

Calibration GAin Register 0	*[MCP ONLY]*	AL6	[CGAR0]

Calibration gain register 0

Calibration GAin Register1	*[MCP ONLY]*	AL6	[CGAR1]

Calibration gain register 1

Calibration GAin Register 2	*[MCP ONLY]*	AL6	[CGAR2]

Calibration gain register 2

Calibration GAin Register 3	*[MCP ONLY]*	AL6	[CGAR3]

Calibration gain register 3

Calibration GAin Register C	*[MCP ONLY]*	AL6	[CGARC]

Calibration gain register C

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MENU 14 - FILE (ONLY MCP)

File Transfer ABoRt	*[MCP ONLY]*	AL2	[FTABR]

This function allows to abort the current file transfer

File Transfer STAte	*[MCP ONLY]*	AL0	[FTSTA]

This function allows to show the file transfer state

Read Last EVenTs	*[MCP ONLY]*	AL2	[RLEVT]

This function allows to read the latest system events

Read All EVenTs	*[MCP ONLY]*	AL2	[RAEVT]

This function allows to read all current system events

Read Last Logged DaTa	*[MCP ONLY]*	AL2	[RLLDT]

This function allows to read the latest logged data

Read All Logged DaTa	*[MCP ONLY]*	AL2	[RALDT]

This function allows to read all current logged data

Read Last Sensor Verify Data	*[MCP ONLY]*	AL2	[RLSVD]

This function allows to read the latest sensor verify data

Read All Sensor Verify Data	*[MCP ONLY]*	AL2	[RASVD]

This function allows to read all sensor verify data

File SEND	*[MCP ONLY]*	AL2	[FSEND]

This function allows to set the file name for read operation

File ReCeiVE	*[MCP ONLY]*	AL5	[FRCVE]

This function allows to set file the name for write operation

File ReCeive APpend mode	*[MCP ONLY]*	AL5	[FRCAP]

This function allows to set the file name for write-append

File OFFSet position	*[MCP ONLY]*	AL2	[FOFFS]

This function allows to set the file offset position

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ConFiGuration file WRite	*[MCP ONLY]*	AL2	[CFGWR]

This function allows to save a file with the configuration data

ConFiGuration file ReaD	*[MCP ONLY]*	AL2	[CFGRD]

This function allows to read the configuration from a file

FuNCtion list file WRite	*[MCP ONLY]*	AL2	[FNCWR]

This function allows to save the functions list to file

Function Enable Status WRite	*[MCP ONLY]*	AL6	[FESWR]

This function allows to save the function enable status to file

Quick Start function Status WRite	*[MCP ONLY]*	AL6	[QSSWR]

This function allows to save the quick start function enable.

MENU 15 - PROCESS DATA (ONLY MCP)

OUTput 1 Set	*[MCP ONLY]*	AL0	[OUT1S]

This function allows to set value for digital output 1

OUTput 2 Set	*[MCP ONLY]*	AL0	[OUT2S]

This function allows to set value for digital output 2

Digital INput 1 Status	*[MCP ONLY]*	AL0	[DIN1S]

Digital input 1 status read

Flow Rate Full Scale in chosen Units	*[MCP ONLY]*	AL0	[FRFSU]

Flow rate f.scale in chosen units

Flow Rate Value PerCentage	*[MCP ONLY]*	AL0	[FRVPC]

Flow rate value in percentage

Flow Rate Value Percentage without cut-off	*[MCP ONLY]*	AL0	[FRVPX]

Flow rate in perc.without cut-off

Flow Rate Value Binary without cut-off	*[MCP ONLY]*	AL0	[FRVBX]

Flow rate in binary.without cut-off

Flow Rate Value Technical Unit	*[MCP ONLY]*	AL0	[FRVTU]

Flow rate value in unit of measure

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Volume Totalizer Total Positive Value	*[MCP ONLY]*	AL0	[VTTPV]
Totalizer T+ read value			
Volume Totalizer Partial Positive Value	*[MCP ONLY]*	AL0	[VTPPV]
Totalizer P+ read value			
Volume Totalizer Total Negative Value	*[MCP ONLY]*	AL0	[VTTNV]
Totalizer T- read value			
Volume Totalizer Partial Negative Value	*[MCP ONLY]*	AL0	[VTPNV]
Totalizer P- read value			
Volume Totalizer Total Positive Overflow	*[MCP ONLY]*	AL0	[VTTPO]
Totalizer T+ number of overflows			
Volume Totalizer Partial Positive Overflow	*[MCP ONLY]*	AL0	[VTPPO]
Totalizer P+ number of overflows			
Volume Totalizer Total Negative Overflow	*[MCP ONLY]*	AL0	[VTTNO]
Totalizer T- number of overflows			
Volume Totalizer Partial Negative Overflow	*[MCP ONLY]*	AL0	[VTPNO]
Totalizer P- number of overflows			
Board TeMPeratureS	*[MCP ONLY]*	AL0	[BTMPS]
Board temperatures (read-only parameter)			
CPU TemPerature	*[MCP ONLY]*	AL0	[CPUTP]
CPU temperature (read-only parameter)			
Sensor CoiLs TemPerature	*[MCP ONLY]*	AL0	[SCLTP]
Sensor’s coils temperature (read-only parameter)			
LiQuid VELocity	*[MCP ONLY]*	AL0	[LQVEL]
Liquid velocity in m/s			
AVeraGe process data Samples Number	*[MCP ONLY]*	AL0	[AVGSN]
Number of samples for averaged values			
ALARM status	*[MCP ONLY]*	AL0	[ALARM]
Active alarm(s) status			
Sensor TeSt Result Code	*[MCP ONLY]*	AL0	[STSRC]
Sensor test result code			

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Main power status	*[MCP ONLY]*	AL0	[MPWRS]

Status of main power supply

INput RESistance	*[MCP ONLY]*	AL0	[INRES]

Equivalent Input resistance of liquid measured by electrodes

INput VoLtageS	*[MCP ONLY]*	AL0	[INVLS]

Electrodes input voltages

System Battery Voltage	*[MCP ONLY]*	AL0	[SBVLT?]

View battery voltage

System Battery Charge Status	*[MCP ONLY]*	AL0	[SBCHS?]

View system battery charge status

Measure BUFFers	*[MCP ONLY]*	AL0	[MBUFF]

Measure buffers data read

SEQuence NumBer	*[MCP ONLY]*	AL0	[SEQNB]

This function allows to create a random sequential number to identify the MCP reply messages and verify that the messages are sent in the right sequence.
The user can combine to MCP command the command SEQNB=n, with a different n to every sent command. The reply that the meter will give, will include the same SEQNB sent number, so you can correctly match each reply with the respective request, maintaining control of the messages time line. With this function you can also monitor if there are missed messages or messages that have not been answered by the device.

*Sensor **TaBLe** Version*	*[MCP ONLY]*	AL0	[STBLV]

Sensor's table version

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METER DATA

The "METER DATA" system allows the import of data up to level 4, included, (working and factory parameters of the card) of the converter to another device and the restoration of the data of a meter in case the electronic card needs to be replaced .

Operation: during normal operation the meter saves all data, including the dynamic data of the totalizers, every hour, on a specific file on the SD card. The file is incremental, so its length increases linearly over the time. Each recording is time-stamped for future use. Currently, automatic data recovery uses only the last valid recording in chronological order.

Data reset: The reset is done manually, after inserting the SD card taken from the meter to be replaced, on the new electronics to be used as a replacement. This operation must be done strictly with the electronics off. Once the SD card has been replaced, wait for the device to restart and connect the MCP interface via the USB connection. Then select the “Data recovery” function on the “Functions” menu and confirm. Wait for the device to restart (the time required will depend on the configuration and the presence or absence of operations with the modem, if installed).

Consequences of restoring data on the SD card: the new electronic card will acquire all the existing data from the old meter. The root directory of the old card will be renamed with the serial number of the new card and no existing data will be altered. The data that belonged to the new card that may have been created during the recovery (data logger or events) are stored in a root directory with the name “<new card series number> .OLD”. In any case, no data will be overwritten or deleted.

Limits of data saving and retrieval: Data recovery is possible with the following limitations:

- The new board to be used as a replacement must have the same hardware configuration as the one to be replaced.
- If the device to be replaced is MID, the new board to be used as a replacement must already be preconfigured as MID, with the appropriate functions locked and the CRC comparison value set correctly.
- It is NOT possible to recover any passwords saved for internet connection services (email, FTP, etc.). These will need to be re-entered manually or via a separate configuration file. Restoring data does NOT involve resetting any passwords that may have been pre-configured in the new card.
- It is NOT possible to recover the passwords relating to the access levels of the instrument. Also in this case they will be re-set manually or pre-configured in the new board.
- The data relating to the hardware calibrations of the board are NOT transferred, therefore those stored in the new board remain valid.

The following data are NOT recoverable:

- Function parameters accessible with level 5 and 6 (typically hardware calibration data)
- Passwords and others encrypted data
- Hardware configuration parameters
- Enable status of the functions selected for the "quick-start" menu
- System function enable status

The recovered data are also saved simultaneously in the “FACTORY DEFAULTS” memory and thWey become the new factory standard values of the board.

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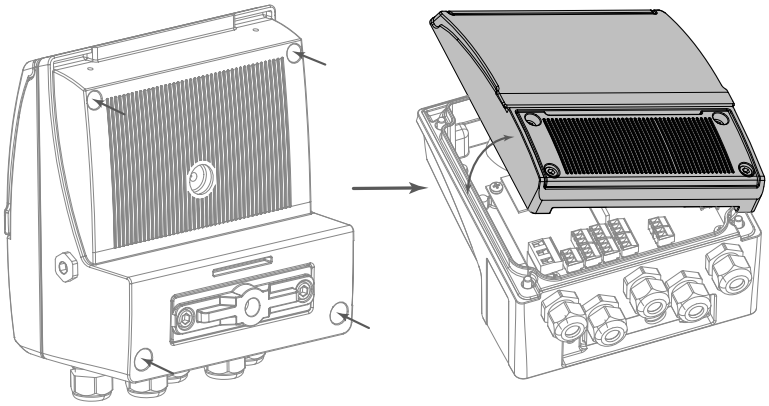
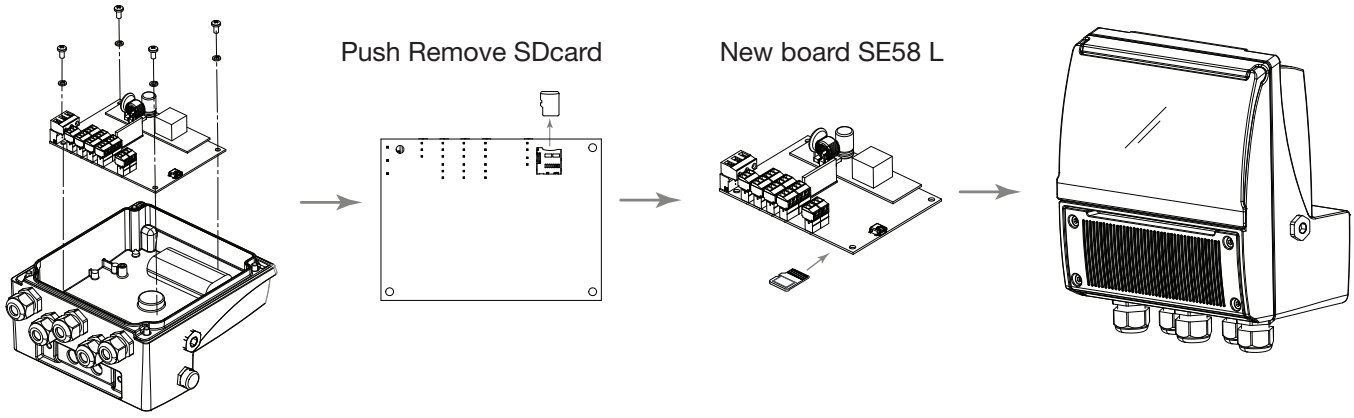
Operating procedure to change the transmitter Board

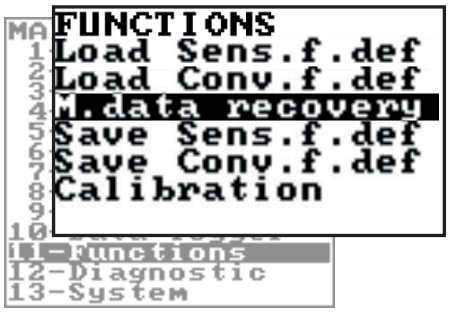
Remove the 4 screws (“SE58 L construction” pag. 14) to remove the main housing. Attention of any electrical cables.



Remove the 4 screws (see “SE58 L construction” pag. 14) to remove the SE58 L board. Attention of any electrical cables. Remove the SD card and insert the new SE58 L board.



Install the card, turn on the transmitter and enable the function **M.data recovery** to restore data



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ALARM MESSAGES (CAUSES AND ACTIONS TO BE TAKEN)

MESSAGE	CAUSES	ACTION TO TAKE
NO ALARMS	All works regularly	---
[000] SYSTEM RESTART	---	---
[001] INTERNAL PS FAIL	Internal supply voltage error	Contact the service
[002] CLOCK NOT SET	System Clock not set	Set the system clock from the transmitter menu 13 (see also MCP function).
[003] SD CARD FAILURE	SD card not found or unreadable	check and/or replace SD card
[005] F-RAM ERROR	Error writing / reading Flash-RAM	Contact the service
[006] EXCITATION ERROR	The excitation of the sensor coils resulting from cable is interrupted	Check the connecting cables to the sensor.
[007] SIGNAL ERROR	The measure is strongly effected by external noise or the cable connecting the transmitter to the sensor is broken.	Check the status of the cables connecting the sensor, the grounding connections of the devices and the possible presence of noise sources.
[008] PIPE EMPTY	The measuring pipe is empty or the detection system has not been properly calibrated.	Check whether the pipe is empty or repeat the empty pipe calibration procedure.
[009] FLOW>MAX+	The flow rate is higher than the maximum positive threshold set.	Check the maximum positive flow rate threshold set and the process conditions.
[010] FLOW>MAX-	The flow rate is higher than the maximum negative threshold set.	Check the maximum negative flow rate threshold set and the process conditions.
[011] FLOW<MIN+	The flow rate is lower than the minimum positive threshold set.	Check the minimum positive flow rate threshold set and the process conditions.
[012] FLOW<MIN-	The flow rate is lower than the minimum negative threshold set.	Check the minimum negative flow rate threshold set and the process conditions.
[013] FLOW>FULL SCALE+	The flow rate is higher than the full scale positive value set on the device.	Check the full scale positive value set on the device and the process conditions.
[014] FLOW>FULL SCALE-	The flow rate is higher than the full scale negative value set on the device.	Check the full scale negative value set on the device and the process conditions.
[015] PULSE1>RANGE	The pulse generation output 1 of the device is saturated and cannot generate the sufficient number of impulses.	Set a bigger unit of volume or, if the connected counting device allows it, reduce the pulse duration value.
[016] PULSE2>RANGE	The pulse generation output 2 of the device is saturated and cannot generate the sufficient number of impulses.	Set a bigger unit of volume or, if the connected counting device allows it, reduce the pulse duration value.
[017] CALIBR.ERROR	Calibration Error	Contact the service
[018] SYSTEM FREQ. ERR	System Freq. Error	Contact the service
[019] B.DATA NOT INIT	Uninitialized data system	Contact the service
[020] FL.SENSOR ERROR	Flow rate sensor error	Contact the service
[021] BATTERY LOW	(Rechargeable) battery depleted	Contact the service to Replace the battery

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[022] BATTERY V>MAX	Battery voltage (rechargeable)> max. Allowed	Contact the service to Replace the battery
[023] BATTERY I>MAX	Battery charge current> max. allowed	Contact the service to Replace the battery
[024] MAIN PS V.ERR	Main supply voltage (+ 5V) out of tolerance.	Contact the service
[025] USB VOLTAGE ERR	Voltage of USB connection out of tolerance.	Contact the service
[026] SDC ALMOST FULL	SD card space <500 MB.	For more information see function “12.9” pag. 38.
[027] SDC FULL	SD card out of memory	Memory Full. You can not save logger. Contact the service to replace the SD memory.
[028] BATT.TEMP.CRIT	The battery can not be charged. The temperature is out of range (detected temperature <0 C° or temperature >50°)	Wait for the normal temperature reset. View Environmental Use Conditions “Environmental Use Conditions” pag. 5.
[030] BATCHING ERROR	This error activates in two conditions (see “BATCHING” page 53)	Check the status of the actuator and the system

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ERROR CODE TEST SYSTEM OF SENSOR

The codes are in hexadecimal format, the meaning is given for each bit. There are several possible error simultaneous combinations (more bits active) then that will give the combined numerical codes.

CODE	ANOMALIES DESCRIPTION	ACTION TO TAKE
0000	NO ERROR	---
0001	SENSOR TEST INSULATION: Generator power too low	Contact the service
0002	SENSOR TEST INSULATION: Generator power too high	
0004	SENSOR TEST INSULATION: Phase 1 generator voltage too low	
0008	SENSOR TEST INSULATION: Phase 1 generator voltage too high	
0010	SENSOR TEST INSULATION: Phase 1 terminal voltage coils 1 too low	
0020	SENSOR TEST INSULATION: Phase 1 terminal voltage coils 2 too low	
0040	SENSOR TEST INSULATION: Phase 2 generator voltage too low	
0080	SENSOR TEST INSULATION: Phase 2 generator voltage too high	
0100	SENSOR TEST INSULATION: Phase 2 terminal voltage coils 1 too low	
0200	SENSOR TEST INSULATION: Phase 2 terminal voltage coils 2 too low	
0400	SENSOR TEST INSULATION: Insulation loss, leakage current out of tolerance	Check: wiring between sensor transmitter conditions of use set parameters If the problem persists contact the service
0800	TEST TEMPERATURE (RESISTANCE) COILS: Temperature (resistance) out of tolerance	
1000	TEST TIME GETTING ON CURRENT PHASE (A): Value out of tolerance	
2000	TEST TIME GETTING ON CURRENT PHASE (B): Value out of tolerance	
4000	TEST RESISTANCE INPUTS ELECTRODES: Input value 1 out of tolerance	
8000	TEST RESISTANCE INPUTS ELECTRODES: Input value 2 out of tolerance	
10000	SENSOR EXCITATION TEST: Invalid sensor driving conditions	Contact the service
20000	REFERENCE VALUES TEST: Invalid reference values	
40000	ELECTRODES INPUT RESISTANCE TEST: Empty pipe, test not possible	Check if the pipe is full

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At the end of its lifetime, this product shall be disposed of in full compliance with the environmental regulations of the state in which it is located.

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MANUAL VERSION

VERSION	DATE	DESCRIPTION
SE58L_EN_BU_R00_1.02.XXXX	07/04/2021	First Edition
SE58L_EN_BU_R01_1.04.XXXX	18/08/2021	Update for electrical safety certification. Firmware update for adding Mbus protocol
SE58L_EN_BU_R02_1.04.XXXX	08/10/2021	Changes to data relating to digital output
SE58L_EN_BU_R03_1.04.XXX	02/12/2021	Added note for maintenance
SE58L_EN_BU_R04_1.04.XXX	26/02/2021	Added notes for MCP and made some corrections on texts

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